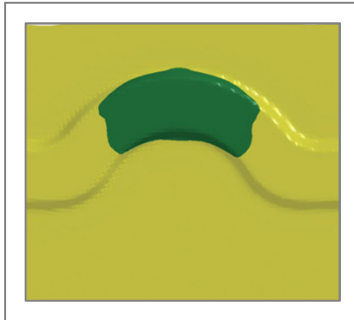


Recent developments for process simulations of composite structures in LS-DYNA



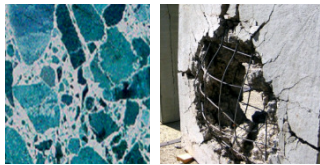
Dr. Thomas Klöppel, Christian Liebold, Dr. André Haufe

DYNAmore GmbH
Stuttgart

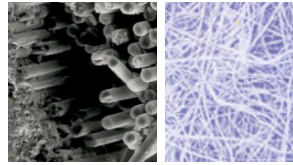
Composites: A rather broad term!

Definition

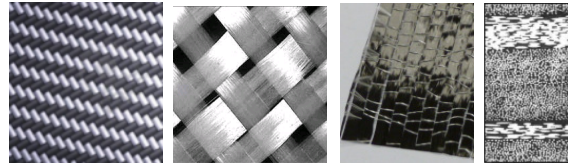
A **combination** of two or more **materials** (reinforcing elements, fillers, and composite matrix binder), differing in form or composition on a **macroscale**. The constituents retain their identities, i.e. they do not dissolve or merge completely into one another although they act in concert. The components can be physically identified and exhibit an interface between one another.



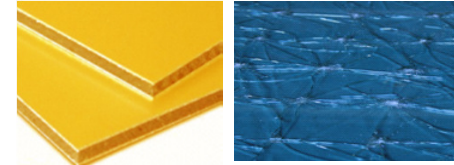
Concrete
(cement/stone/steel)



Short/long fiber
reinforced polymers
(glass/PP)



Endless fiber
reinforced polymers
(glass/carbon/PA/PP/EP)



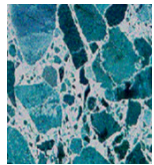
Sandwich/Laminates
(alloy/polymer/..glass/PVB/...)



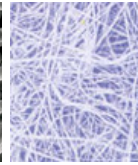
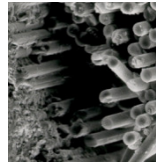
Composites: A rather broad term!

Definition

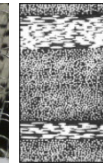
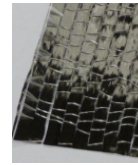
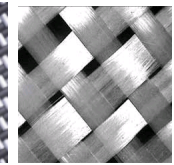
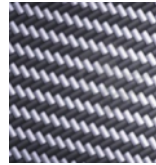
A **combination** of two or more **materials** (reinforcing elements, fillers, and composite matrix binder), differing in form or composition on a **macroscale**. The constituents retain their identities, i.e. they do not dissolve or merge completely into one another although they act in concert. The components can be physically identified and exhibit an interface between one another.



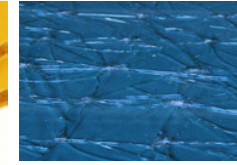
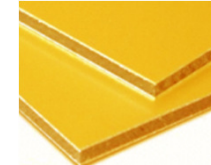
Concrete
(cement/stone/steel)



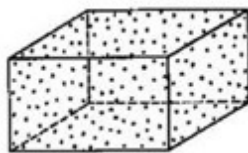
Short fiber
reinforced polymers
(glass/PP)



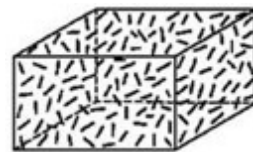
Long fiber
reinforced polymers
(glass/carbon/PA/PP/EP)



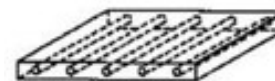
Sandwich/Laminates
(alloy/polymer/..glass/PVB/...)



particulate composite materials
(particles in a matrix)

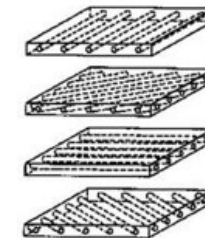


short fibers



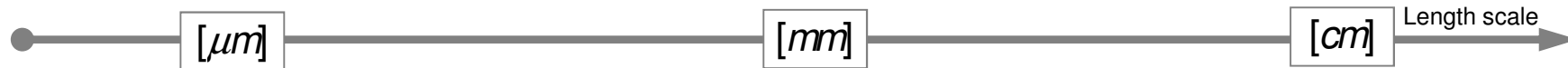
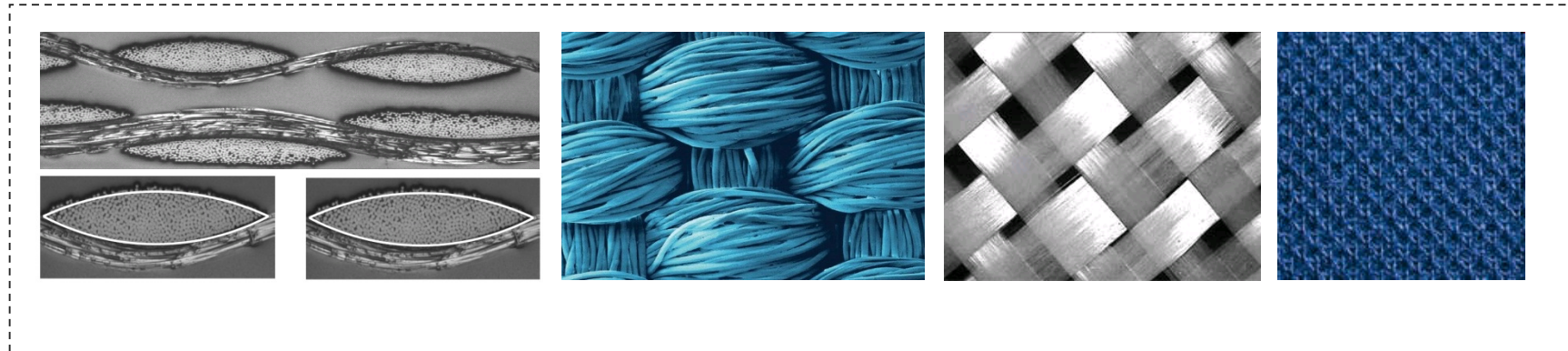
long fibers

fibrous composite materials
(fibers in a matrix)



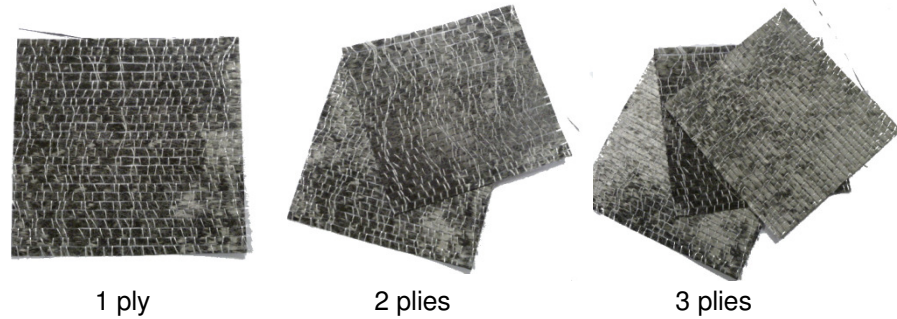
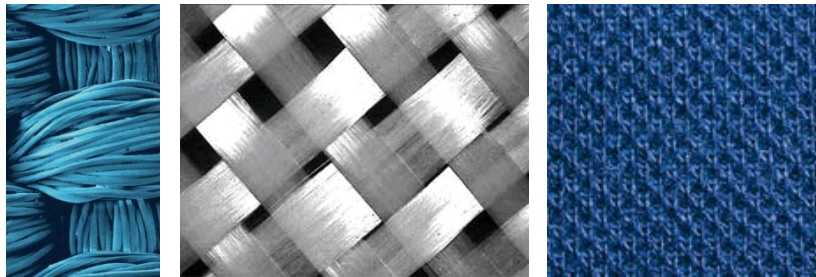
laminated composite materials
(layers of various materials)

Process simulation: Motivation



<ul style="list-style-type: none"> • Bundled beam elements • Automatic model setup • Detailed studies 	<ul style="list-style-type: none"> • Solid- or shell elements • Automatic model setup • Impact / draping simulation 	<ul style="list-style-type: none"> • Single shell elements • Autom. Model setup • Draping simulation 	<ul style="list-style-type: none"> • Smeared modeling • Production-/Processsim. • Draping and wrinkles

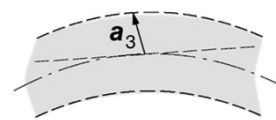
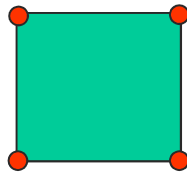
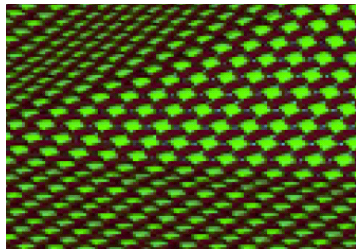
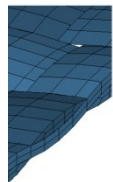
Process simulation: Motivation



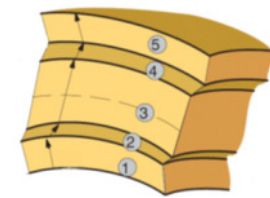
[mm]

[cm]

Length scale



homogeneous shell



stacked solid or shell

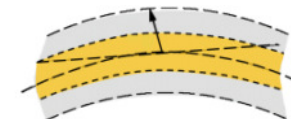


- Single shell elements
- Autom. Model setup
- Draping simulation

- Smear modeling
- Production-/Processsim.
- Draping and wrinkles



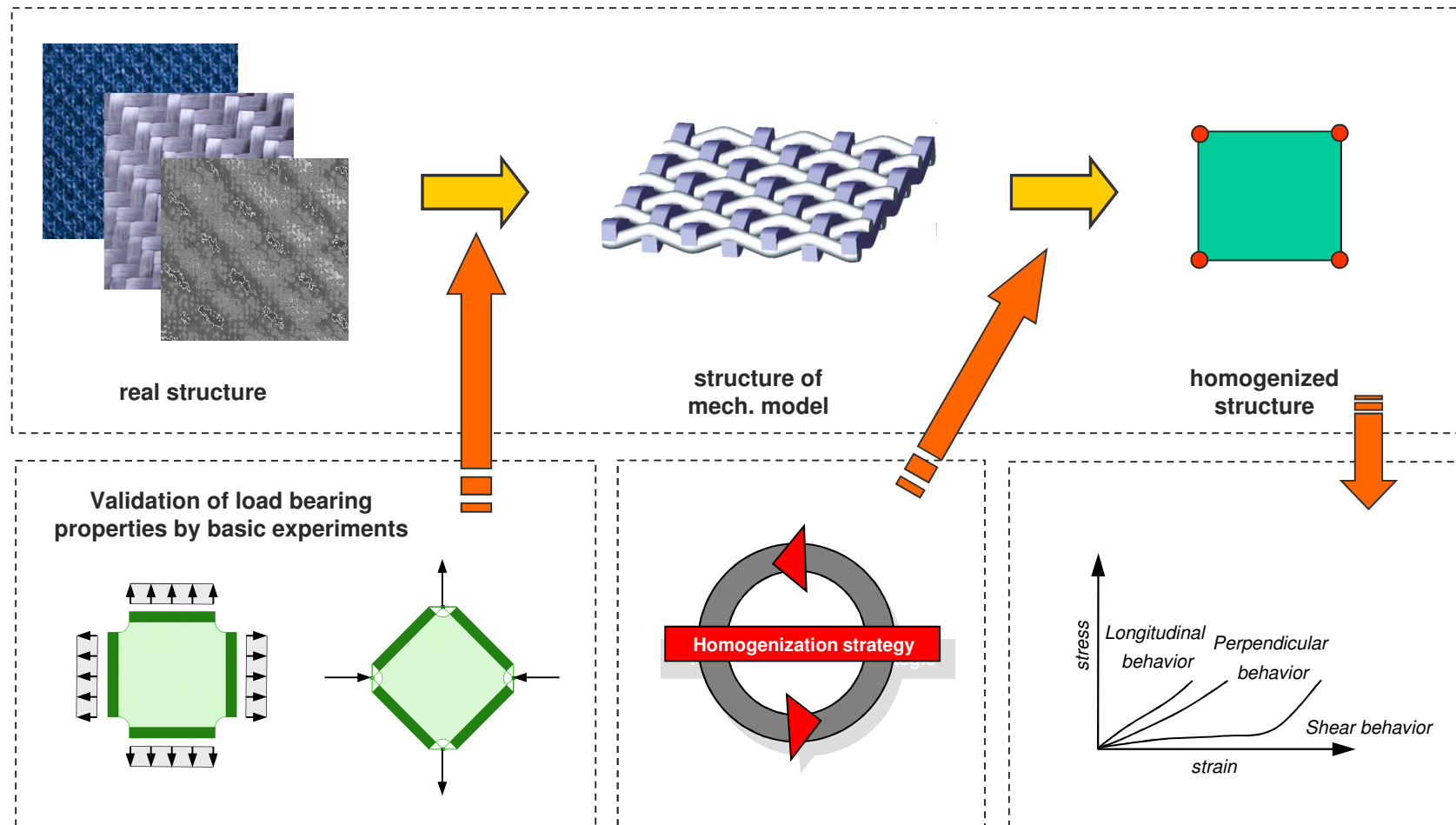
membrane



layered solid/shell

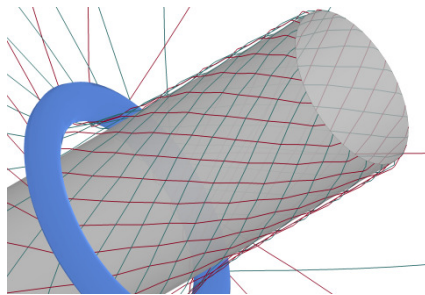
Simulation on cm-scale

Smeared approach: Homogenization of local structure and constitutive properties



Agenda

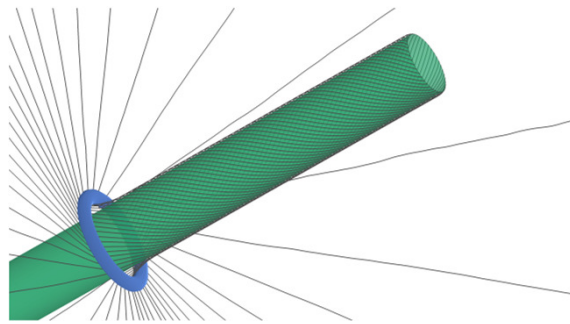
- Braiding
- Draping
- Organo sheets
- RTM
- Mapping



Braiding

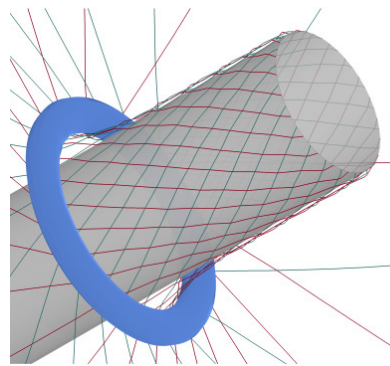
First steps for processing simulation

Filament winding simulation:



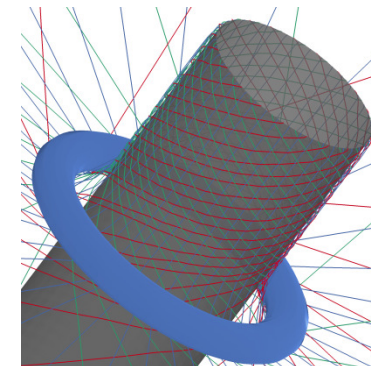
21 yarns
21543 Beam elements, 1 part
Simple rotation of the fibers and pushing of the braiding core through the braiding ring
Simple filament winding

Simple braiding simulation:

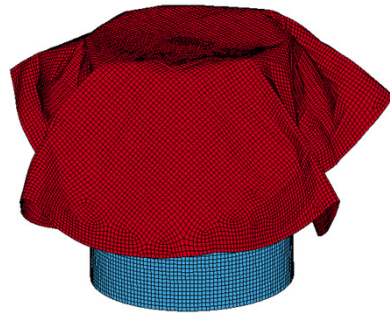


42 yarns
86172 Beam elements, 2 parts
Fibers are rotated and then moved up- and down to create the braiding-pattern
Braiding core is pushed through the braiding ring

Braiding simulation with UD reinforcement:



84 yarns
174348 Beam elements, 3 parts
Half the elements used as UD – reinforcement parts
Fibers are rotated and then moved up- and down to create the braiding-pattern
Braiding core is pushed through the braiding ring



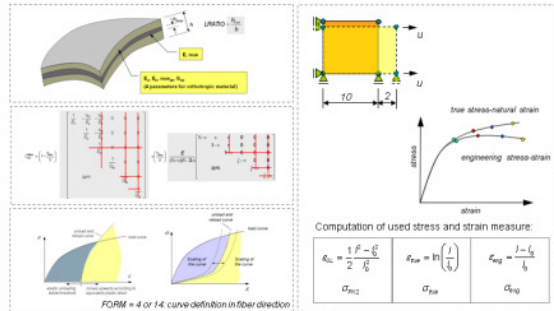
Draping

Modeling techniques on cm-scale: Fabric materials available for draping simulation

MAT_34

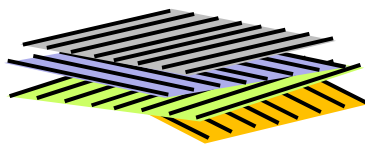
Simulation on cm-scale: MAT_FABRIC (#34)

A special membrane formulation is automatically invoked



New in R7.0: bending stiffness

New: ACMD

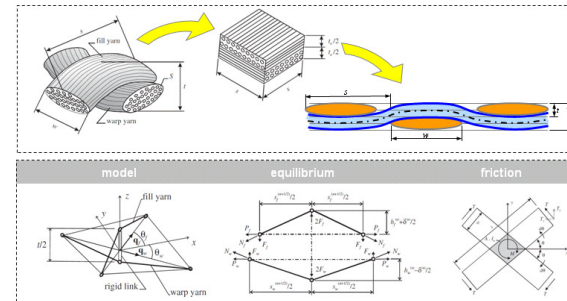


Anisotropic unidirectional layered constitutive model for draping
NEW in future release.

MAT_234

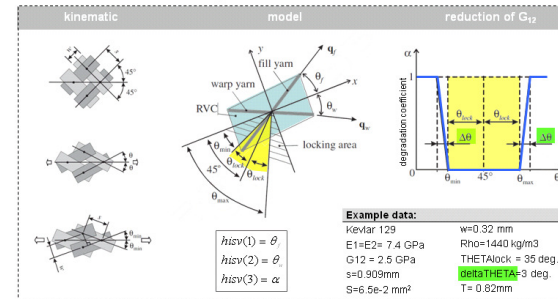
Simulation on cm-scale: MAT_VISCOELASTIC_LOOSE_FABRIC (#234)

Micro-mechanical approach:
Mathematical description of geometry and kinematic of symmetrical woven fabric



Simulation on cm-scale: MAT_VISCOELASTIC_LOOSE_FABRIC (#234)

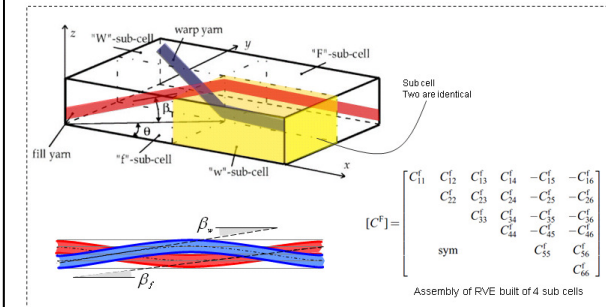
Taking locking angle through reduction factor for G_{12} into account
Visco-elastic enhancement for higher strain rates



MAT_235

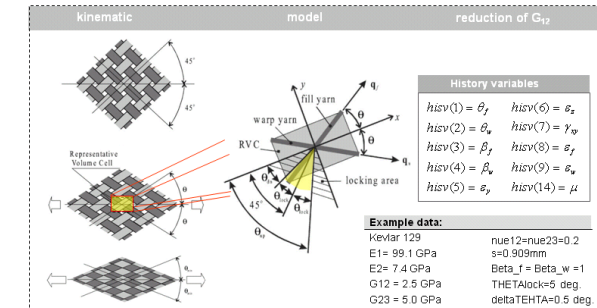
Simulation on cm-scale: MAT_MICROMECHANICS_DRY_FABRIC (#235)

Micro-mechanical approach with homogenization strategy (RVE):
Mathematical description of symmetrically woven fabric



Simulation on cm-scale: MAT_MICROMECHANICS_DRY_FABRIC (#235)

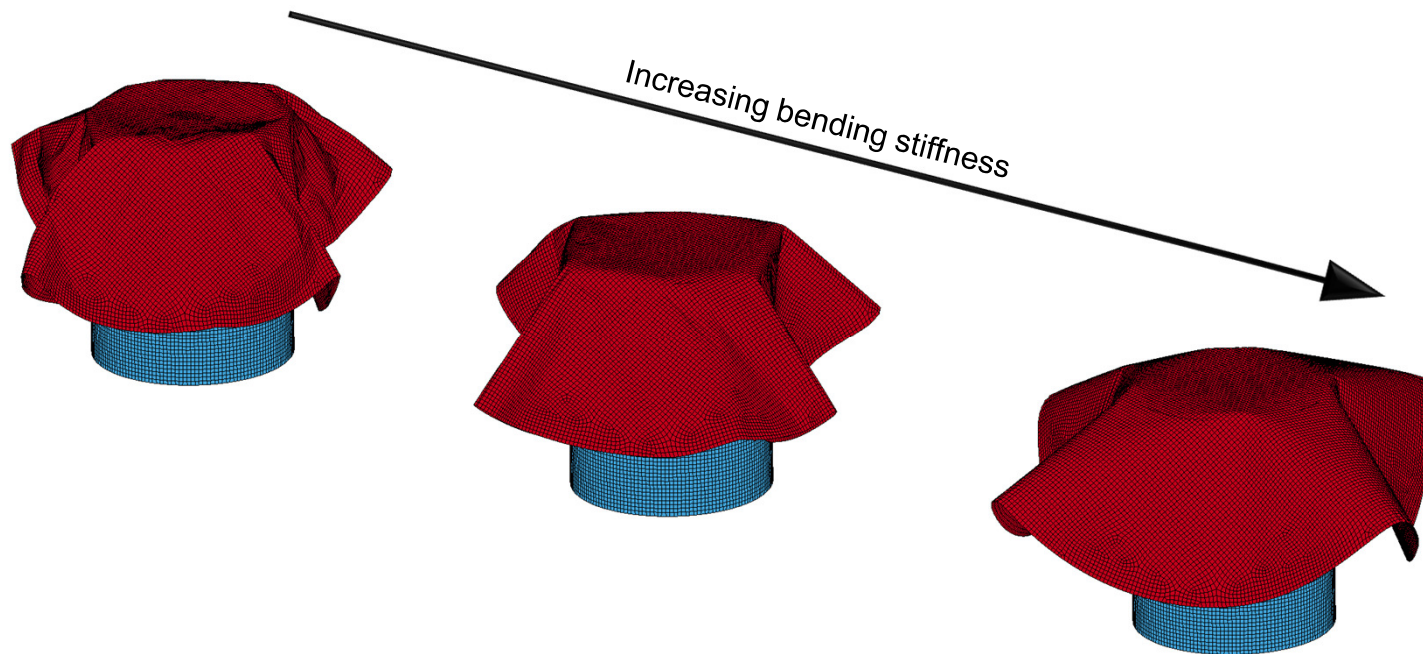
Micro-mechanical approach with homogenization strategy (RVE):
Mathematical description of symmetrically woven fabric



Enhancements in MAT_FABRIC (MAT34) starting with LS-DYNA R7.0

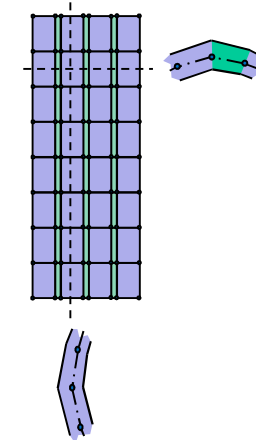
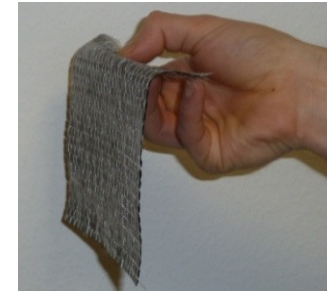
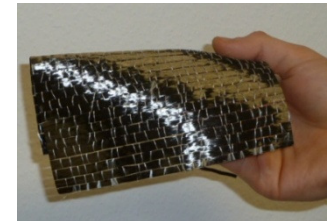
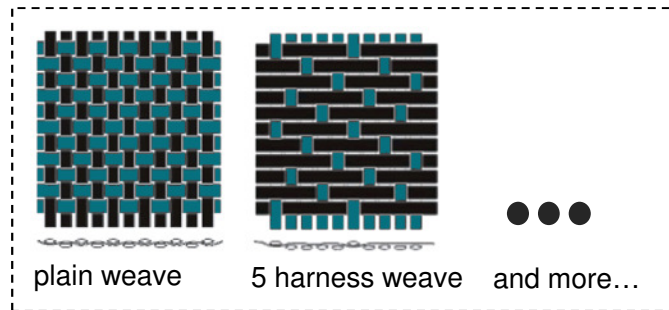
- Material describes an orthotropic material behavior
- Requires discretization with membrane elements
- Allows to add a bending resistance by defining an additional elastic coating in the material card

Example: Tablecloth with varying coating stiffness

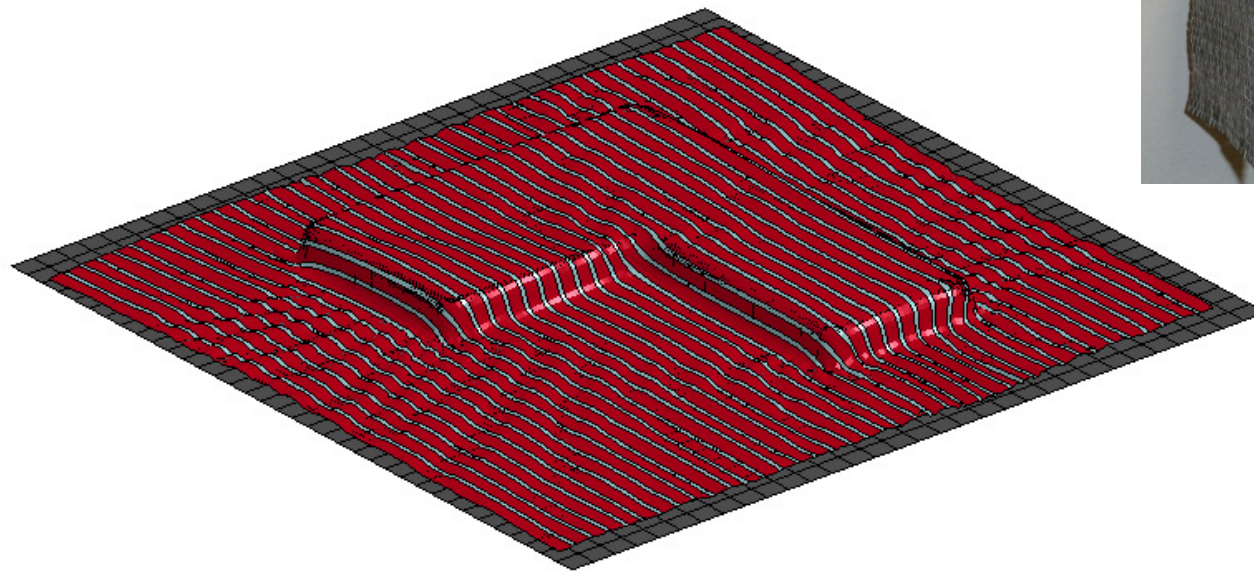


Process simulation: Draping with strong anisotropy

Some fabrics (preforms) show extreme orthotropic behavior. Here modeling with shell elements using different constitutive models is possible:

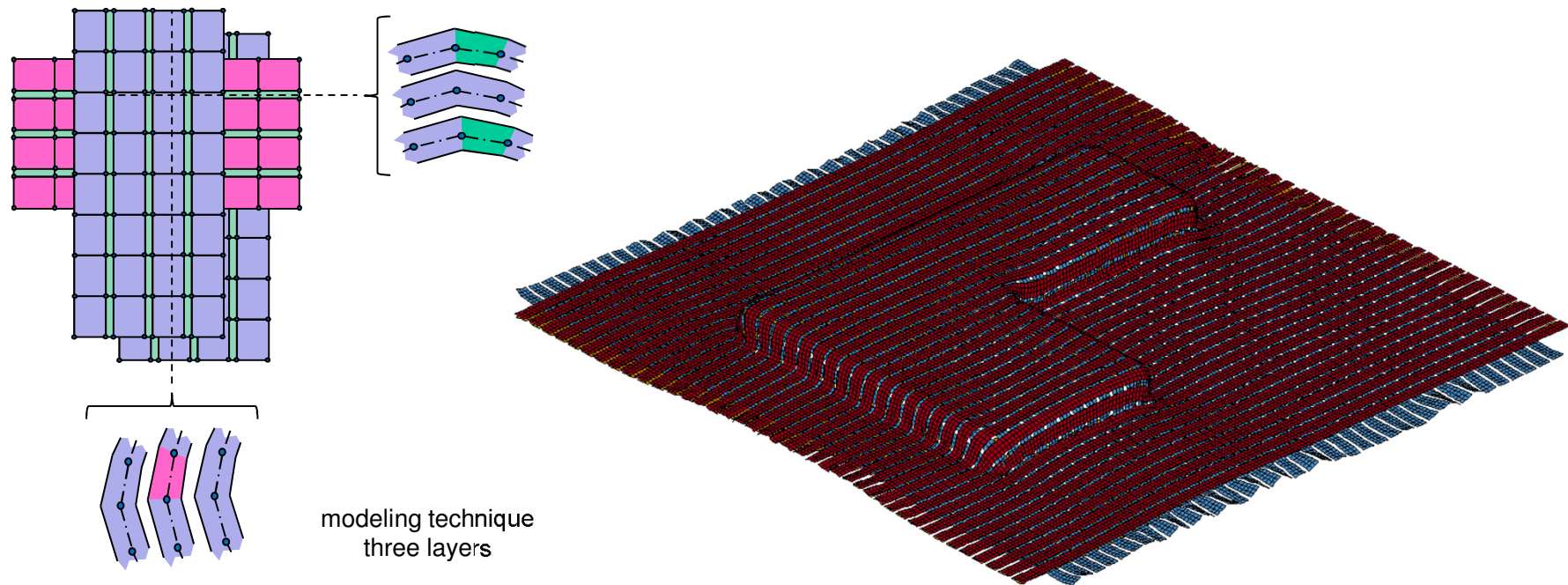


modeling technique
single layer



Process simulation: Draping with strong anisotropy

Some fabrics (preforms) show extreme orthotropic behavior. Here modeling with shell elements using different constitutive models is possible. For stacked preforms a similar approach in finite element modeling is of course possible: Multiple layers of shell elements.

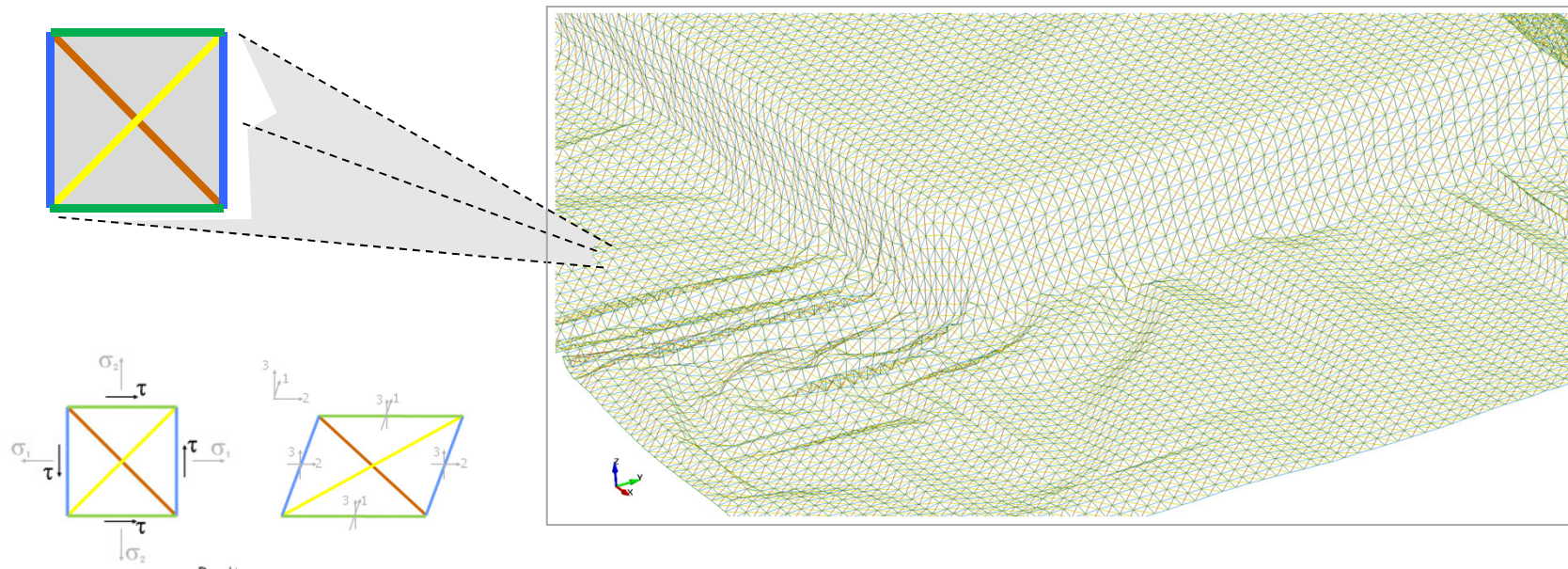


Draping: Using discrete elements for strong anisotropy

Modeling woven fabrics with beam elements:

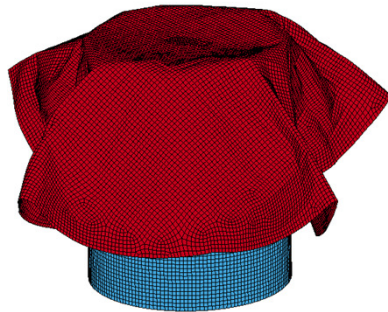
Warp and weft direction *MAT_LINEAR_ELASTIC_DISCRETE_BEAM (MAT_066)

Diagonal behavior modeled with *MAT_CABLE_DISCRETE_BEAM (MAT_071)



This approach allows also to model positive and negative shear loading.

Optional matrix may be represented with shell elements and elastic/plastic material.

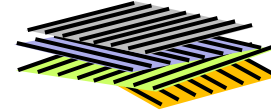


Draping – New Material model

Beta status
(could be enhanced for organo sheets)

New anisotropic constitutive model for draping (ACMD)

- Hyperelastic, anisotropic material formulation, accounting for n discrete fiber families in *each* integration point
- Normalized initial fiber directions \vec{m}_i^0 are defined w.r.t. to material direction
- Current state of fiber \vec{m}_i is given by $\vec{m}_i = \underline{F}\vec{m}_i^0$ with length λ_i
- Response of the fibers according to a function $f(\lambda_i)$ of current length \vec{m}_i of the fiber defined by a load curve
- Stresses due to elongation of the individual fibers families are then computed as



$$\underline{\sigma} = \sum_{i=1}^n \frac{1}{J} f(\lambda_i) \vec{m}_i \otimes \vec{m}_i$$

- Interaction between neighboring fiber families can be accounted for by

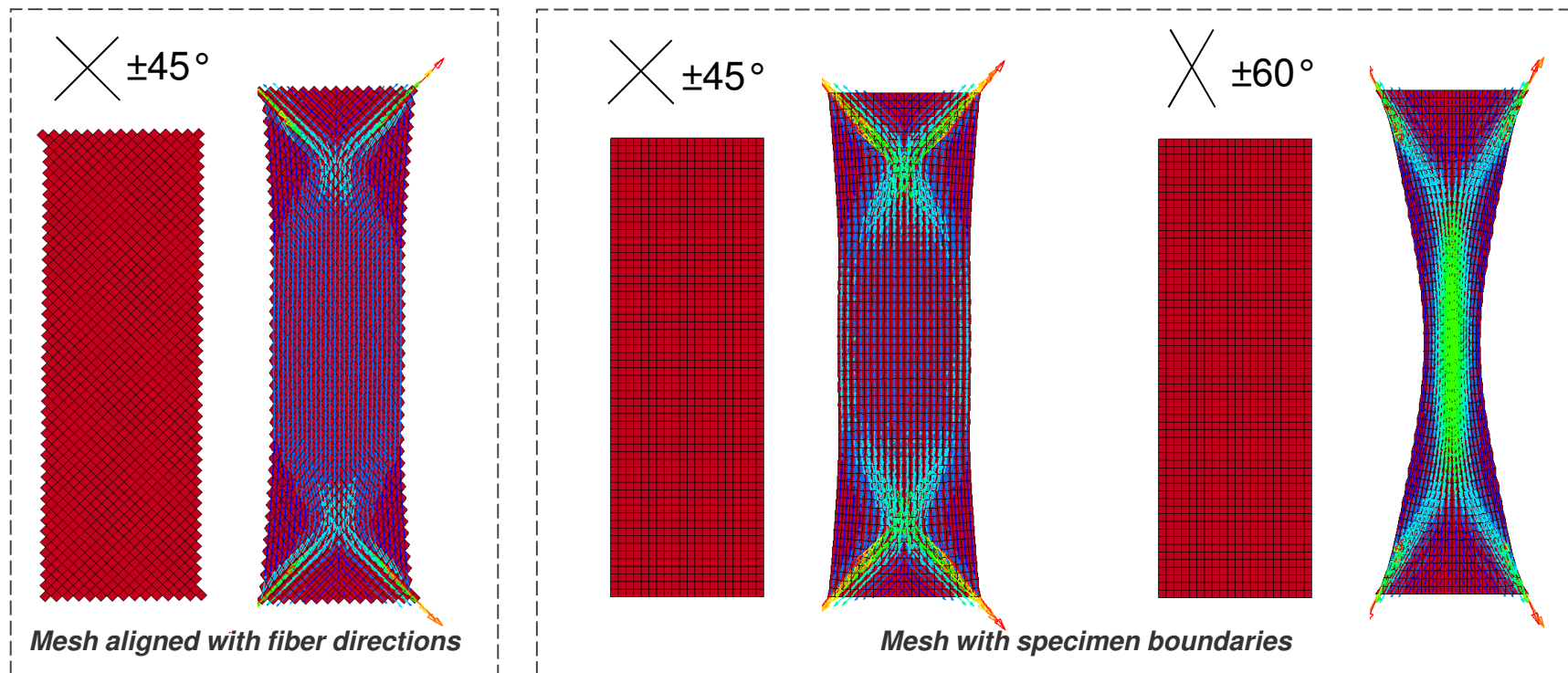
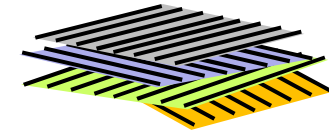
$$\underline{\sigma} = \sum_{\substack{i,j \\ i \neq j}} \frac{1}{J} g(\vec{m}_i \cdot \vec{m}_j) \vec{m}_i \otimes \vec{m}_j$$

where function g can again be provided as a load curve

- For the sake of stability, a linear relation between transverse shear stresses σ_{31}, σ_{32} and the corresponding components of the bulk strain tensor is additionally assumed

Example: tensile test specimen (ACMD)

- Prescribed motion of top nodes
- Arrows indicate the principal stresses

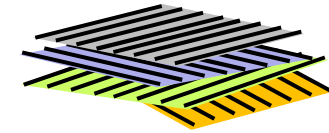


Results show that

- stress orientations are independent of element orientations
- material definition accounts correctly for anisotropic (non-orthotropic) material behavior

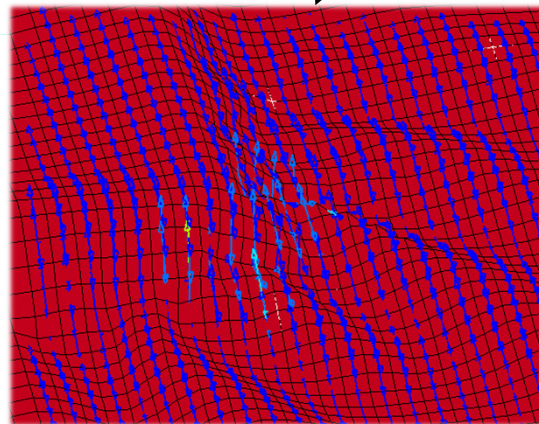
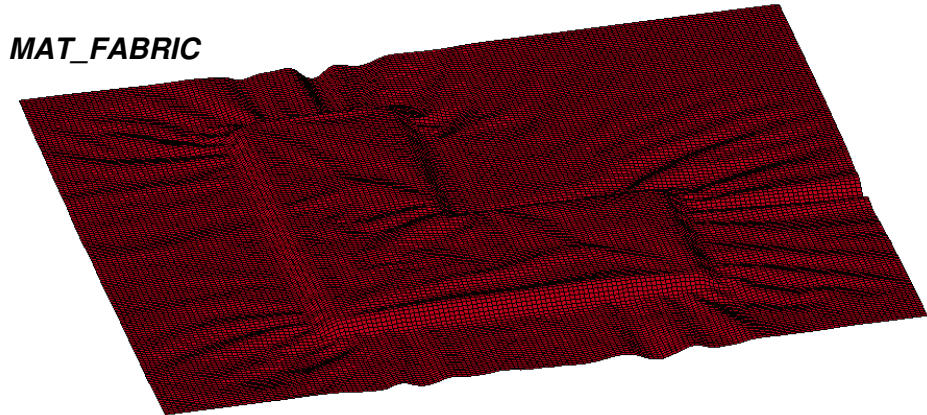
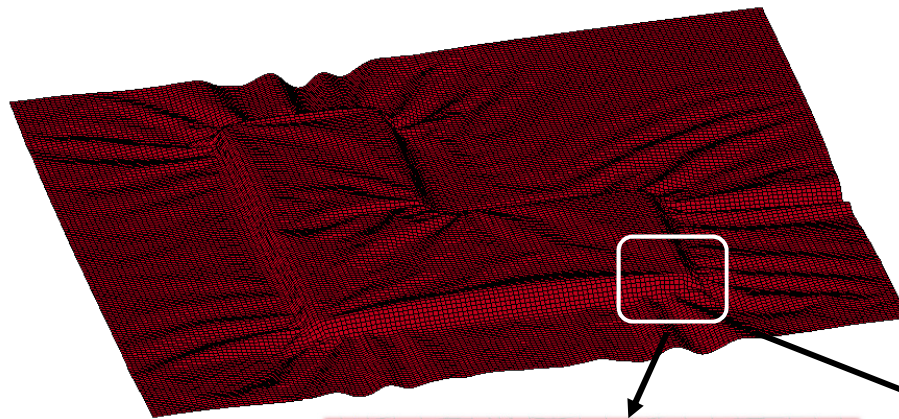
Example ACMD: Draping simulation (0 /90)

Comparison with LS-DYNA standard material MAT_FABRIC (MAT_034)

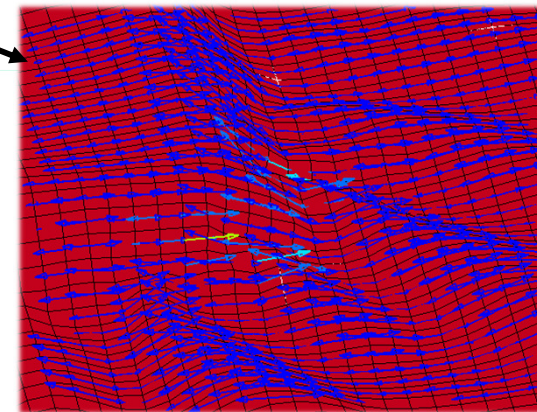


*New anisotropic
constitutive model*

MAT_FABRIC

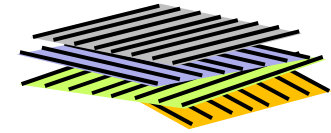


Fiber 1



Fiber 2

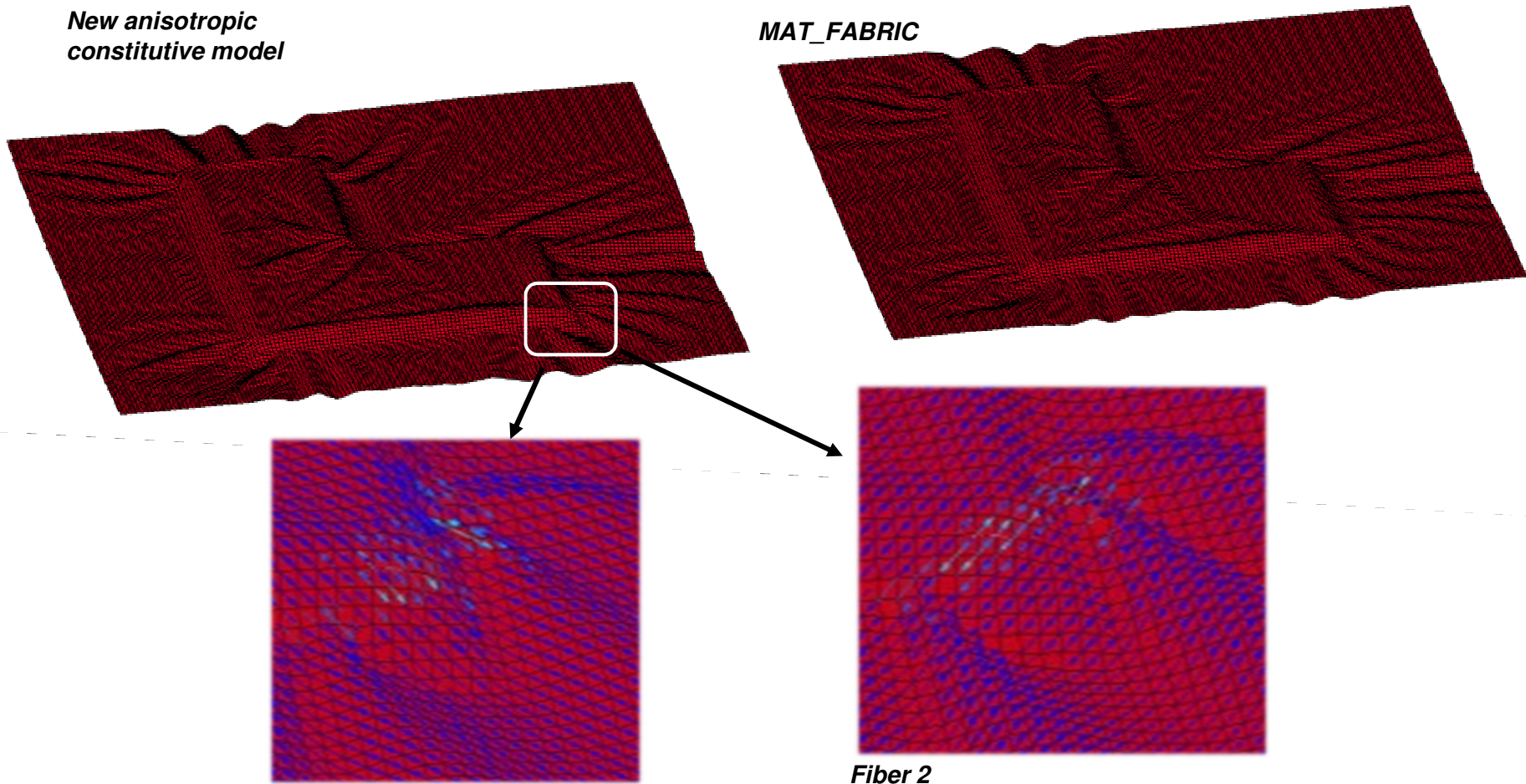
Example ACMD: Draping simulation (-45 / +45)



Comparison with LS-DYNA standard material MAT_FABRIC (MAT_034)

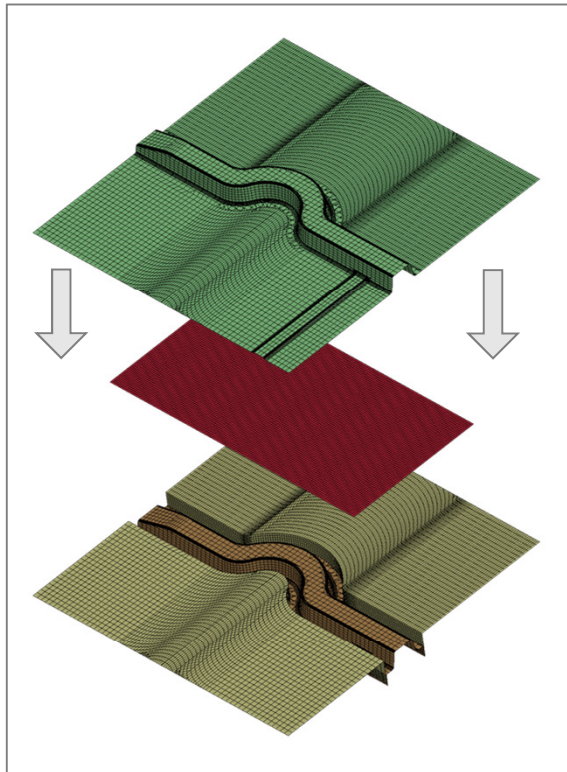
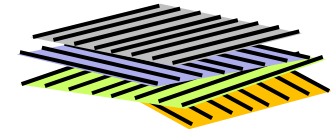
*New anisotropic
constitutive model*

MAT_FABRIC

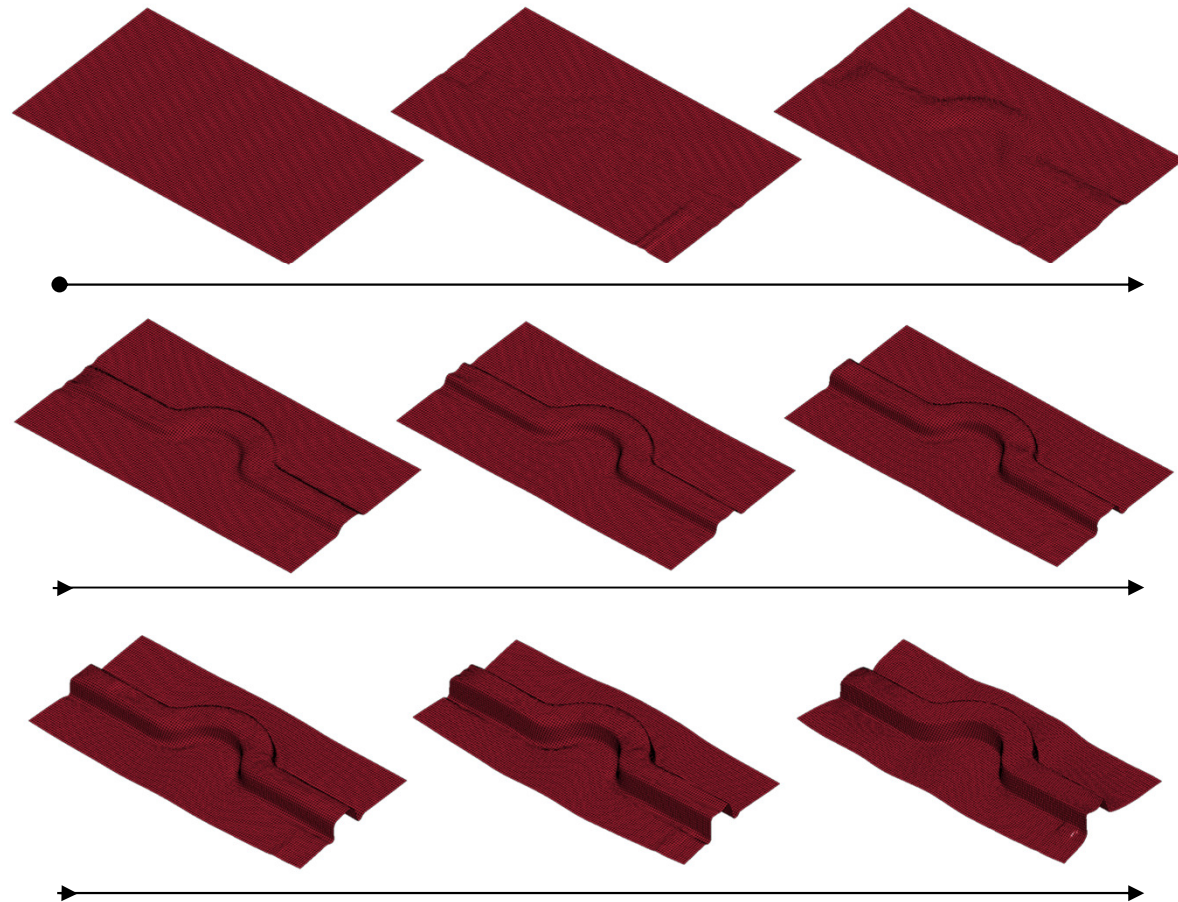


Draping example: S-Rail

Process simulation



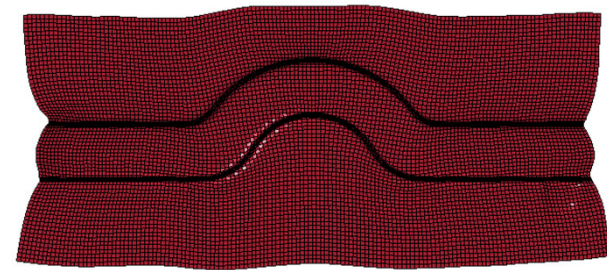
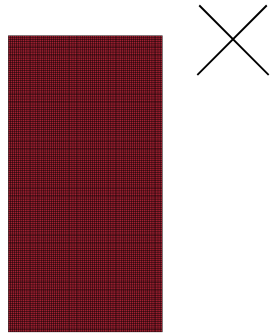
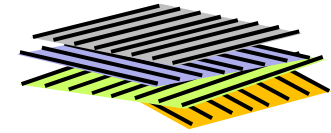
[geometry provided by Benteler-SGL]



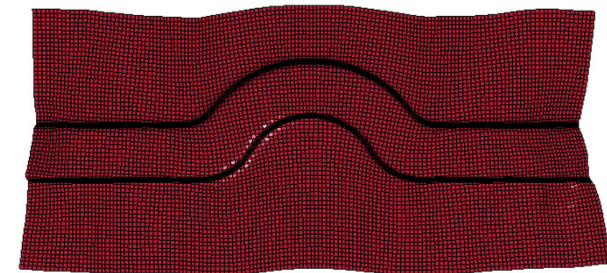
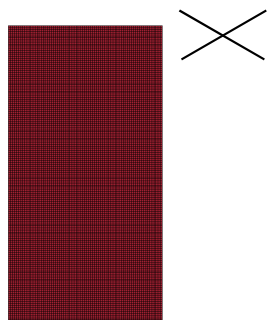


Draping example: S-Rail

- Fiber angle $\pm 45^\circ$, final state



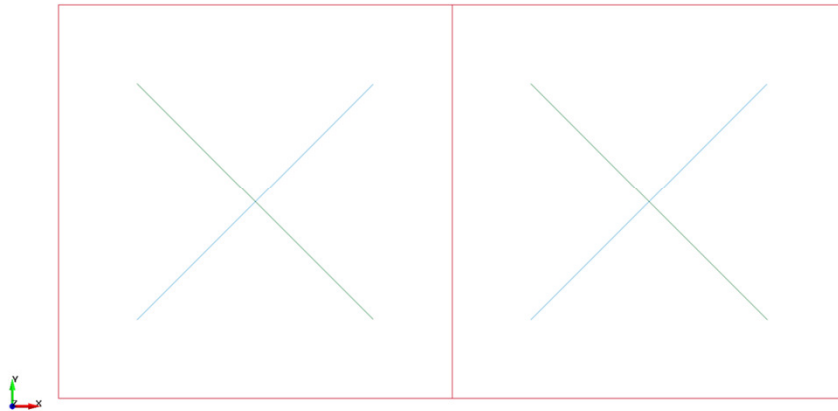
- Fiber angle $\pm 60^\circ$, final state



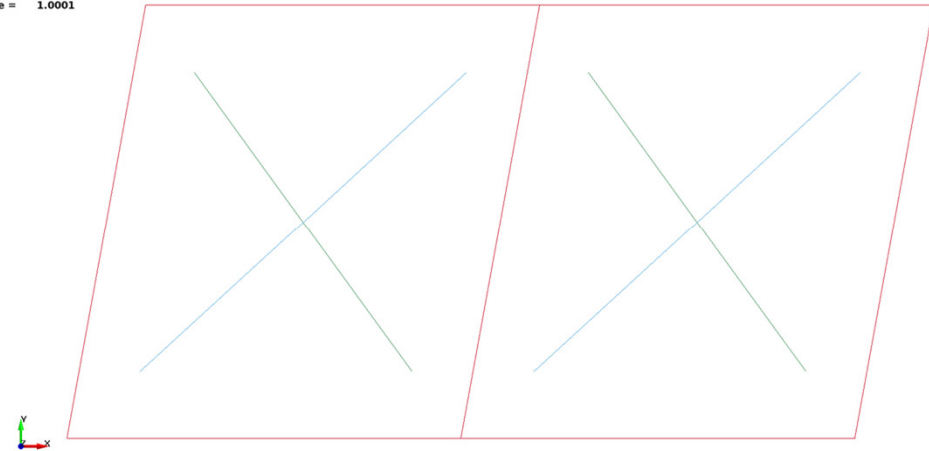
Outlook: Output of composite related data

- Write separate output file including information about
 - Ply-ID the IP under consideration belongs to
 - Fiber directions
 - Damage
 - ...
- Output in binary LSDA-format
- First implementations made in LS-DYNA for the User Material and in LSPP

LS-DYNA keyword deck by LS-PrePost
Time = 0



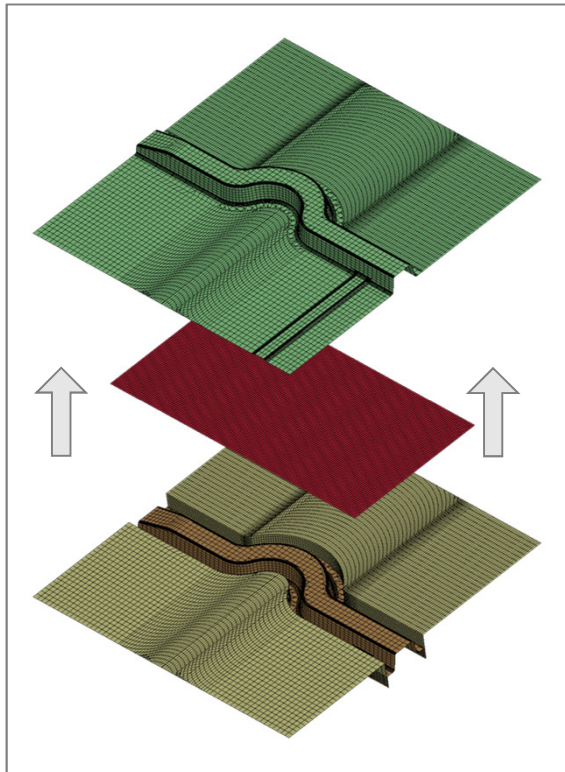
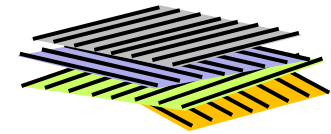
LS-DYNA keyword deck by LS-PrePost
Time = 1.0001



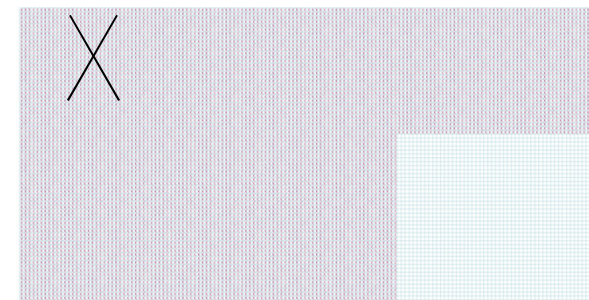
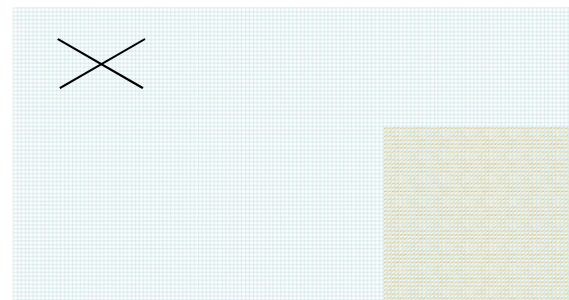
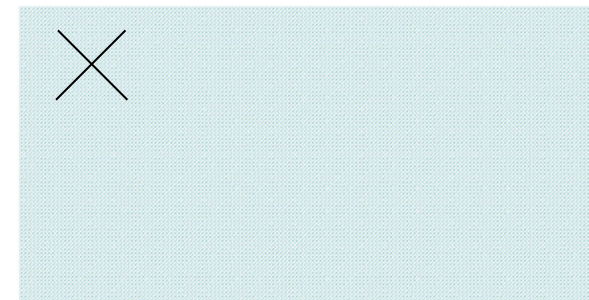
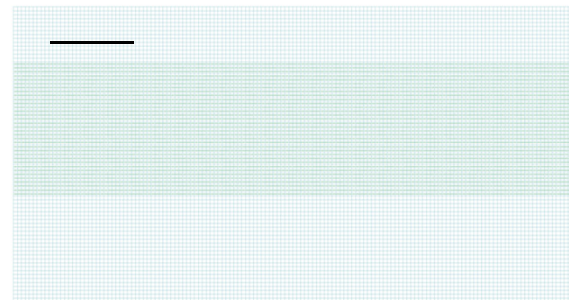
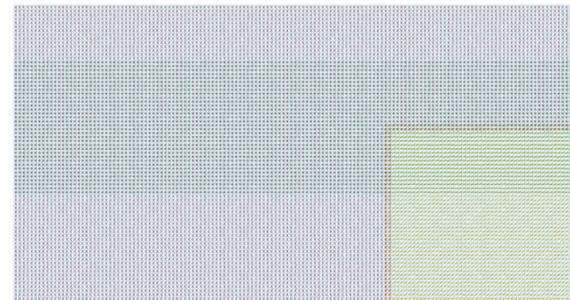
- Next steps: implementation for LS-DYNA standard materials

Draping example: S-Rail

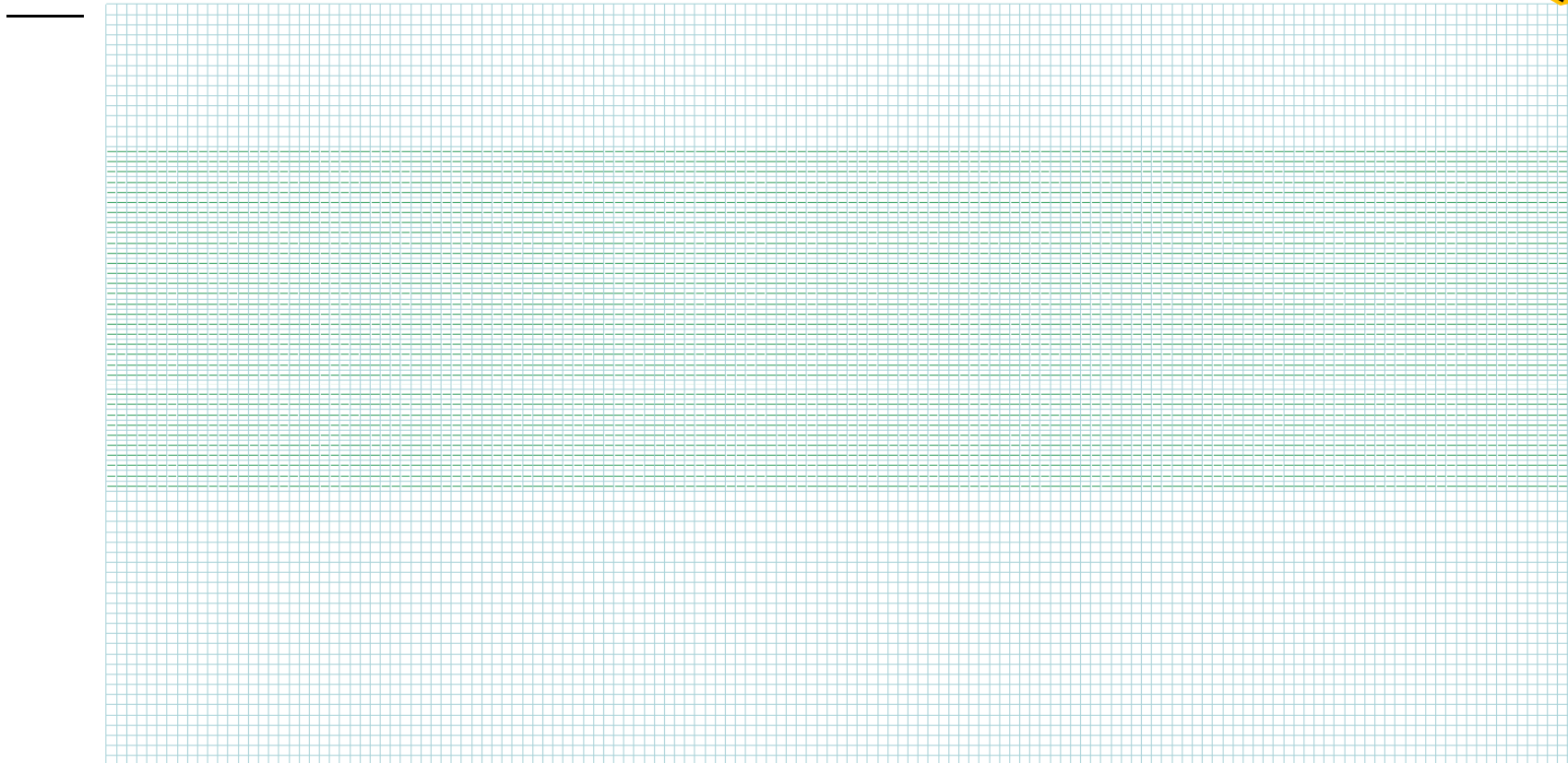
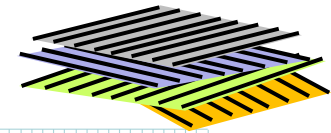
Process simulation



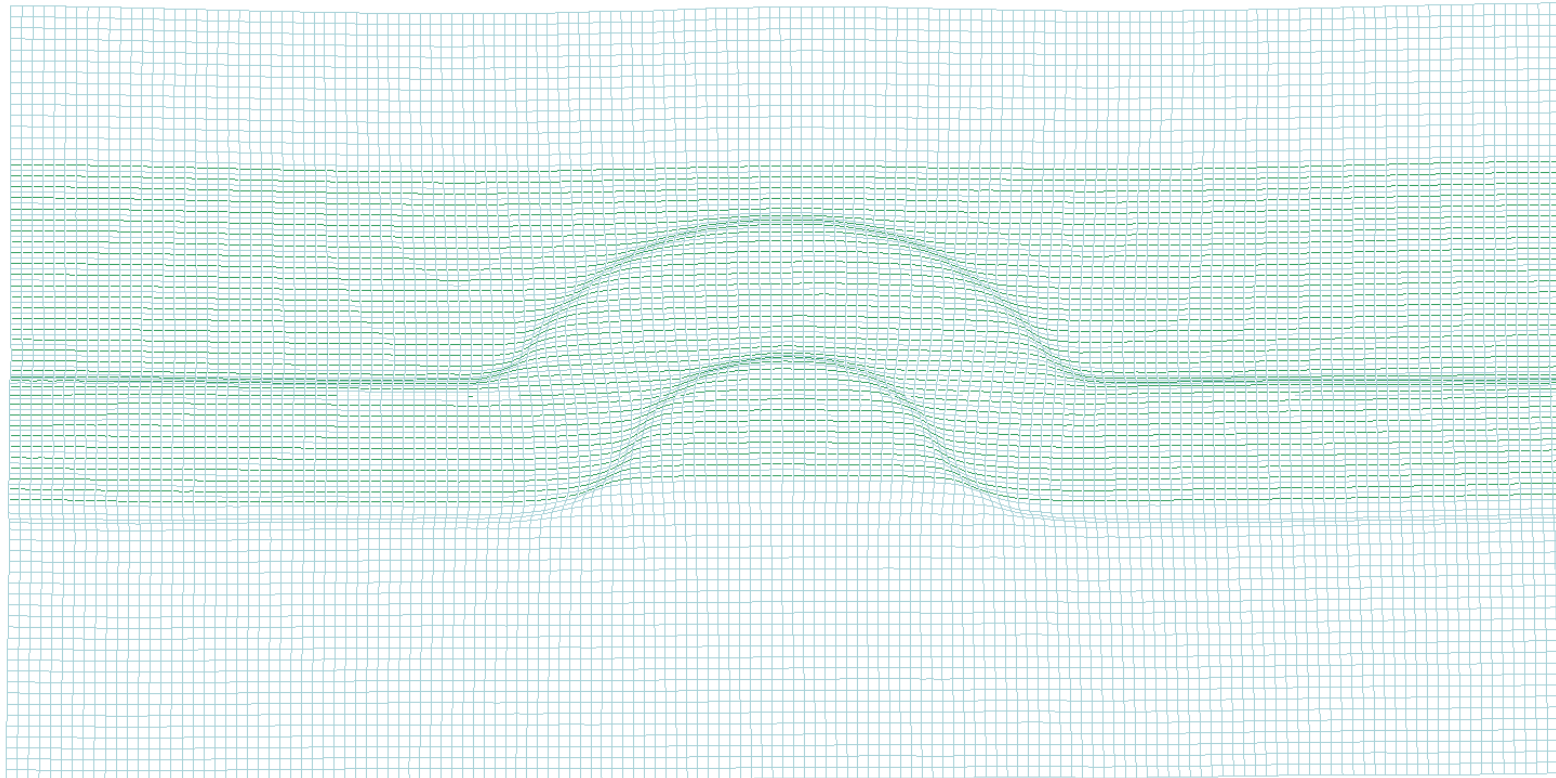
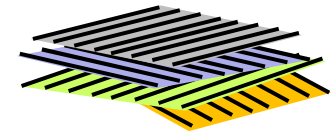
[geometry provided by Benteler-SGL]



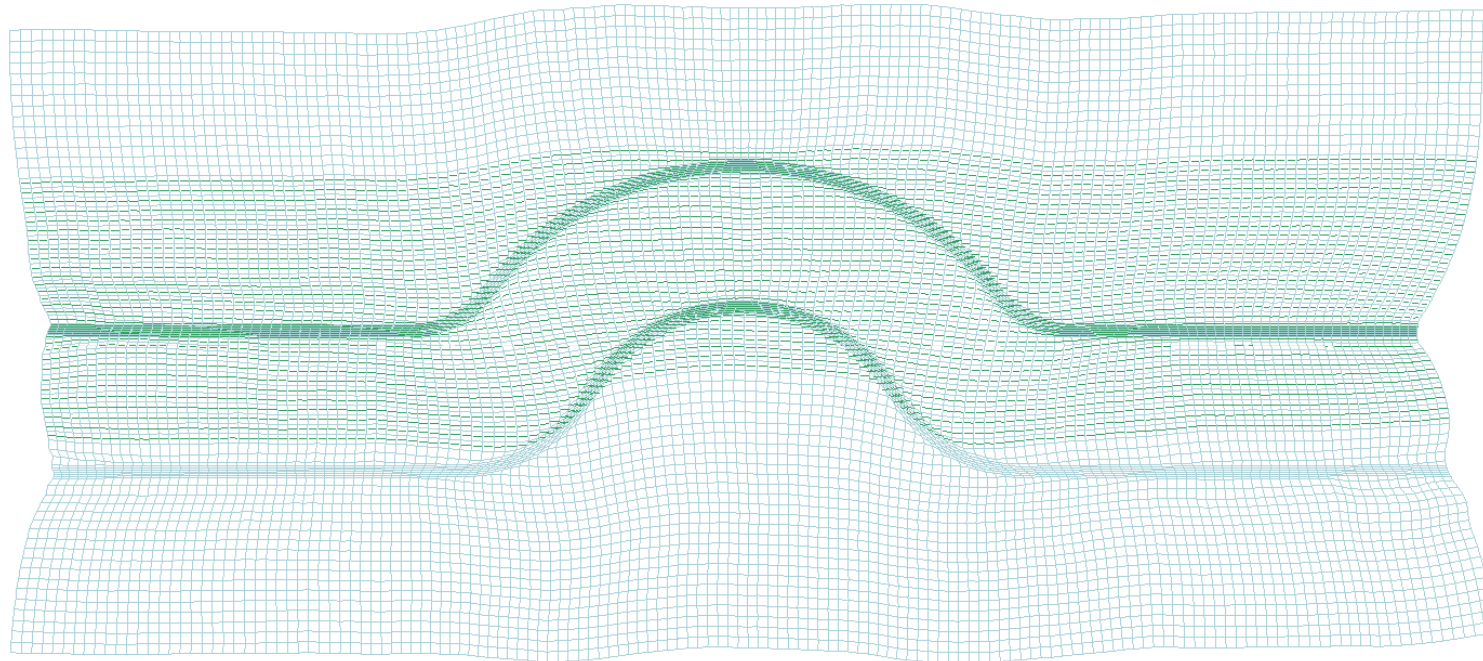
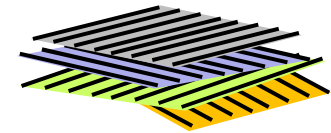
0°- Layer



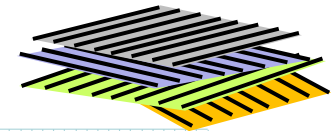
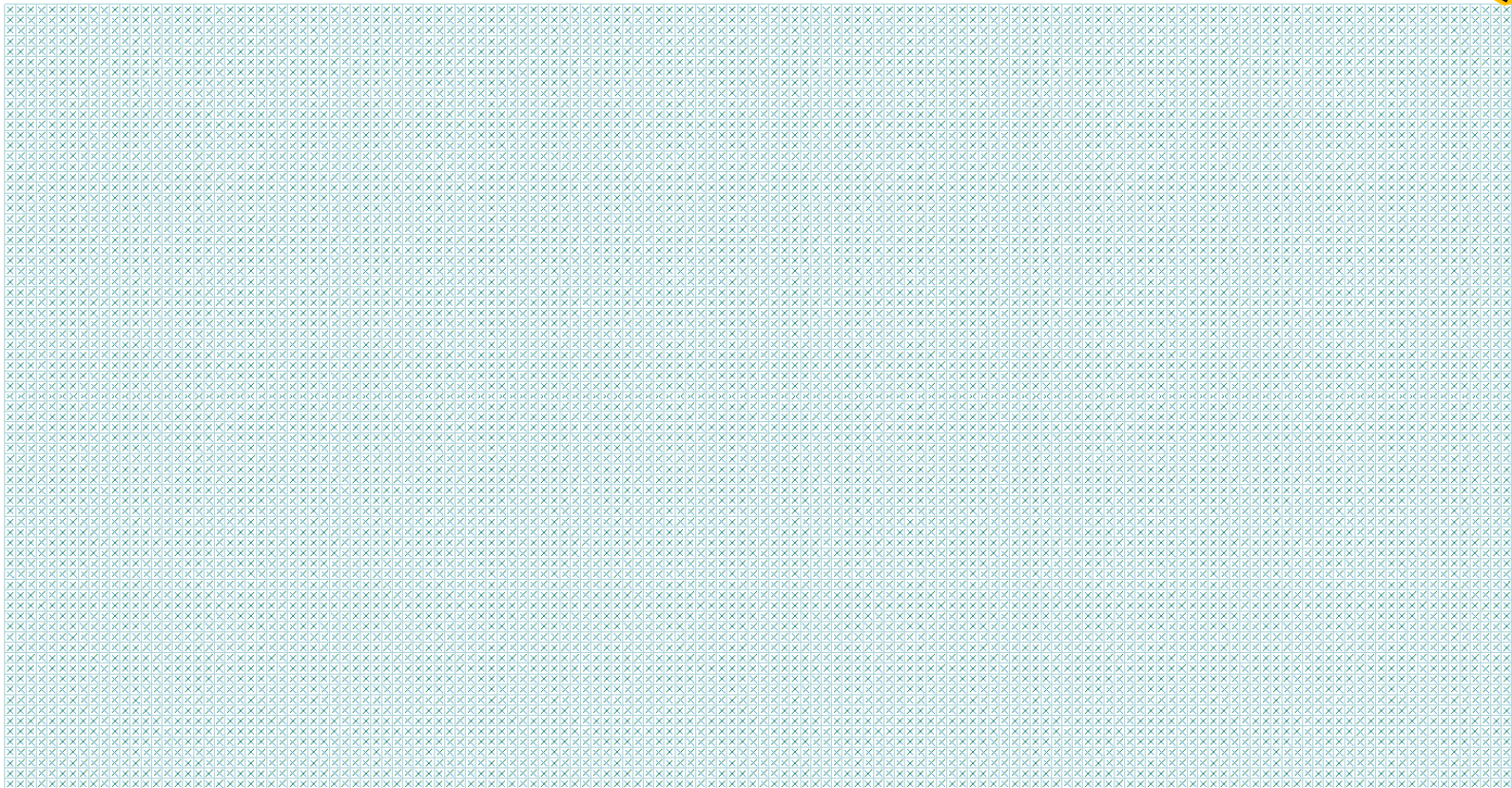
0°- Layer



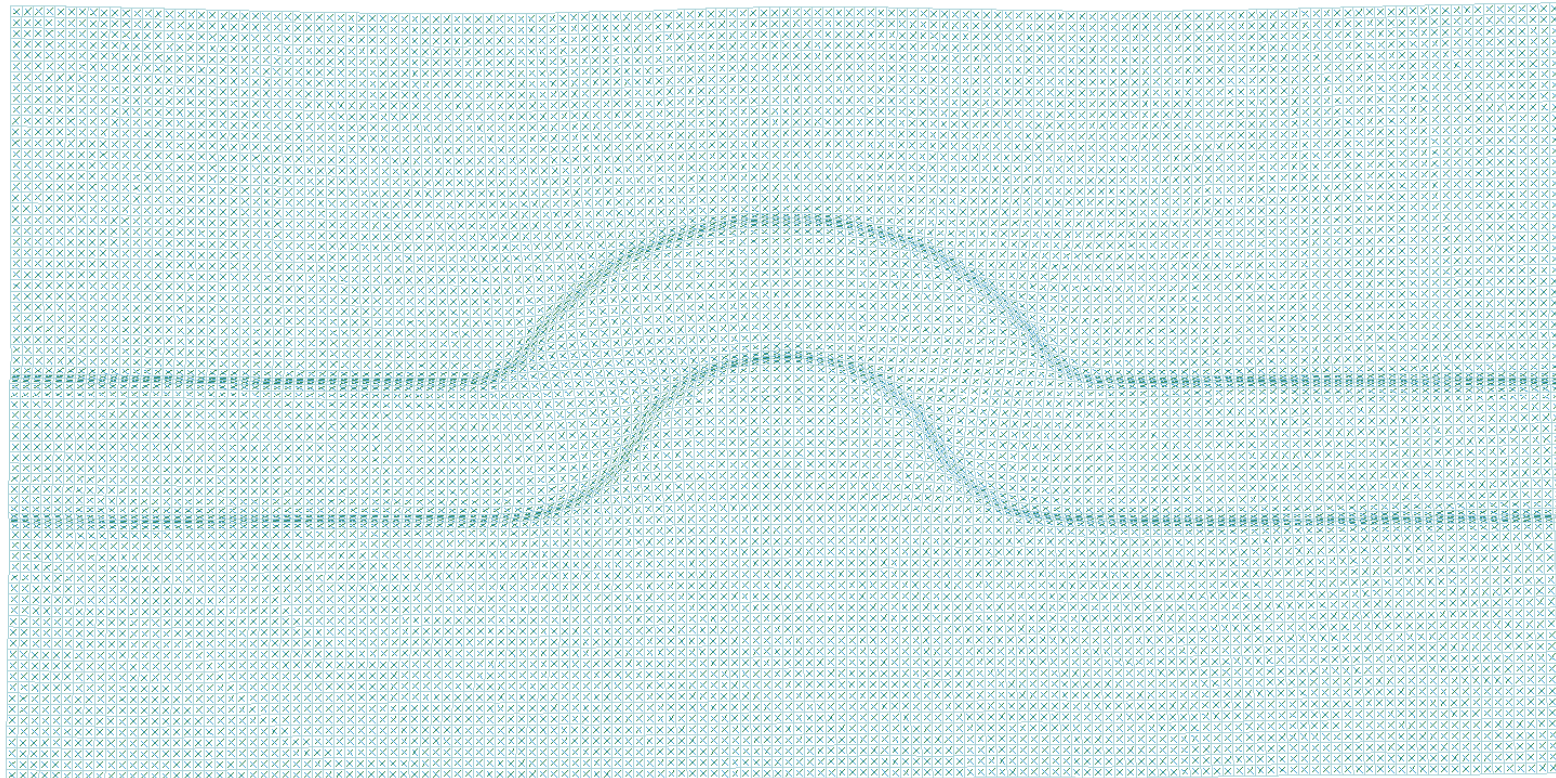
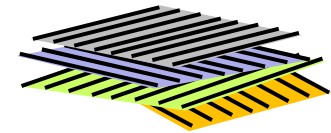
0°- Layer



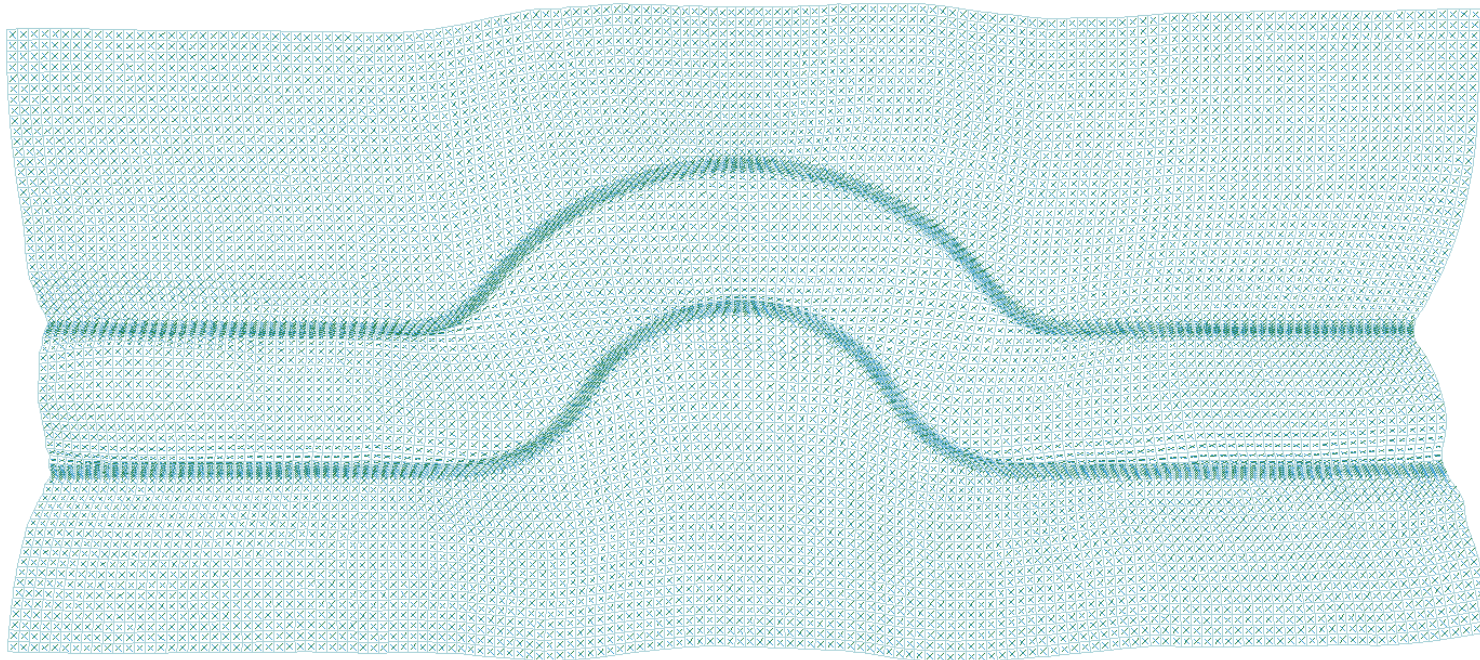
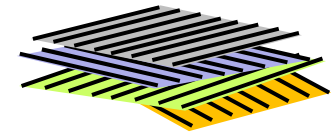
±45° - Layer



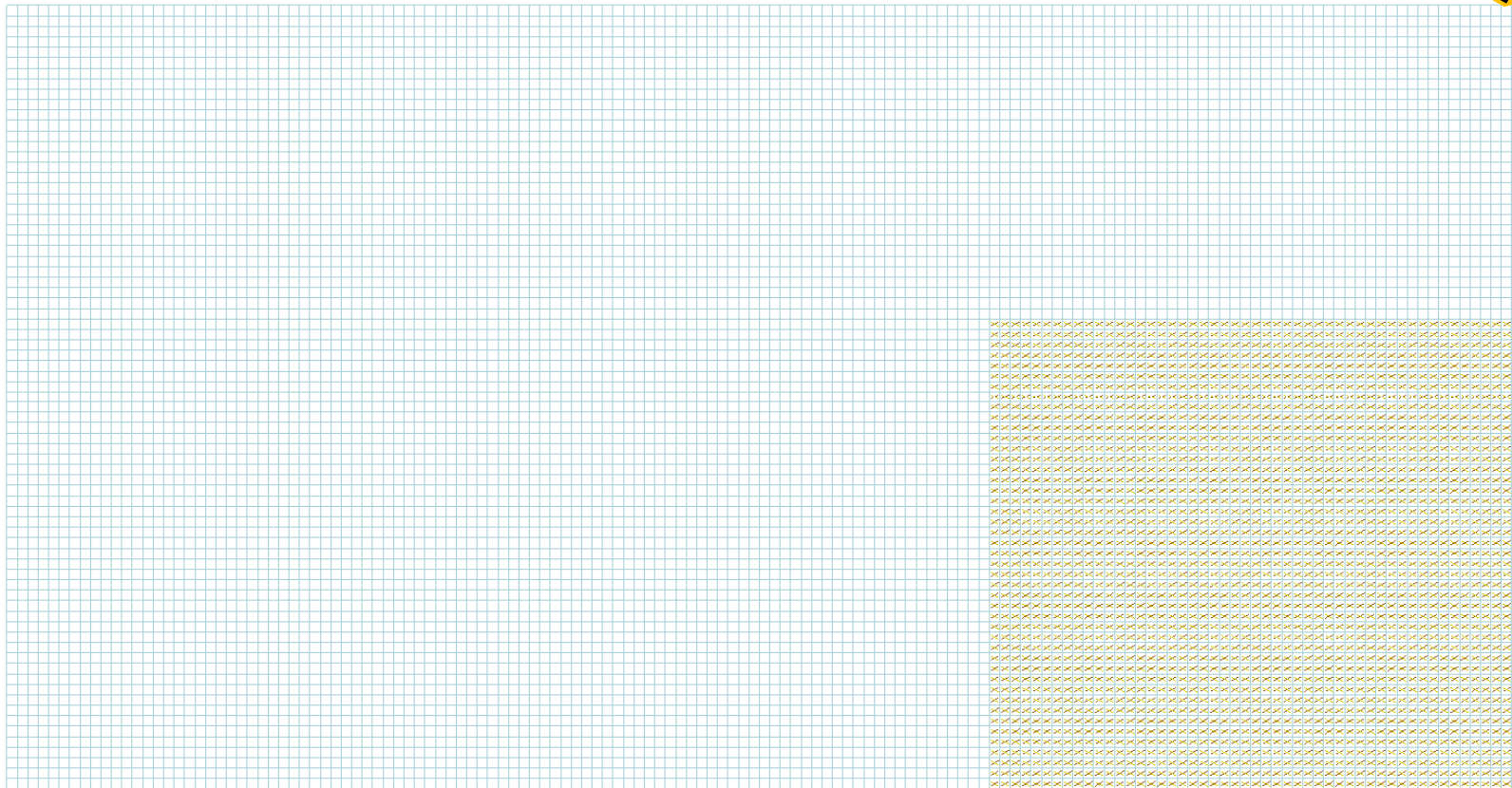
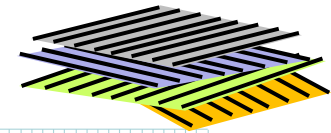
±45° - Layer



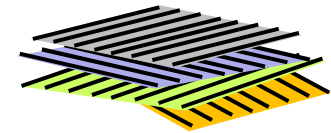
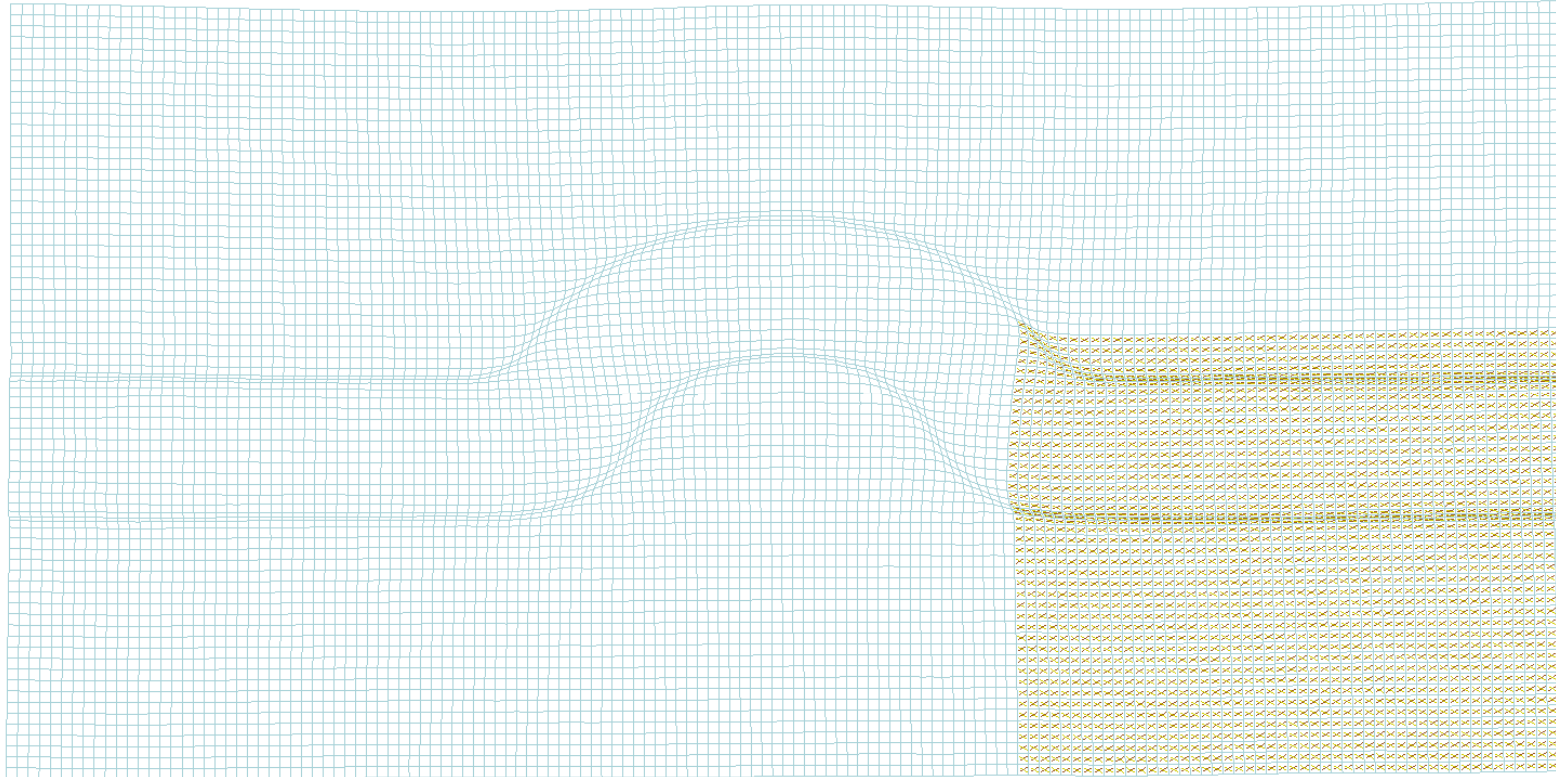
±45° - Layer



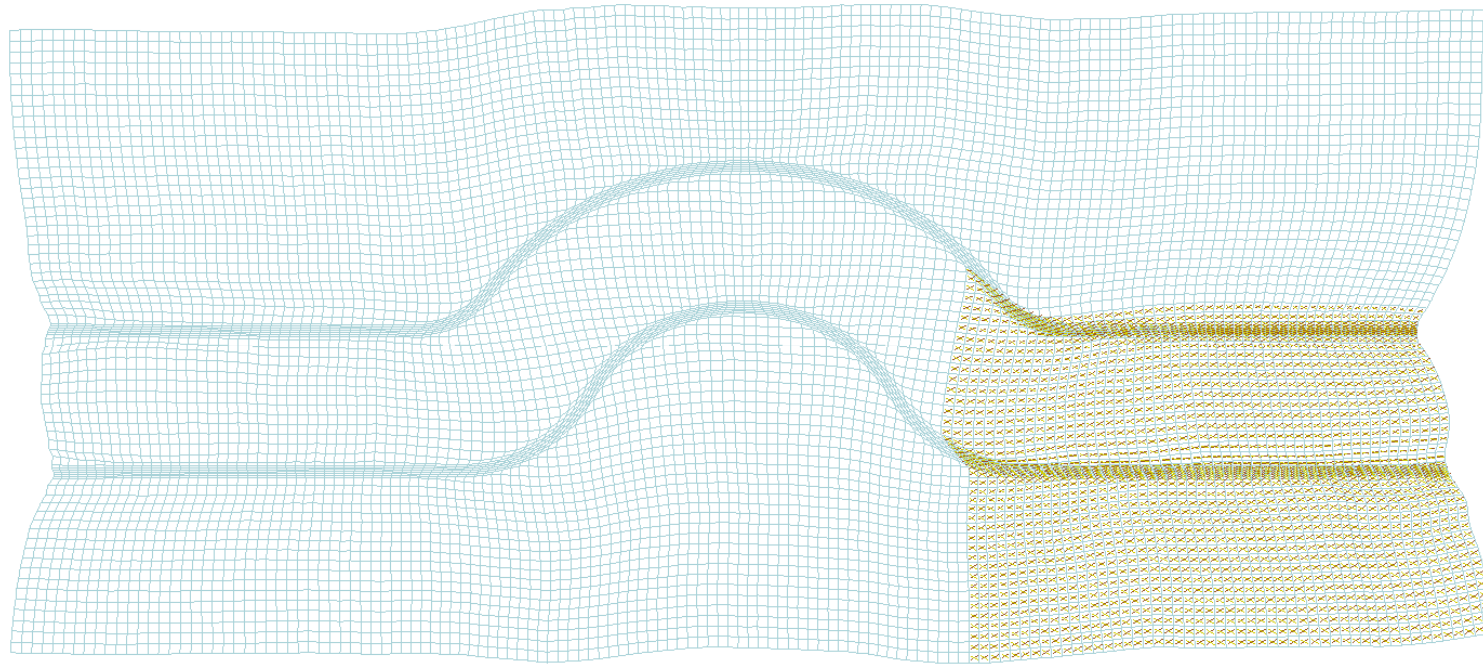
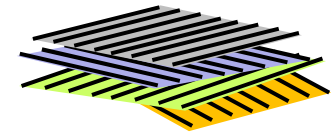
±30° - Layer



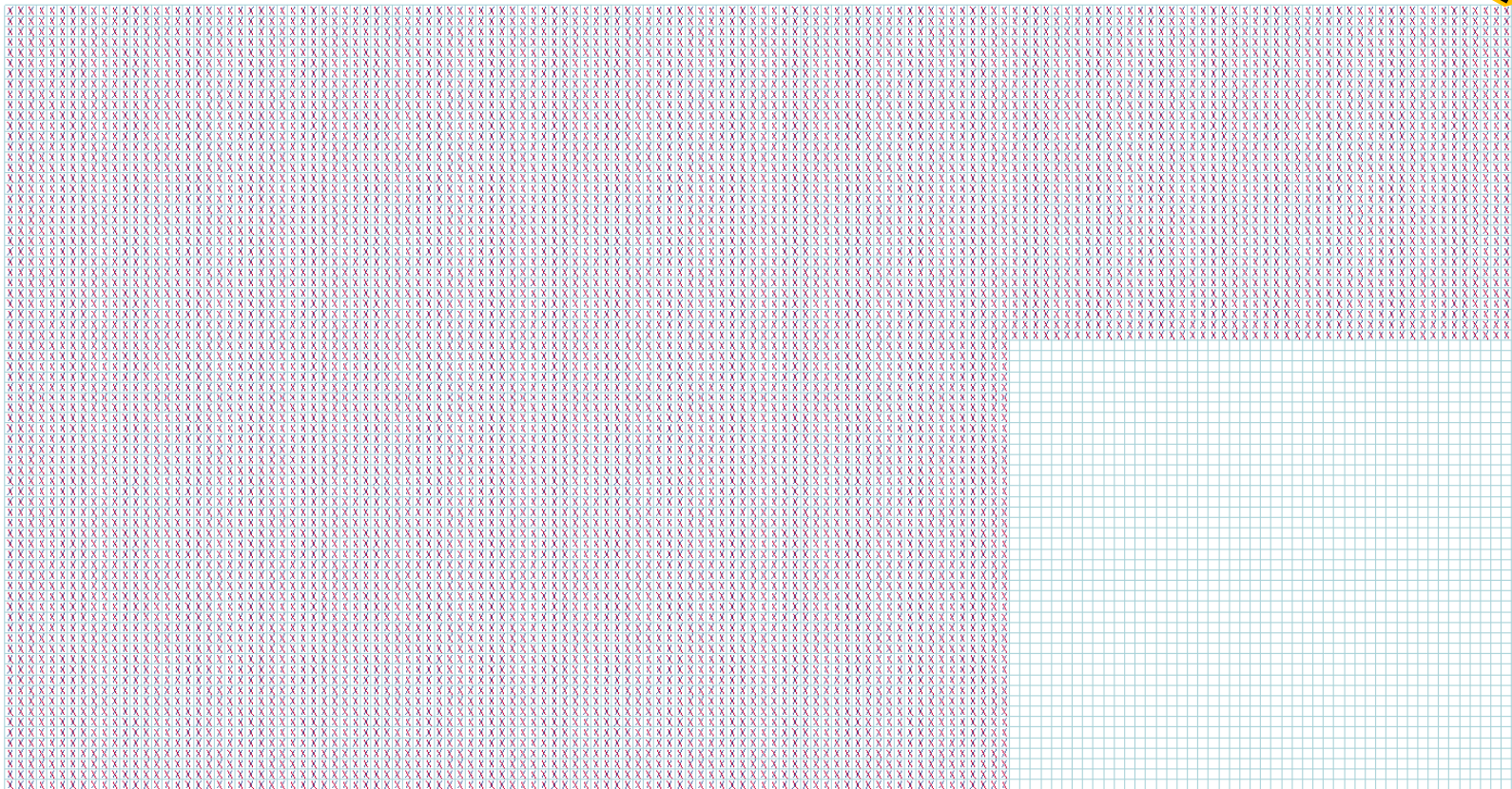
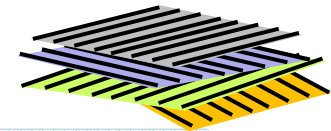
±30° - Layer



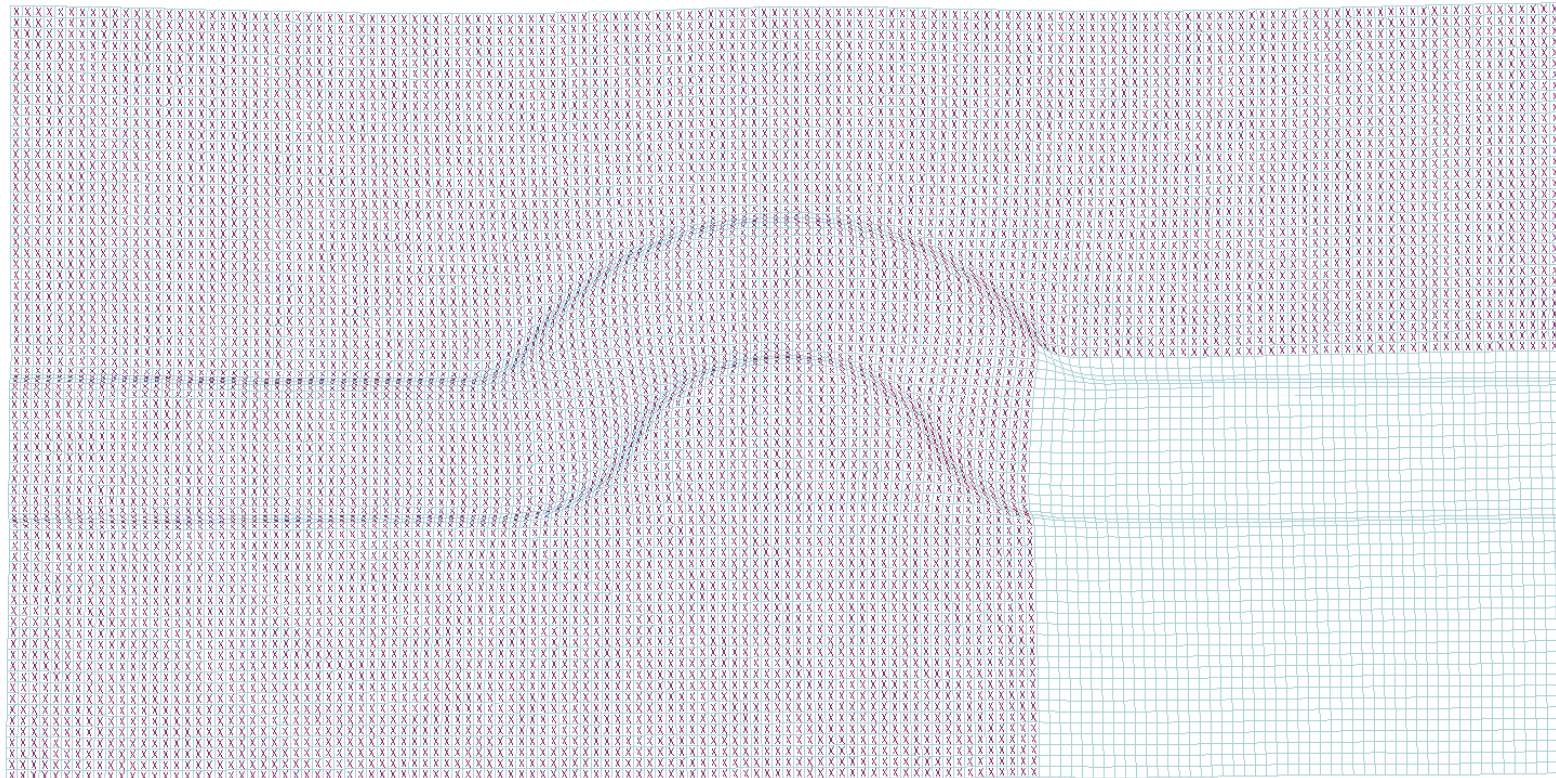
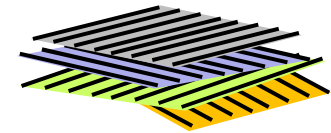
$\pm 30^\circ$ - Layer



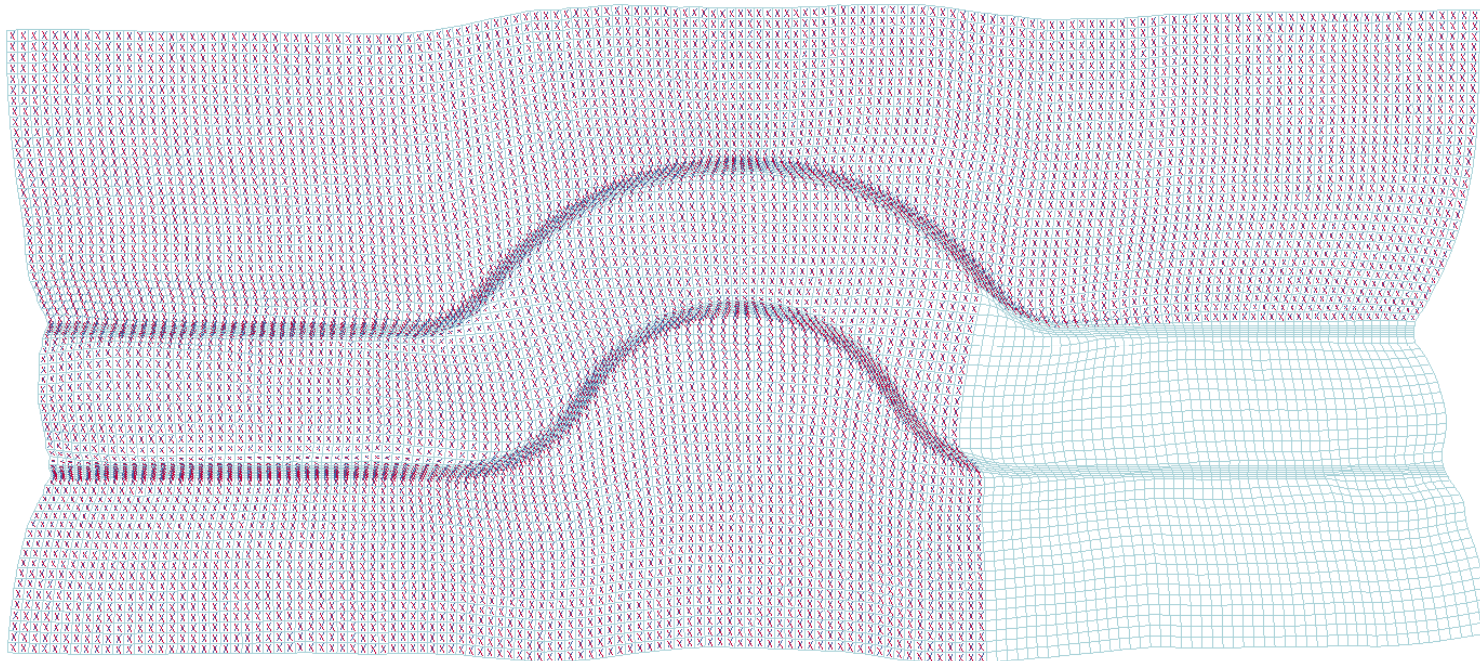
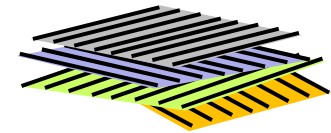
$\pm 60^\circ$ - Layer



$\pm 60^\circ$ - Layer



$\pm 60^\circ$ - Layer



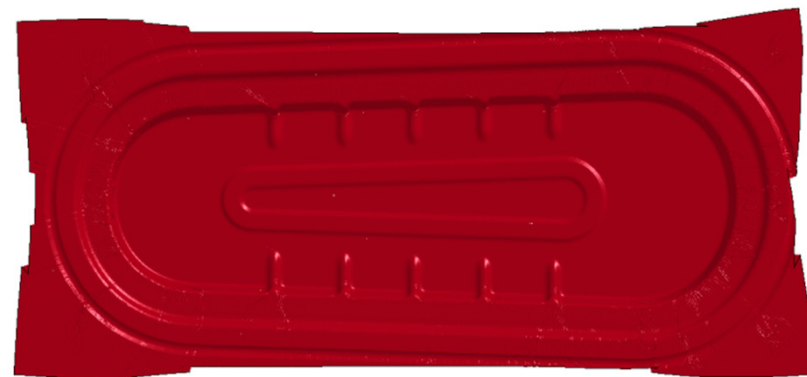
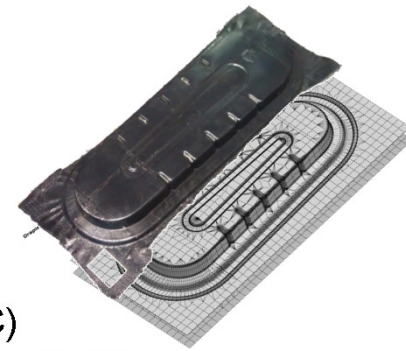


Organo sheet

Process simulation: Organo sheet

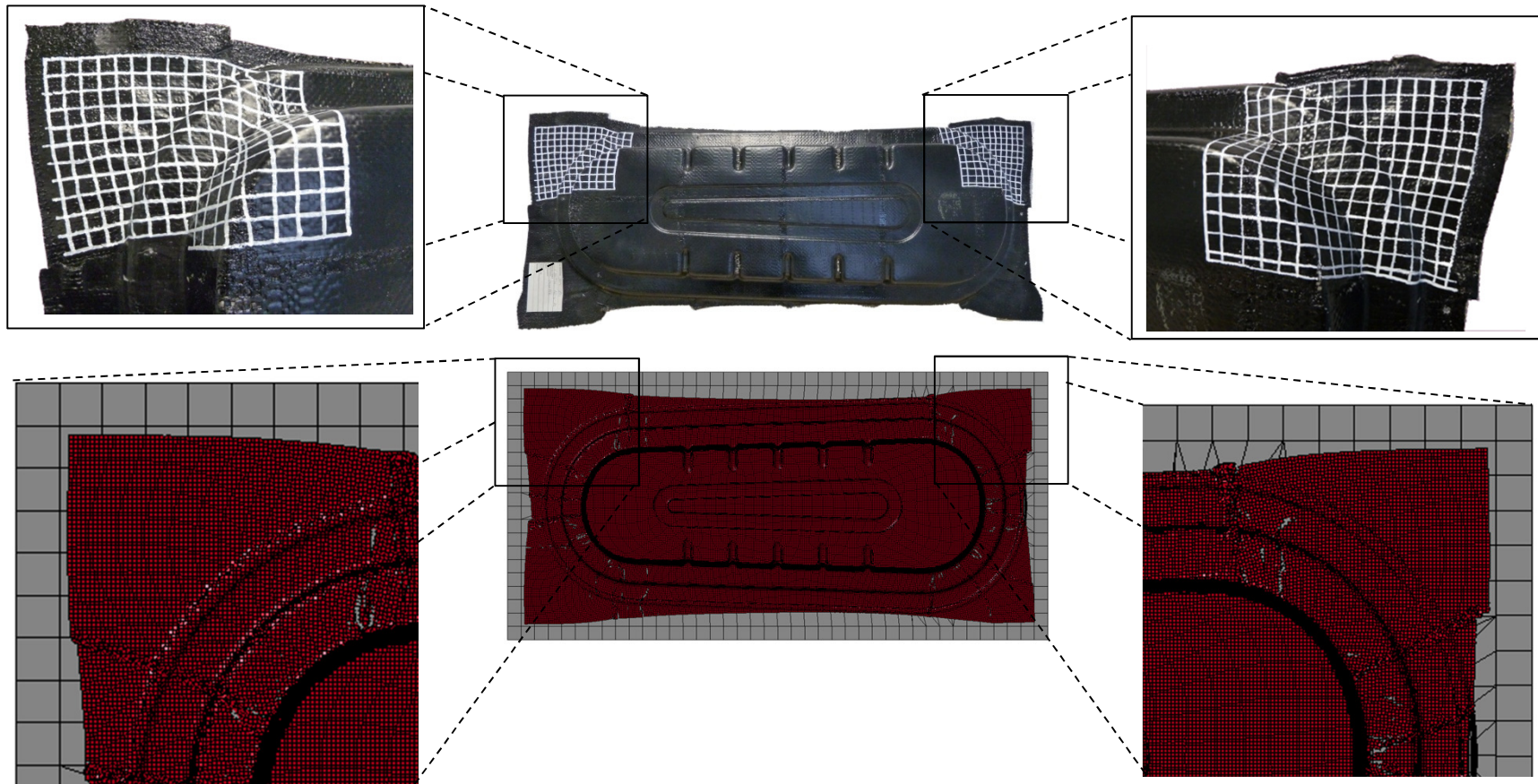
Single layer of woven fabric that is coated on both sides with PA6, $t=1.5\text{mm}$
The forming process is done at 250-300 C.

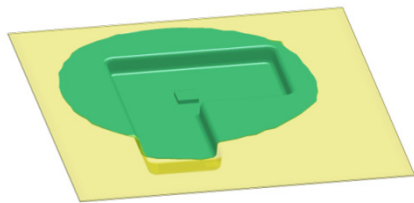
Modeling: Layered shell with *PART_COMPOSITE defining plastic material for PA6 at the outsides (*MAT_PLASTIC_KINEMATIC) and orthotropic material for woven fabric (*MAT_ORTHOTROPIC_ELASTIC).



Process simulation: Organo sheet

Optical comparison of fiber directions (aligned with mesh)

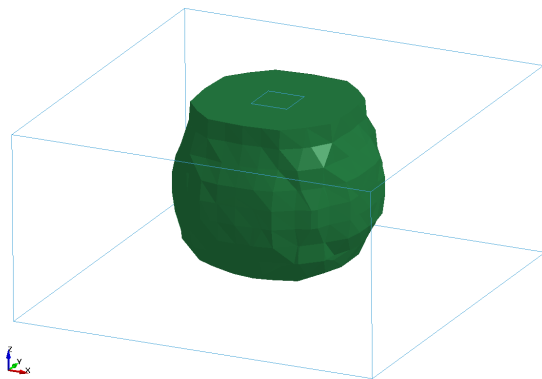




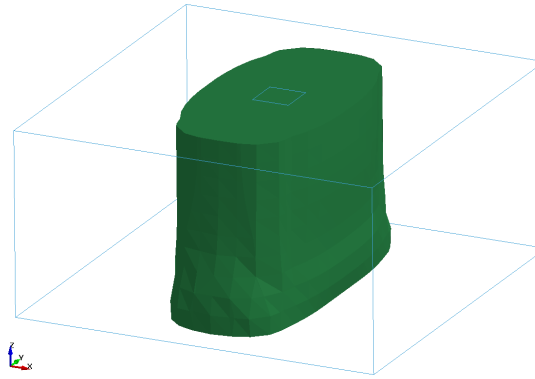
Resin transfer moulding (RTM)

Injection of Resin

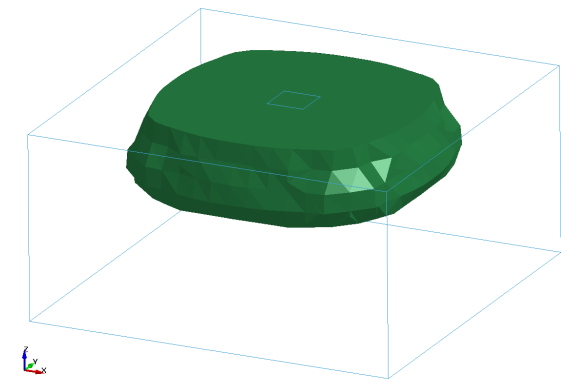
- Infiltration is a 3D flow problem through a porous media
- Porosity depends on the packing density of the fibers
- Fiber orientation results in an anisotropic porosity
- Flow through porous media can be modeled in LS-DYNA using the **CONSTRAINED_LAGRANGE_IN_SOLID** keyword



same porosity in all directions

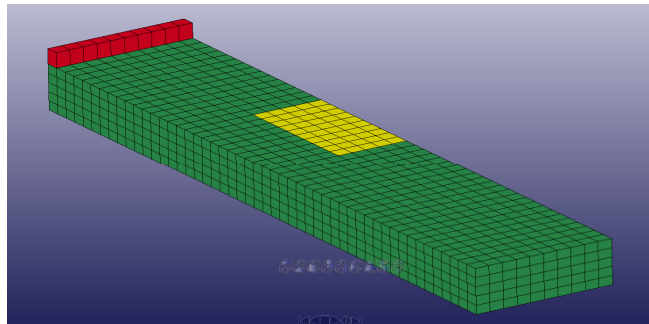


Low porosity in x-direction



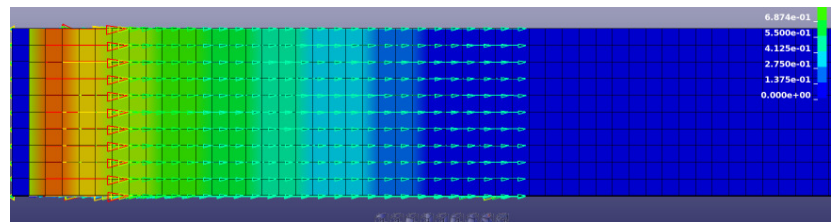
Low porosity in z-direction

Simple test example

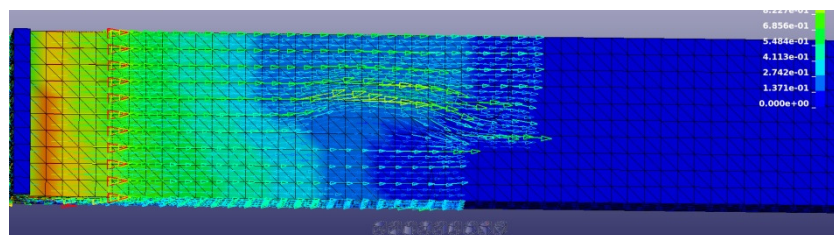


Box with an inclusion
Inflow defined at red elements
Main material (green) and inclusion (yellow)
have same/different viscous coefficients.

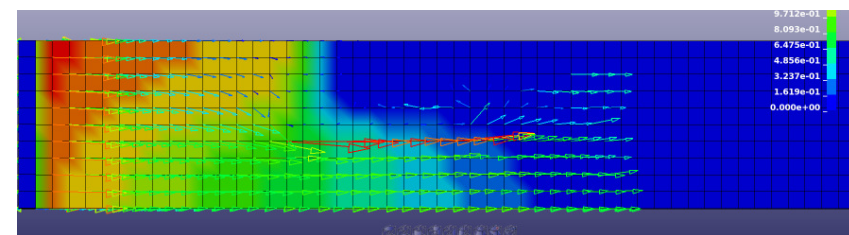
Same porosity coefficients



Inclusion has higher porosity

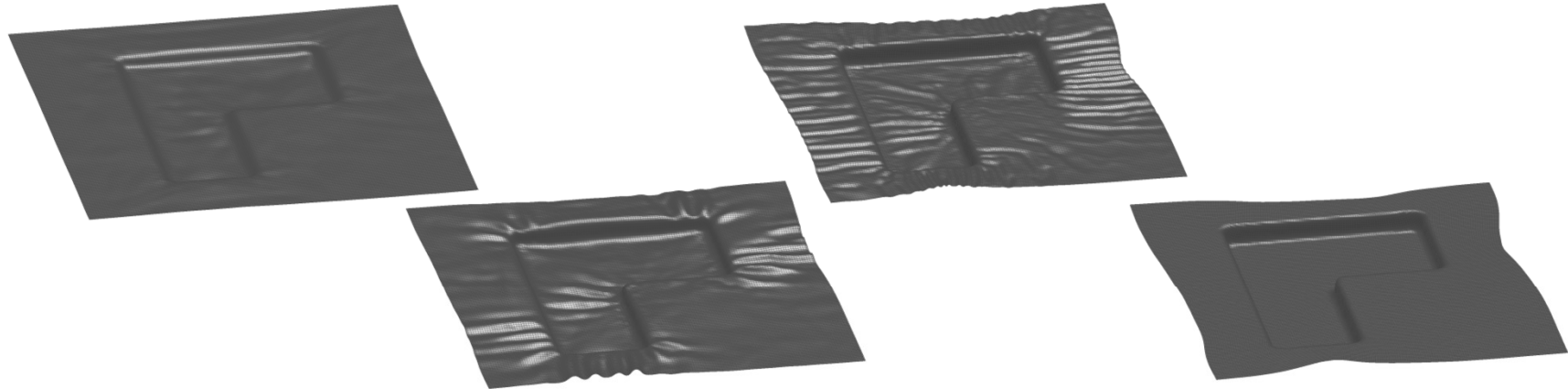


Main material has higher porosity

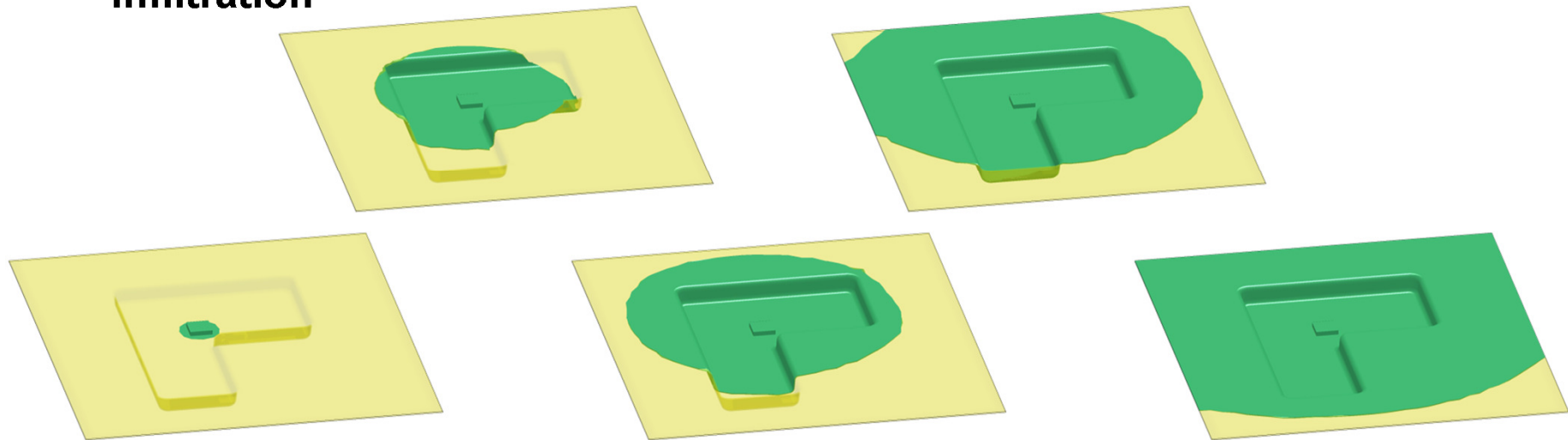


Example: L-Shape

- Draping



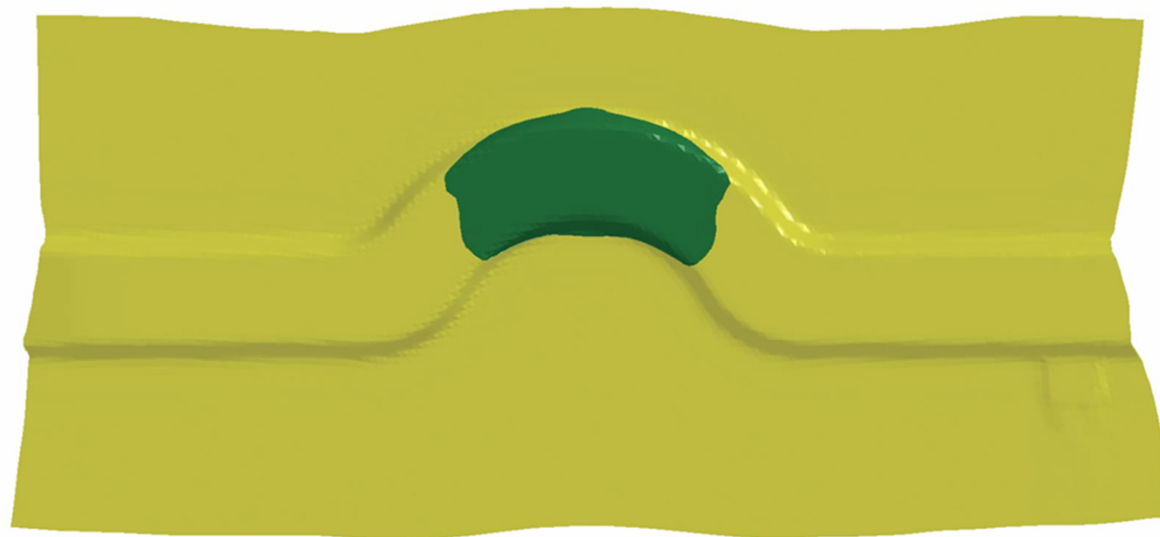
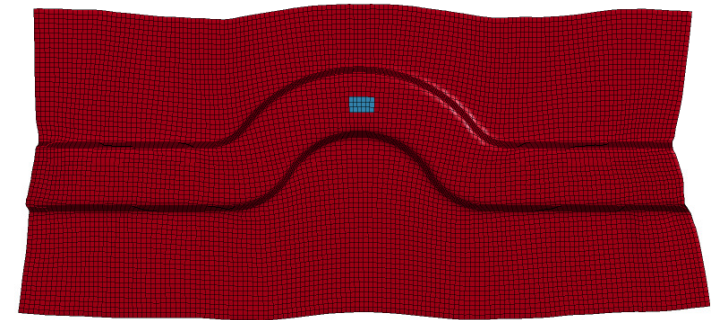
- Infiltration



S-Rail example: Isotropic porosity

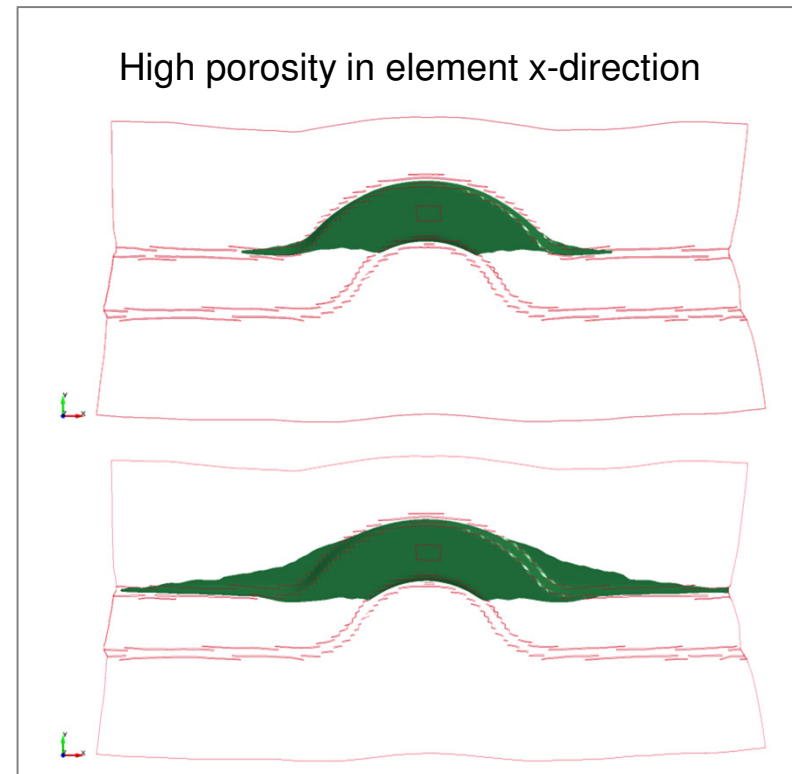
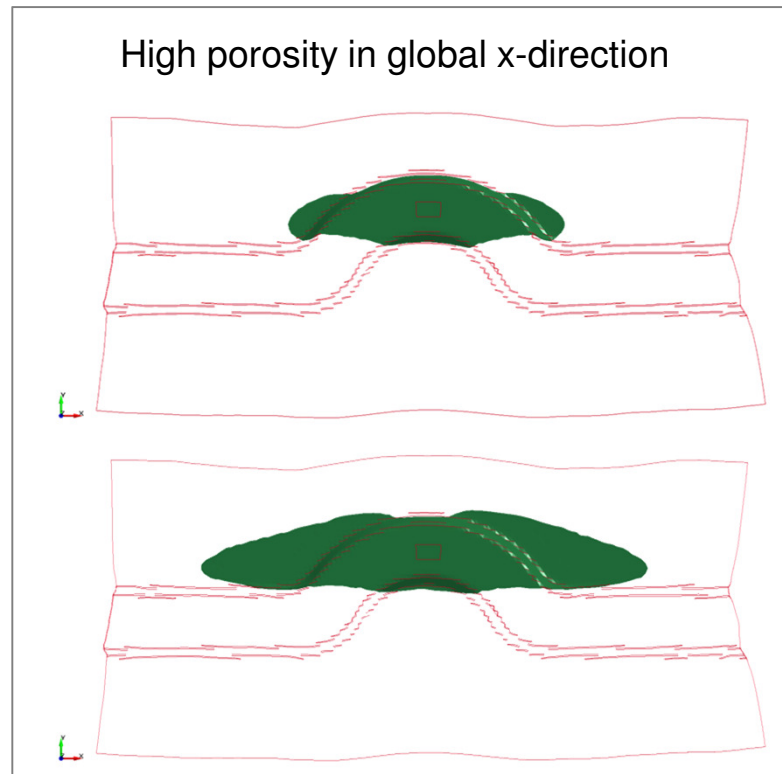
- Mesh obtained from draping simulation
- Flow induced by pressure inlet
- One injection point for resin is considered (blue)

RTM Simulation SRail Geometrie



S-Rail example: Anisotropic porosity

- **LS-DYNA allows to define the porosity with respect to the element coordinate system:**
 - Easy to specify a porosity in thickness direction even for curved geometries
 - Important if the geometry results from a previous draping simulation

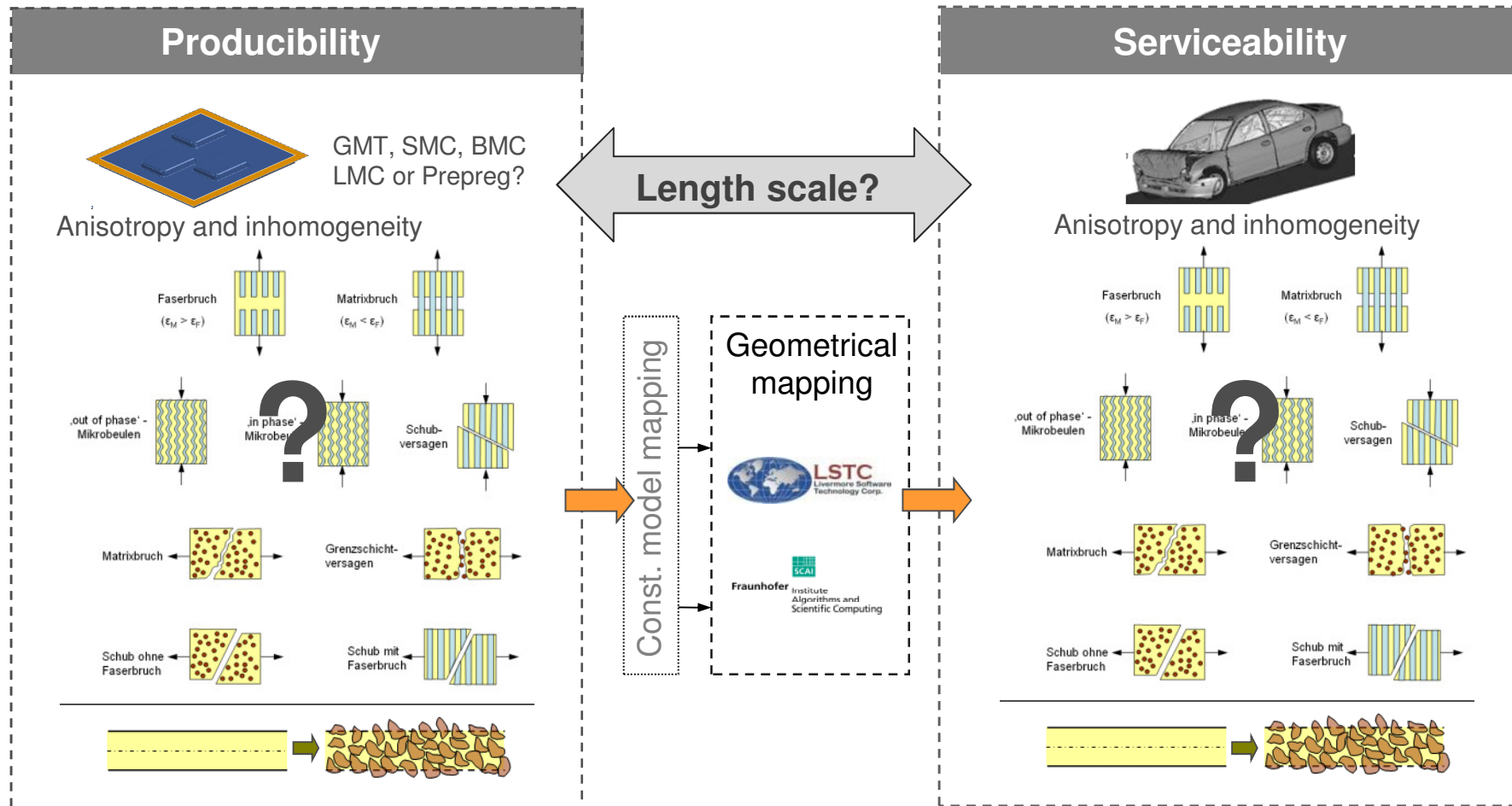


Agenda

- Braiding
- Draping
- Organo sheets
- RTM
- Mapping

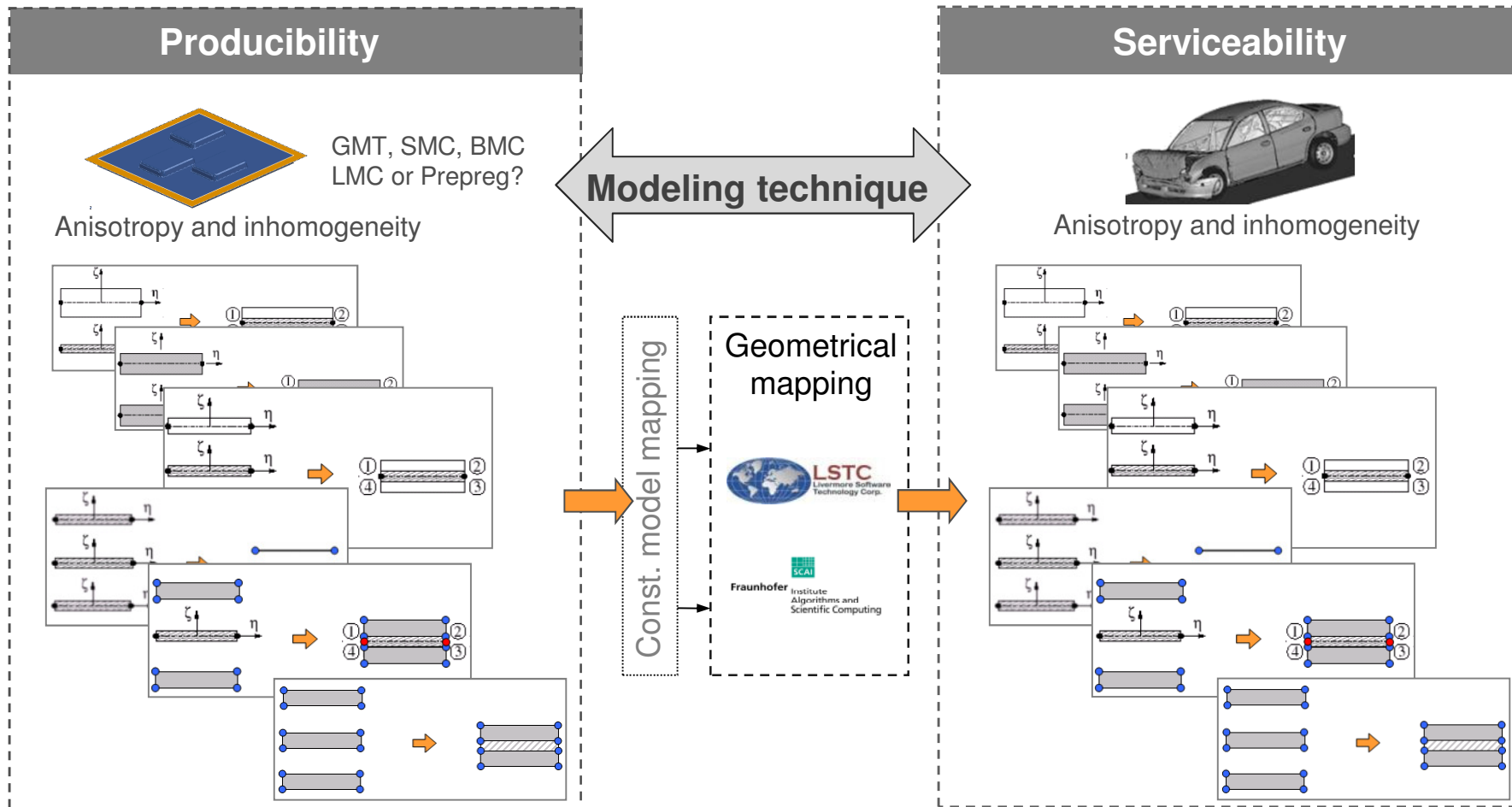
Composite process chain: Producibility2servicability

Problem: Different applications use different modeling techniques, constitutive models, standards and validation procedures.

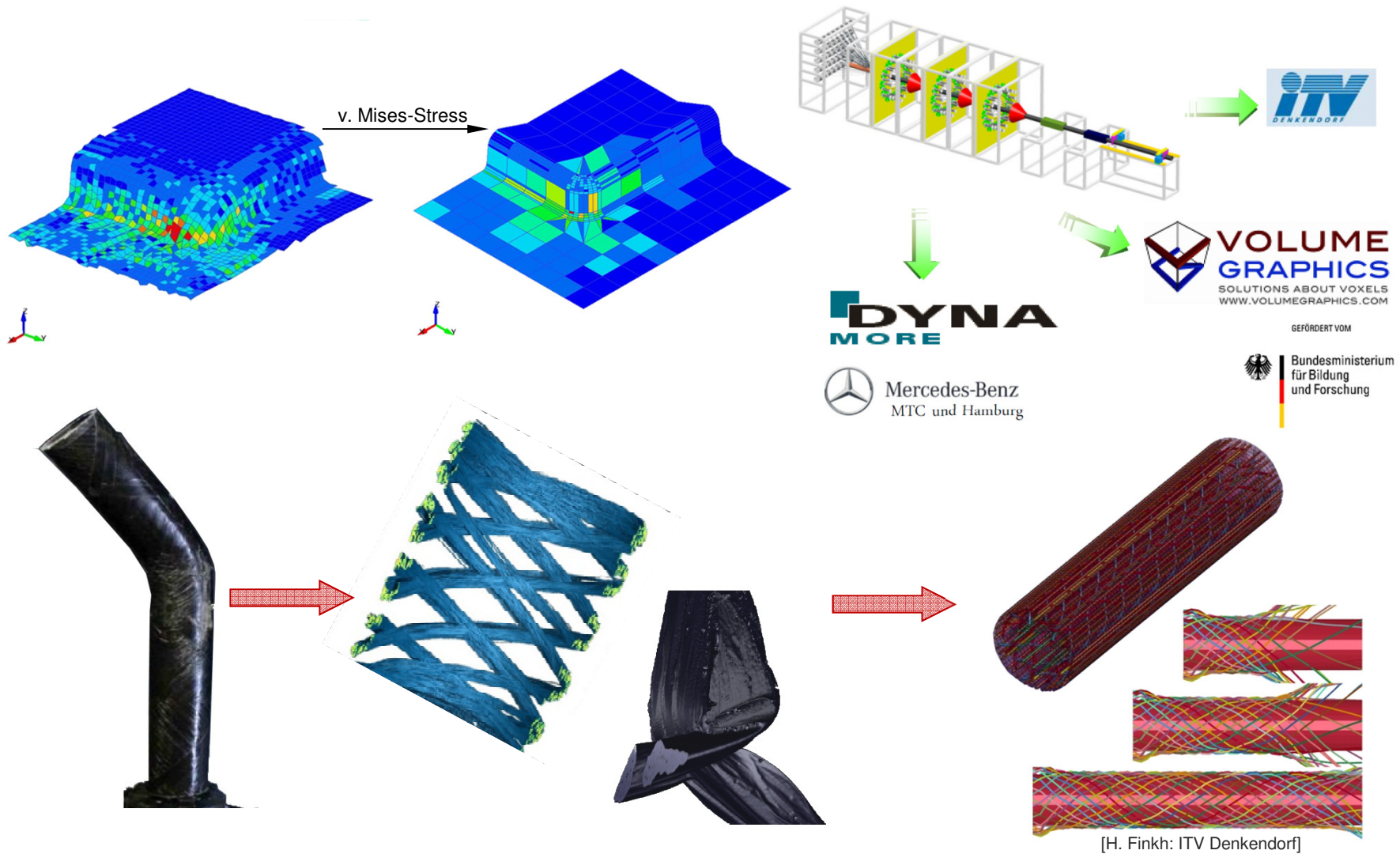


Composite process chain: Producibility2servicability

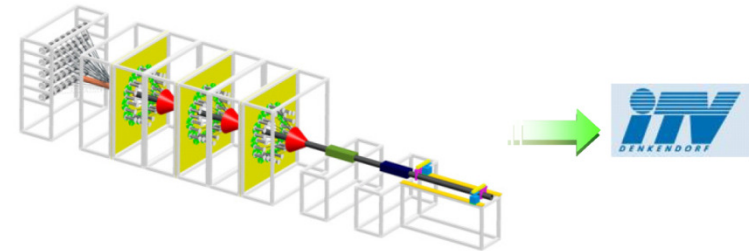
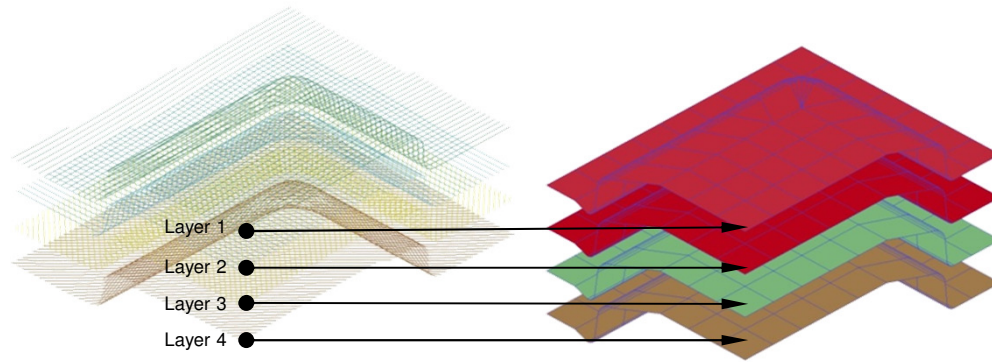
Problem: Different applications use different modeling techniques, constitutive models, standards and validation procedures.



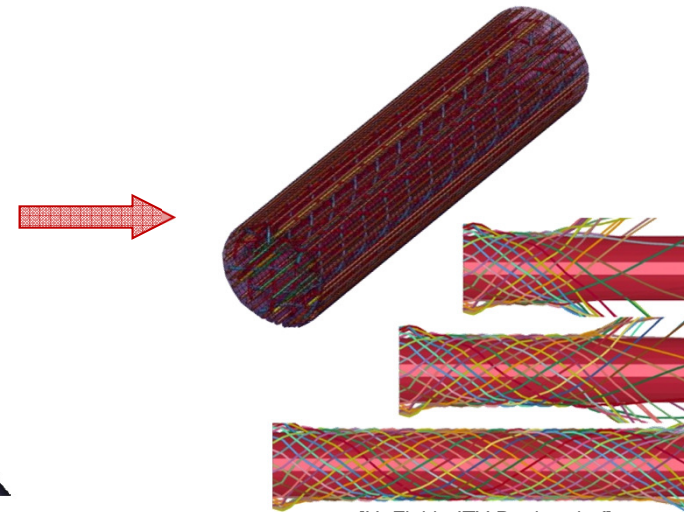
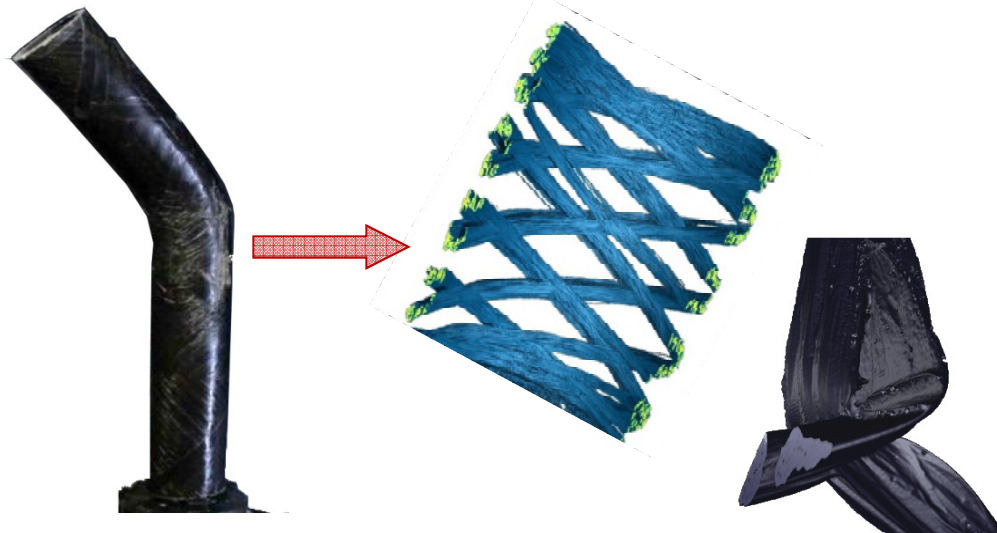
Project TPult



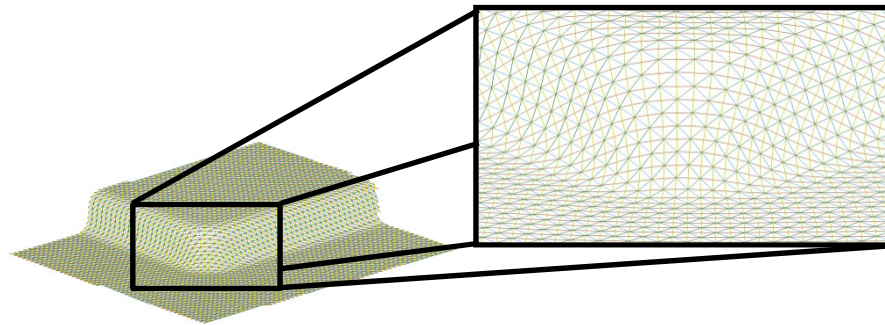
Project TPult



GEFÖRDERT VOM

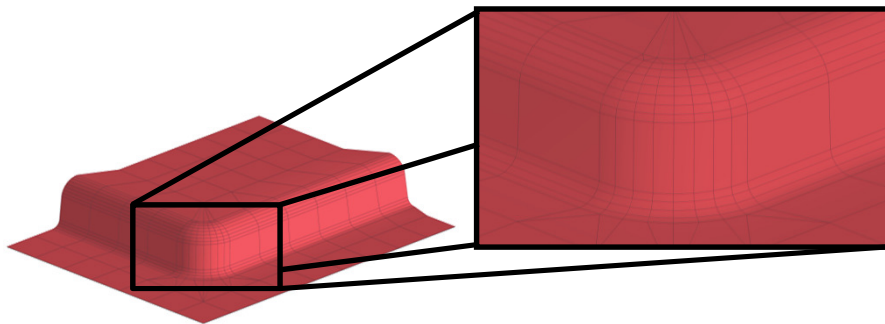


Homogenization strategies



Source Mesh:

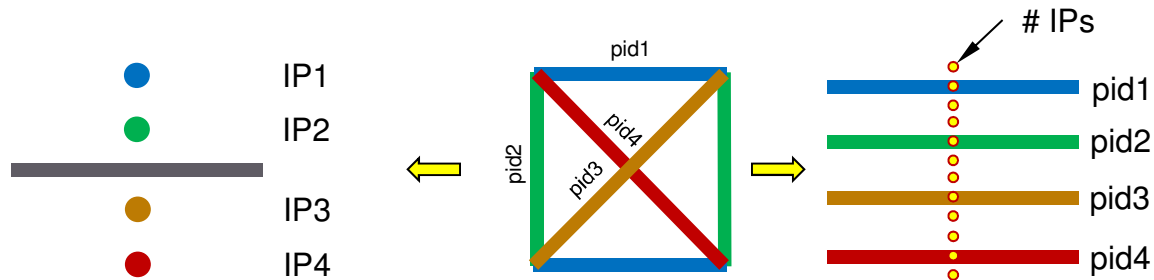
four Parts
 10461 Beam Elements
 avg. length: 1.65 – 3.30 mm



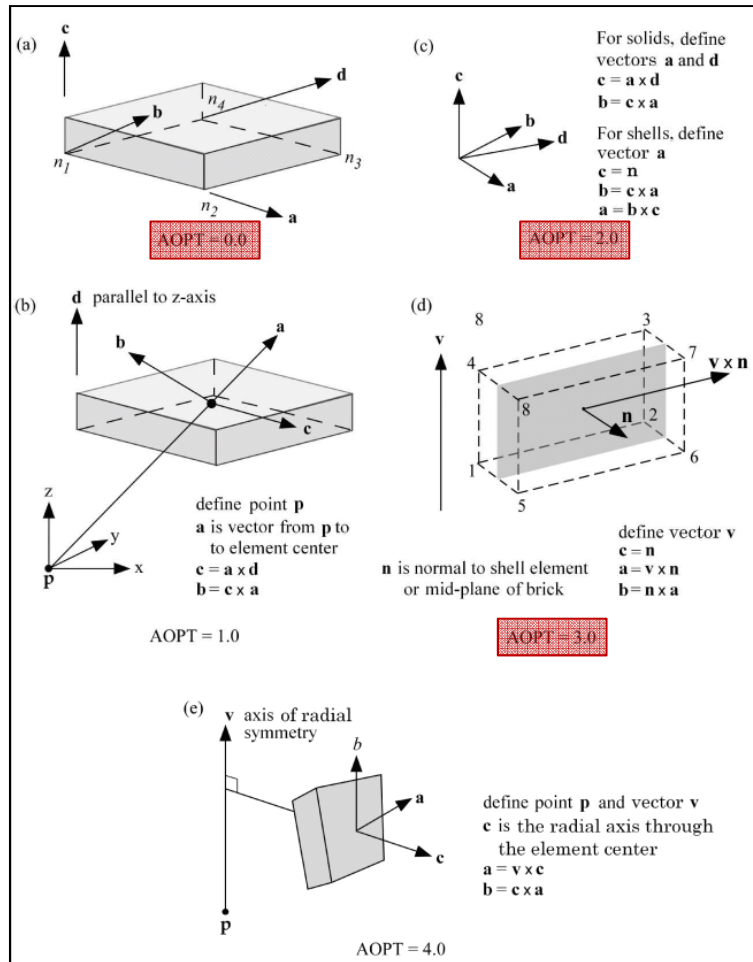
Target Mesh:

one or four Parts
 4x 300 Shell Elements
 avg. length: 1.80 – 18.40 mm

Homogenization strategies:

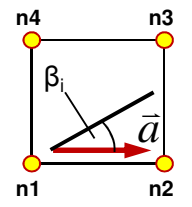


Fiber orientation definition



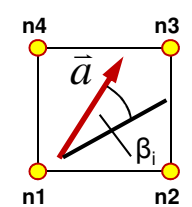
AOPT considered so far...

AOPT = 0



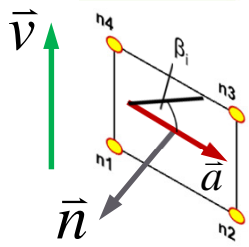
No further user-input required
 Main fiber direction determined by the element's main axis ($n1 \rightarrow n2$)
 β_i can be varied by *ELEMENT_SHELL_COMPOSITE or *PART_COMPOSITE

AOPT = 2



Vector \vec{a} has to be user-defined
 β_i can be varied by *ELEMENT_SHELL_COMPOSITE or *PART_COMPOSITE

AOPT = 3



Vector \vec{v} has to be user-defined
 Main fiber direction $\vec{a} = \vec{v} \times \vec{n}$
 β_i can be varied by *ELEMENT_SHELL_COMPOSITE or *PART_COMPOSITE

***PART_COMPOSITE (_TSHELL)**

Composite Lay up

```

$-----1-----2-----3-----4-----5-----6-----7-----8
$   PID|   ELFORM|   SHRF|   NLOC|   MAREA|   HGID|   ADOPT|
$   MID1|  THICK1|   BETA1|           MID2|  THICK2|   BETA2|
$   MID3|  THICK3|   BETA3|           MID4|  THICK4|   BETA4|
  
```

***ELEMENT_ (T) SHELL_COMPOSITE**

Composite Lay up

```

$-----1-----2-----3-----4-----5-----6-----7-----8-----9-----10
$  EID|   PID|   N1|   N2|   N3|   N4|   N5|   N6|   N7|   N8|
$  MID1|  THICK1|   BETA1|           MID2|  THICK2|   BETA2|
$  MID3|  THICK3|   BETA3|           MID4|  THICK4|   BETA4|
  
```

***ELEMENT_ (T) SHELL_BETA**

Composite Lay up

```

$-----1-----2-----3-----4-----5-----6-----7-----8-----9-----10
$  EID|   PID|   N1|   N2|   N3|   N4|   N5|   N6|   N7|   N8|
$          THICK1|   THICK2|   THICK3|   THICK4|   BETA
  
```

***MAT_ORTHOTROPIC_ELASTIC**

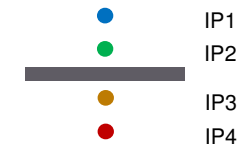
```

$-----1-----2-----3-----4-----5-----6-----7-----8
$   MID|   RO|   EA|   EB|   EC|   PRBA|   PRCA|   PRCB|
$   GAB|   GBC|   GCA|   AOPT|           MACF|
$   XP|   YP|   ZP|   A1|   A2|   A3|   MACF|
$   V1|   V2|   V3|   D1|   D2|   D3|   BETA|   REF|
  
```

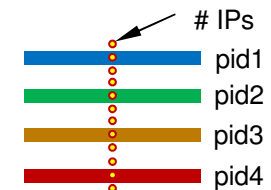
Fiber orientations as a result of a combination of **AOPT** &

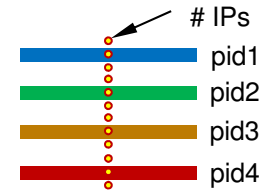
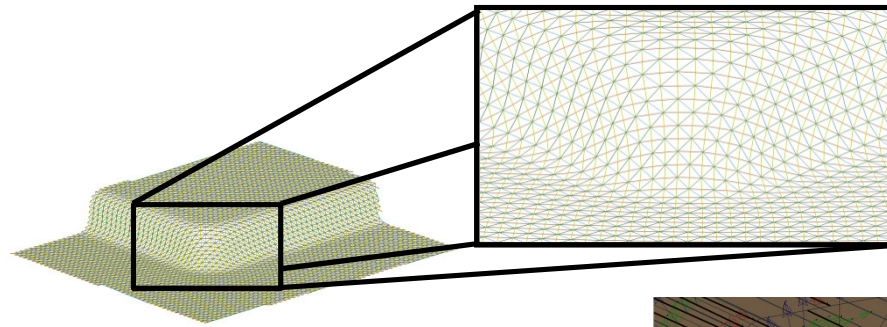
$$\theta_i = \beta + \beta_i$$

*Part_Composite
*Element_Shell_Composite
Diff. Materials for each integration point conceivable

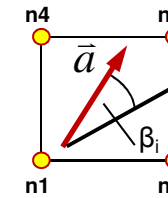


Stacked *Element_Shell_Beta
*Element_Shell & diff. Materials
Cohesive Elements/*Tiebreak
Contact modeling required





AOPT = 2



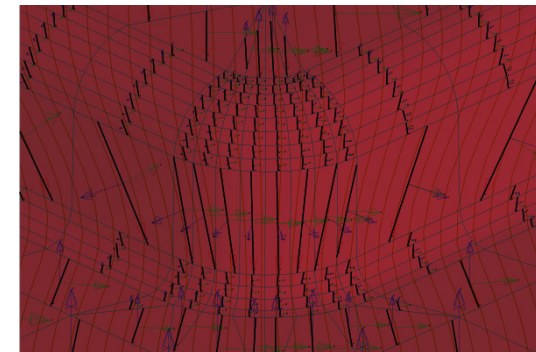
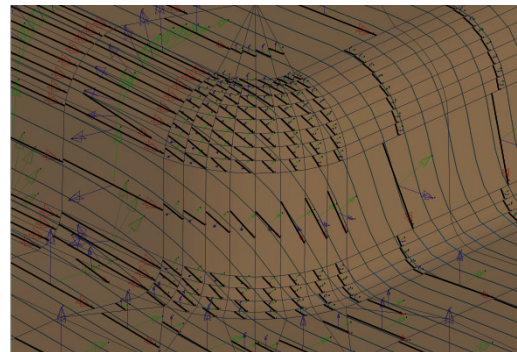
Layer 1

Layer 3

Vector \vec{a} is given directly by the orientations of the beam elements
 *ELEMENT_SHELL_COMPOSITE or
 *PART_COMPOSITE

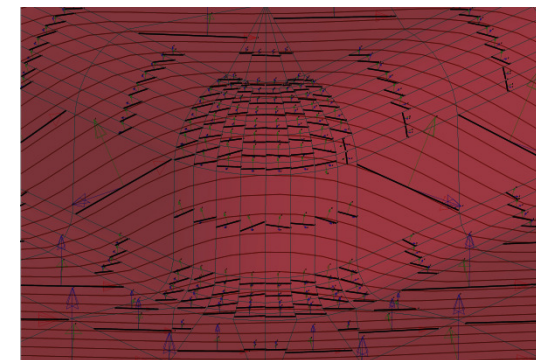
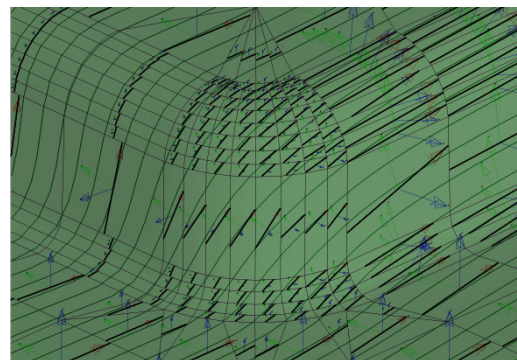
Main disadvantage:

- Each element get's an assigned material card -> 300 elements eq. 300 diff. material cards
- good as a first tryout, but not relevant for any kind of simulation

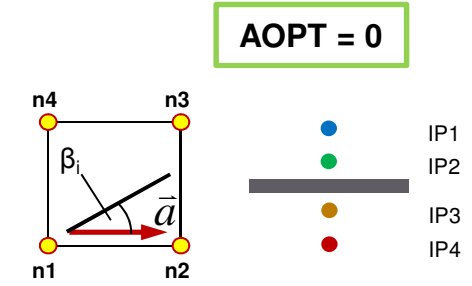
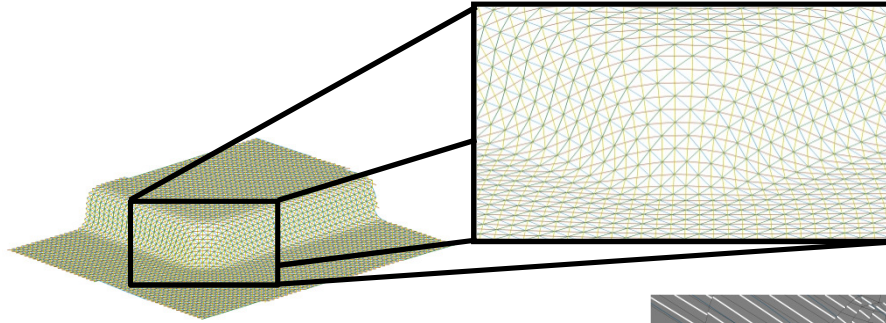


Layer 2

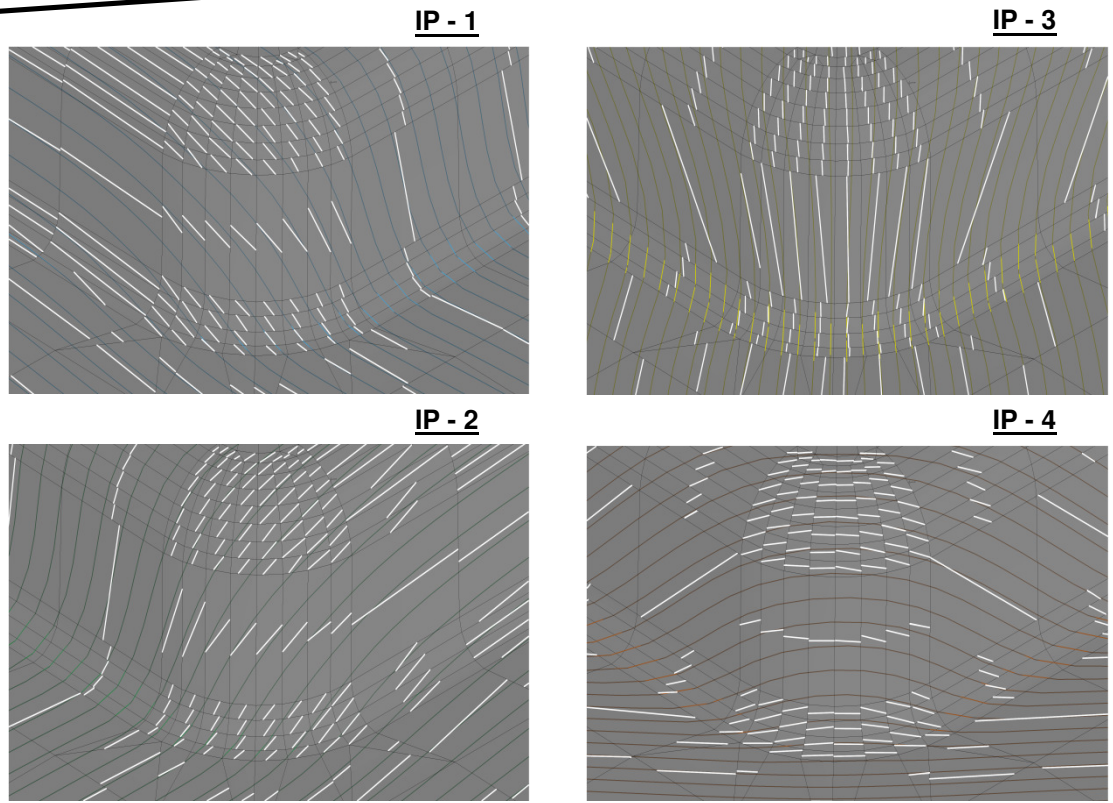
Layer 4



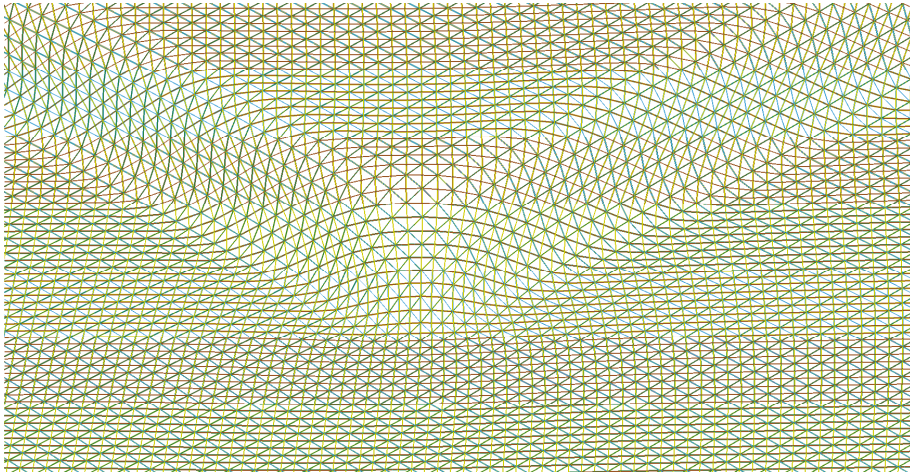
Usage of Element-Direction:



Vector \vec{a} is given directly by the element orientation
 *ELEMENT_SHELL_COMPOSITE or
 *PART_COMPOSITE
 Identification of β_i is a little bit more complicated than writing fiber orientation directly into the material card
 Only one material card per part!
 Relevant for crash simulations...



Mapping with LS-PrePost



Generate vector fields for each main fiber direction (four in this case)
*.dvm - File

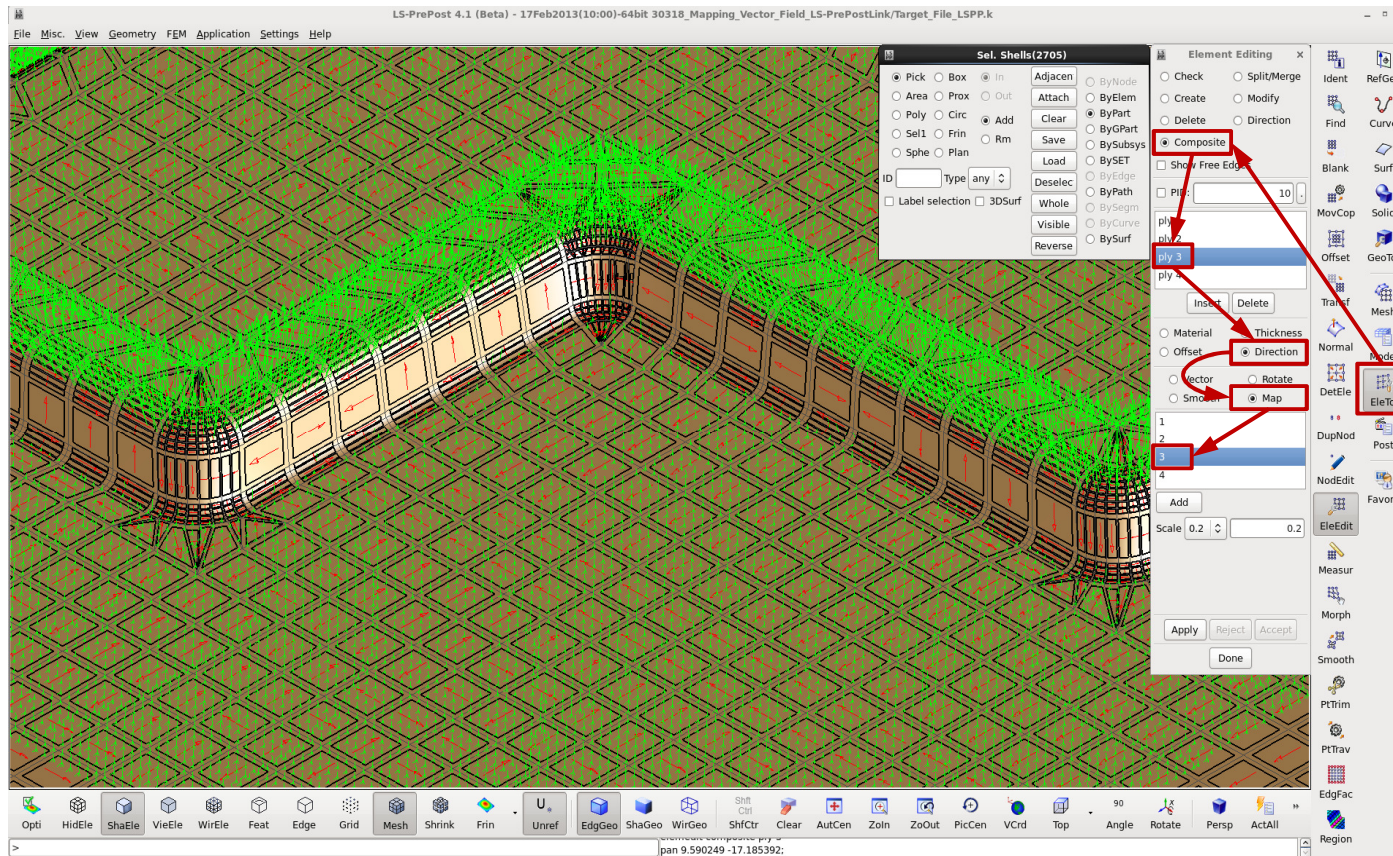
Origin

0.291E+03	0.316E+03	0.506E+02
0.287E+03	0.316E+03	0.506E+02
0.283E+03	0.316E+03	0.506E+02
0.279E+03	0.316E+03	0.506E+02
0.275E+03	0.316E+03	0.506E+02
0.271E+03	0.316E+03	0.506E+02
0.267E+03	0.316E+03	0.507E+02
0.263E+03	0.316E+03	0.507E+02
0.259E+03	0.316E+03	0.506E+02
0.256E+03	0.316E+03	0.506E+02
0.252E+03	0.316E+03	0.506E+02
0.248E+03	0.316E+03	0.506E+02
0.244E+03	0.316E+03	0.506E+02

Direction

-0.110E-01	-0.200E+01	0.000E+00
-0.106E-01	-0.200E+01	0.000E+00
-0.970E-02	-0.200E+01	0.800E-05
-0.858E-02	-0.200E+01	0.000E+00
-0.714E-02	-0.200E+01	-0.400E-05
-0.546E-02	-0.200E+01	0.000E+00
-0.369E-02	-0.200E+01	0.000E+00
-0.180E-02	-0.200E+01	0.000E+00
-0.600E-04	-0.200E+01	0.530E-04
0.160E-02	-0.200E+01	0.221E-03
0.310E-02	-0.200E+01	0.511E-03
0.454E-02	-0.200E+01	0.881E-03
0.580E-02	-0.200E+01	0.129E-02

Mapping with LS-PrePost



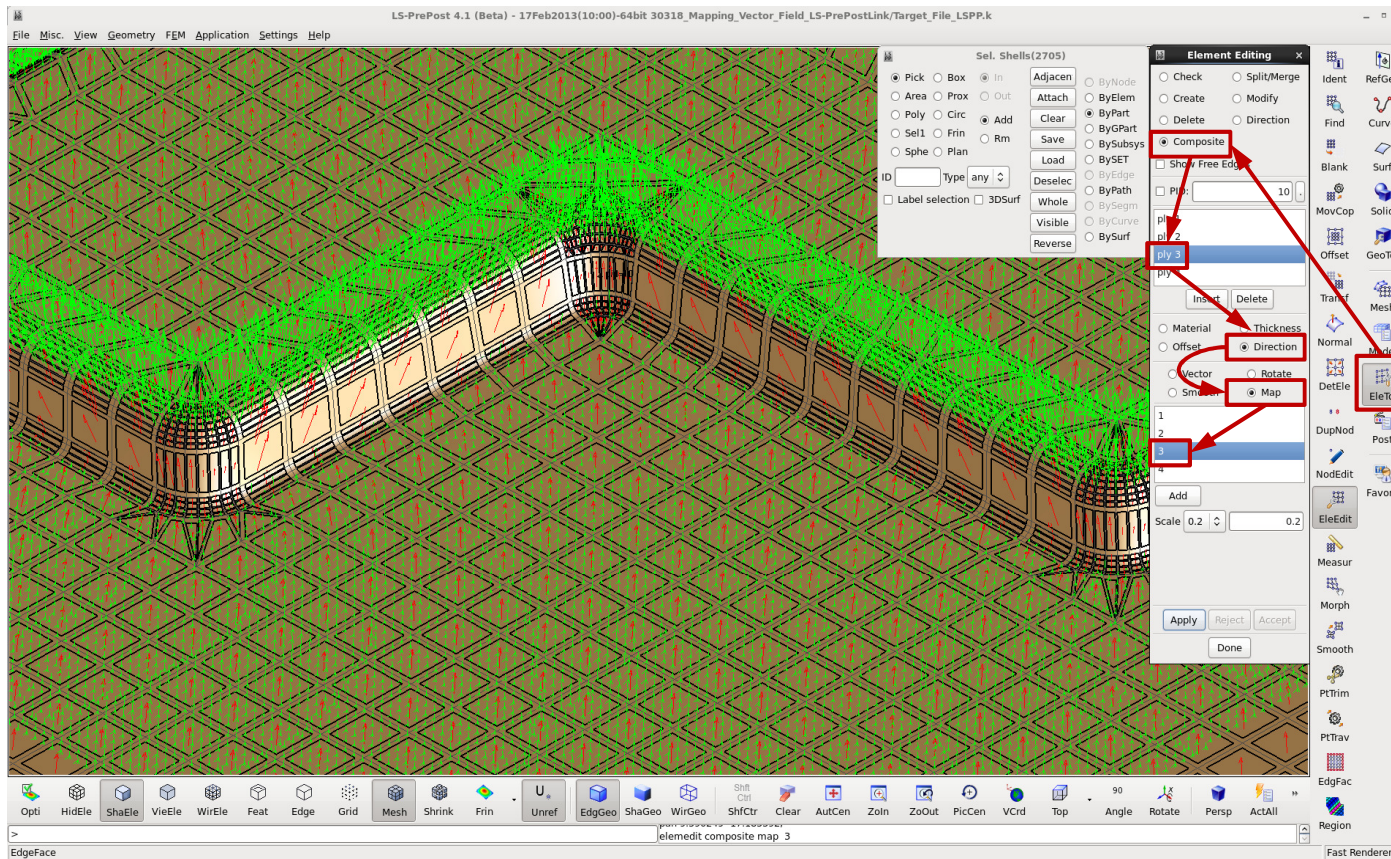
Load vector field into LS-PrePost using the Composite-Modeling feature:

Eletol -> Composite -> Map

For each ply, fiber directions can be mapped

Output will be *ELEMENT_-SHELL_COMPOSITE for LS-DYNA input deck

Mapping with LS-PrePost



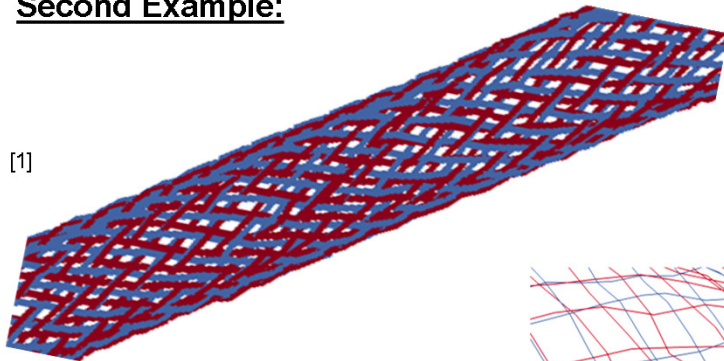
Load vector field into LS-PrePost using the Composite-Modeling feature:

Eletol -> Composite -> Map

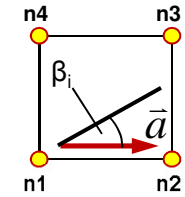
For each ply, fiber directions can be mapped

Output will be *ELEMENT_-SHELL_COMPOSITE for LS-DYNA input deck

Second Example:

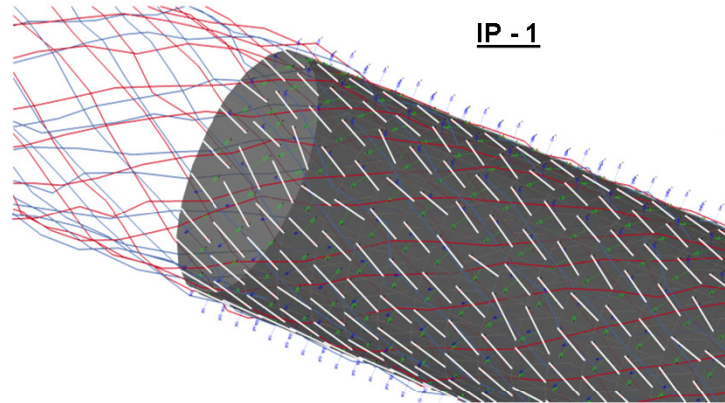


AOPT = 0

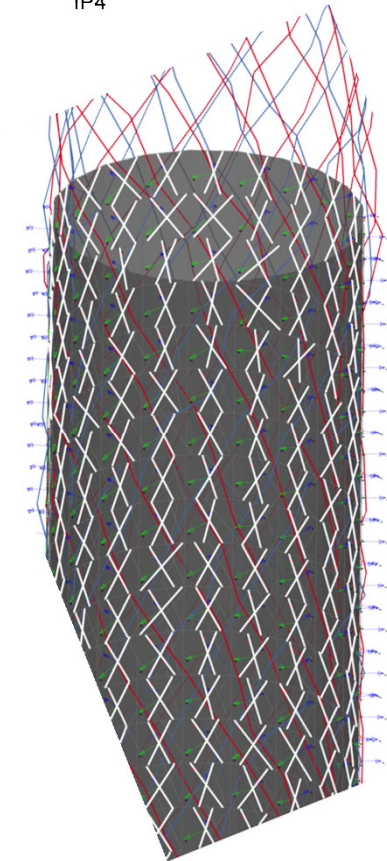
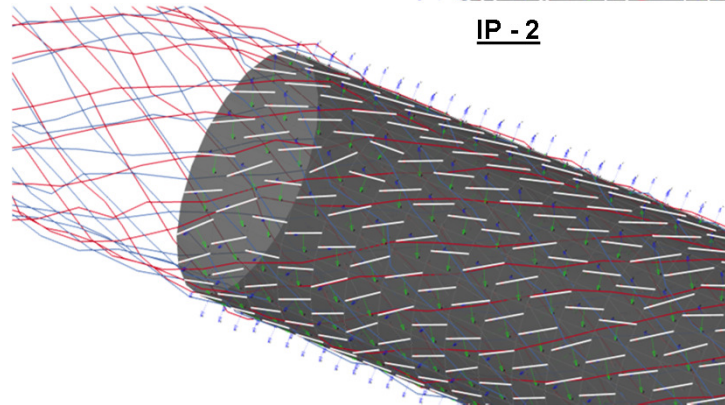


- IP1
- IP2
- IP3
- IP4

IP - 1



IP - 2

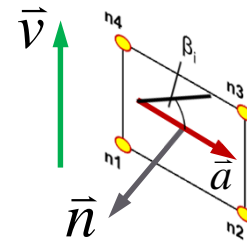
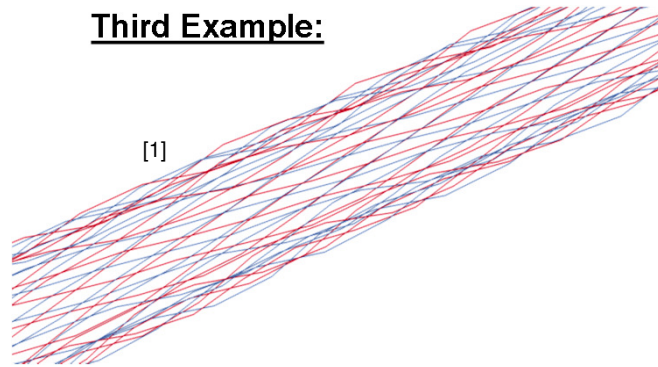


Vector \vec{a} is given directly by the element orientation
 *ELEMENT_SHELL_-COMPOSITE
 or *PART_COMPOSITE
 Identification of β_i is a little bit more complicated than writing fiber orientation directly into the material card

Only one material card per part!
 Relevant for crash simulations...

[1] H. Finckh, ITV Denckendorf

Third Example:

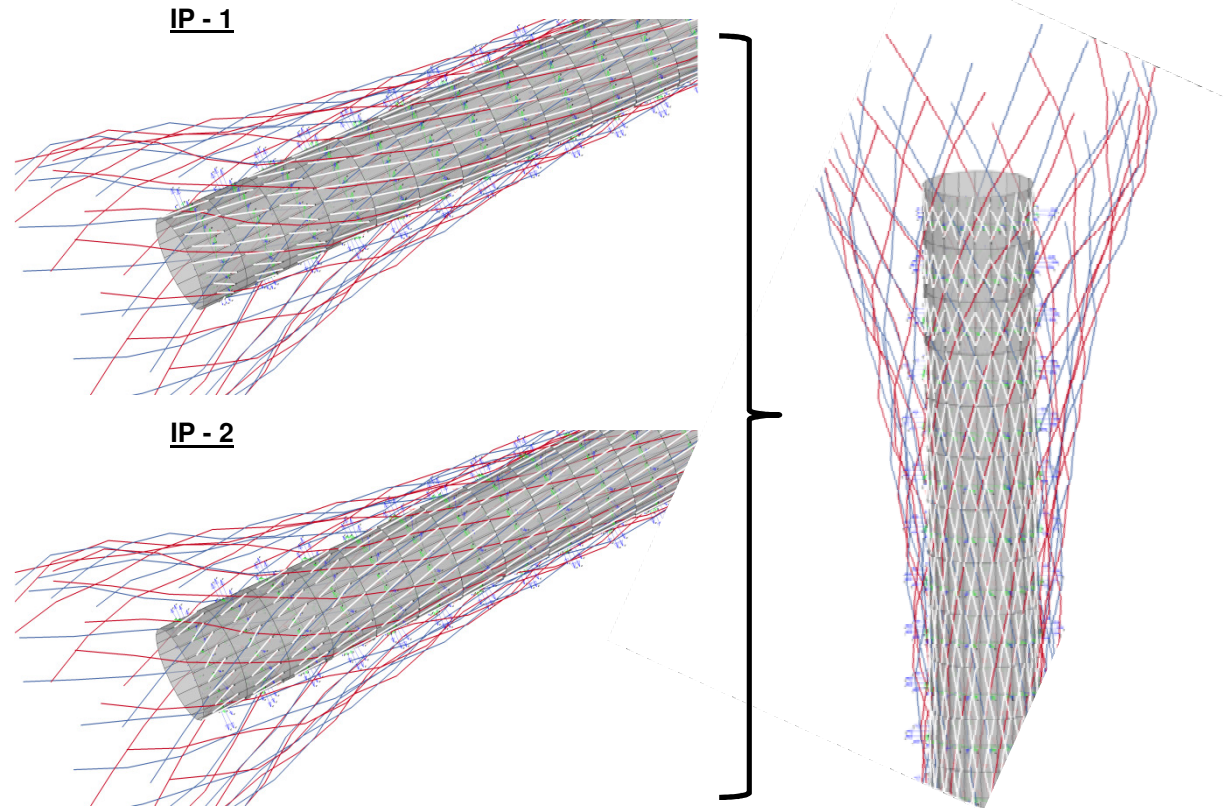


AOPT = 3

- IP1
- IP2
- IP3
- IP4

Vector \vec{a} is given directly by the element orientation
 *ELEMENT_SHELL_-COMPOSITE
 or *PART_COMPOSITE
 Identification of β_i is a little bit more complicated than writing fiber orientation directly into the material card

Only one material card per part!
 Relevant for crash simulations...



[1] H. Finckh, ITV Denckendorf

Mapping from experimental data

so far: transfer of fiber orientation-tensors onto a LS-DYNA mesh

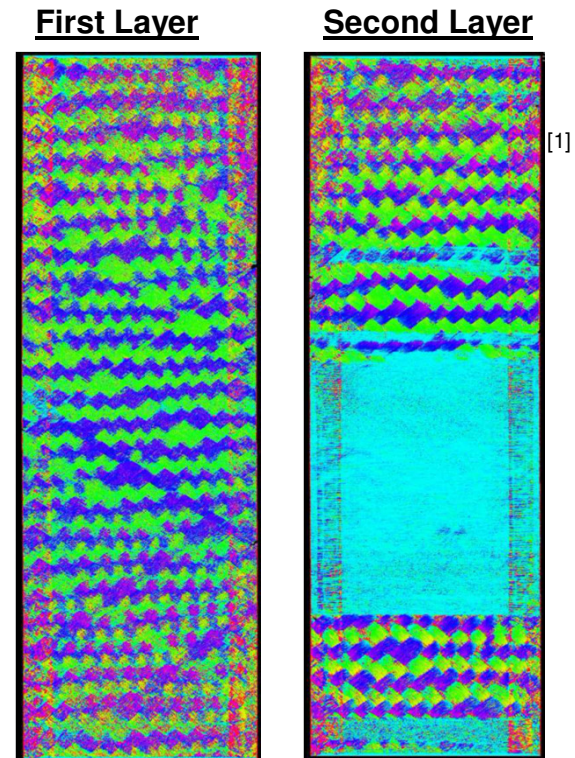
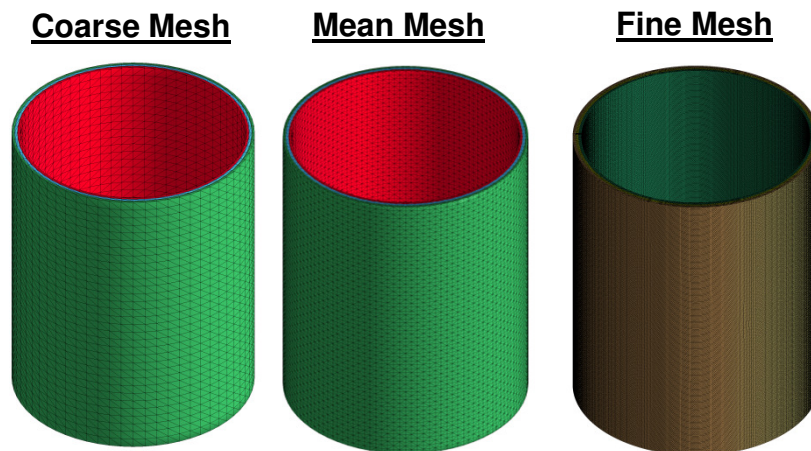
Input: patran-format mesh, output: csv-file containing orientation tensor & fiber-volume ration per element, transfer as *INITIAL_STRESS_SOLID data for visualization purposes only

Three different mesh sizes considered so far: Coarse, Mean, Fine

Example-part: 3-layered braided tube with 0-deg reinforcement fibers

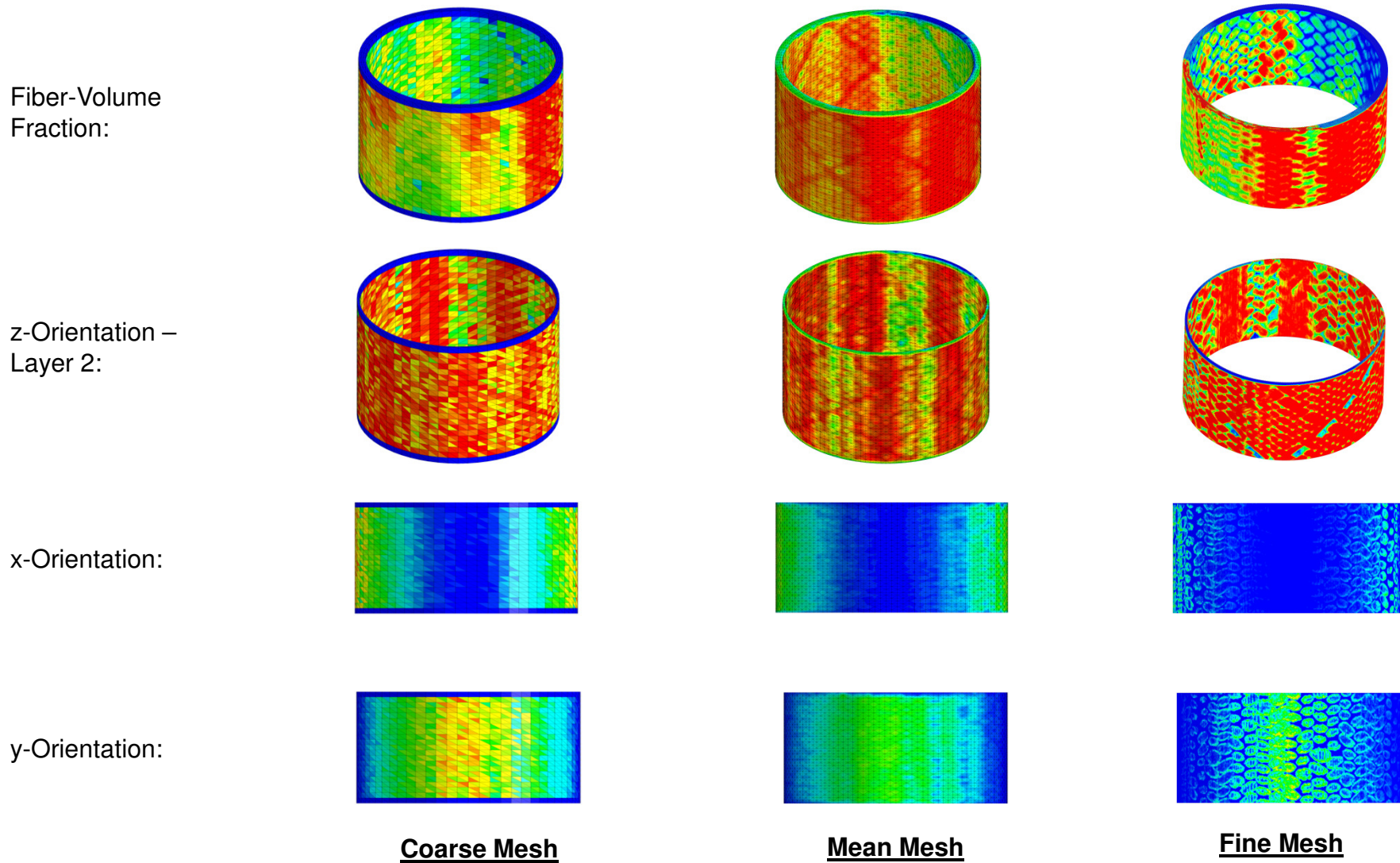
Further enhancements supposed to work with Hexa-elements, maybe with (T)shell elements

	<u>Num. of Elements</u>	<u>Layers</u>	<u>Element-Size</u>
Coarse Mesh	38420	1	0,3 - 1,25 mm
Mean Mesh	150039	2	0,15 - 0,62 mm
Fine Mesh	15078400	4	0,075 - 0,1 mm



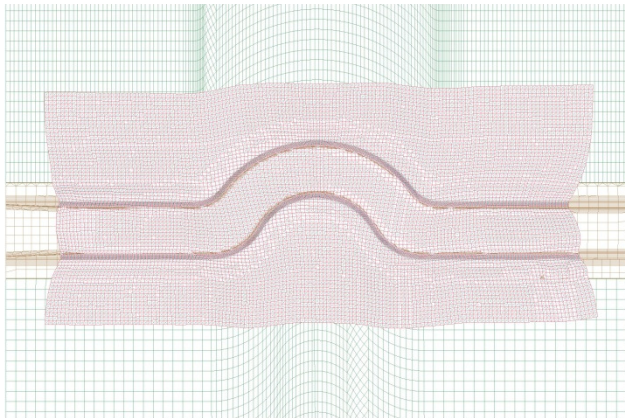
[1] H. Finckh, ITV Denkendorf

Mapping from experimental data

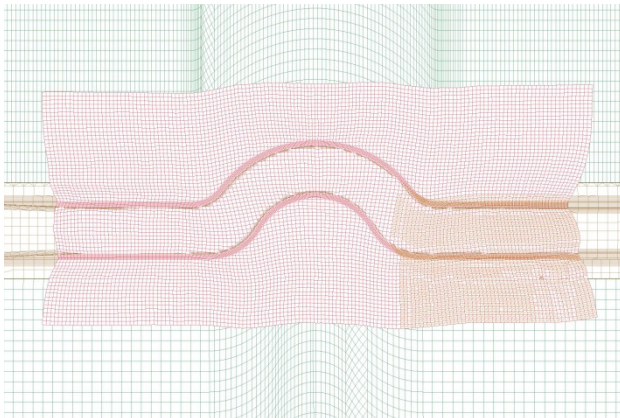


Mapping from LSDA output

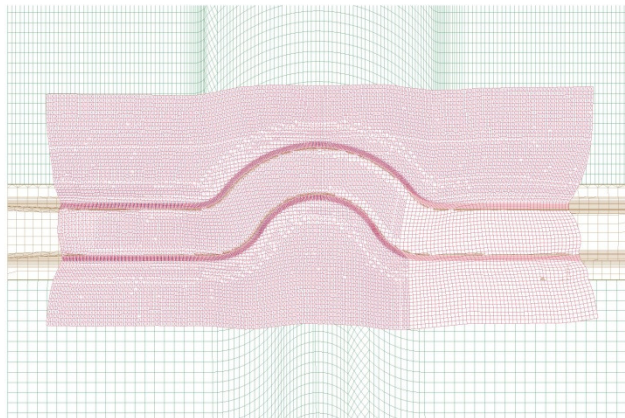
PlyID #1



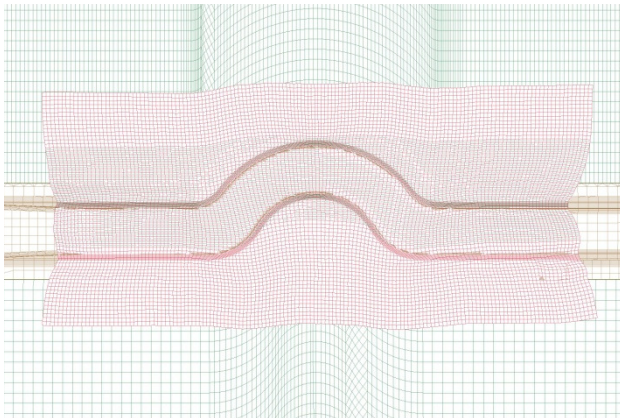
PlyID #3



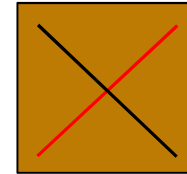
PlyID #5



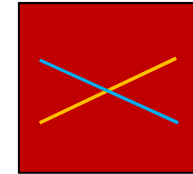
PlyID #7



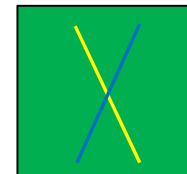
PlyID #1



PlyID #3



PlyID #5

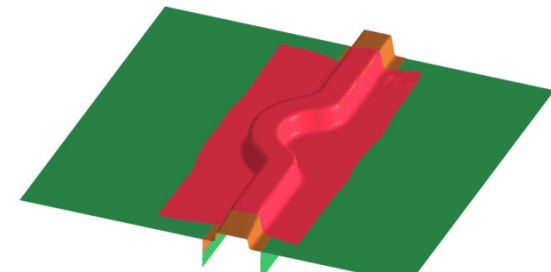


PlyID #7



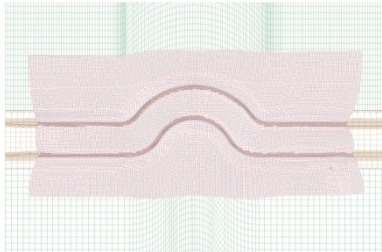
Schichtaufbau:

- PlyID #5
- PlyID #3
- PlyID #1
- PlyID #7

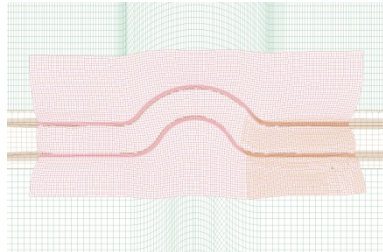




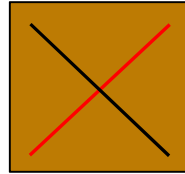
PlyID #1



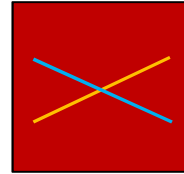
PlyID #3



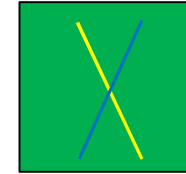
PlyID #1



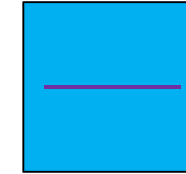
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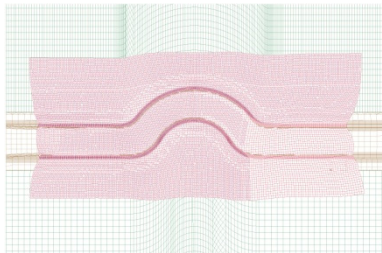
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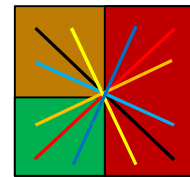
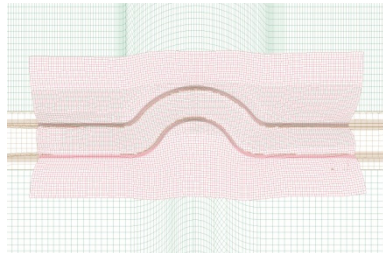
PlyID #7



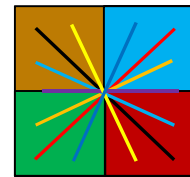
PlyID #5



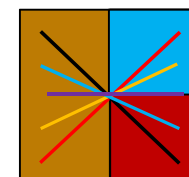
PlyID #7



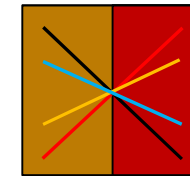
6 Fibers,
PlyID1, PlyID3
& PlyID5



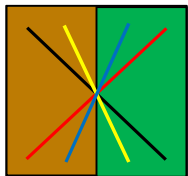
7 Fibers,
PlyID1, PlyID3,
PlyID5 & PlyID7



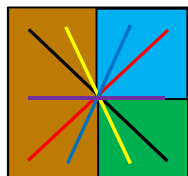
5 Fibers,
PlyID1, PlyID3
& PlyID7



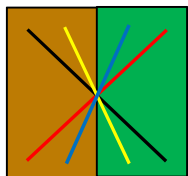
4 Fibers,
PlyID1 & PlyID3



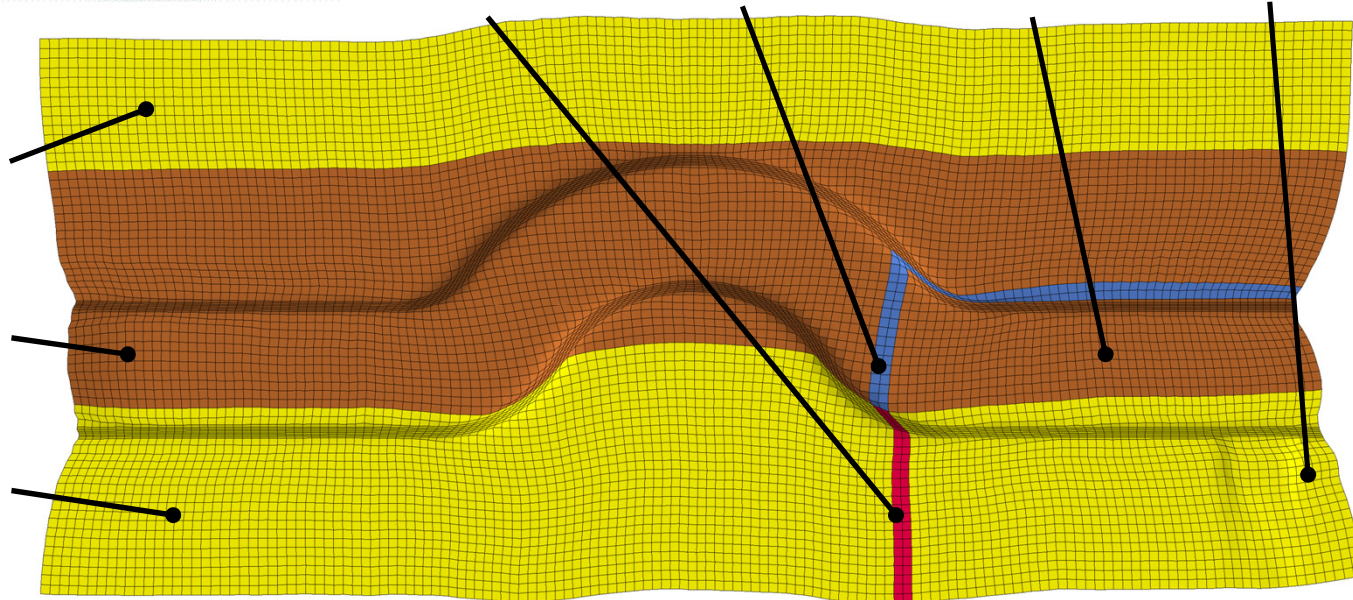
4 Fibers,
PlyID1 & PlyID5

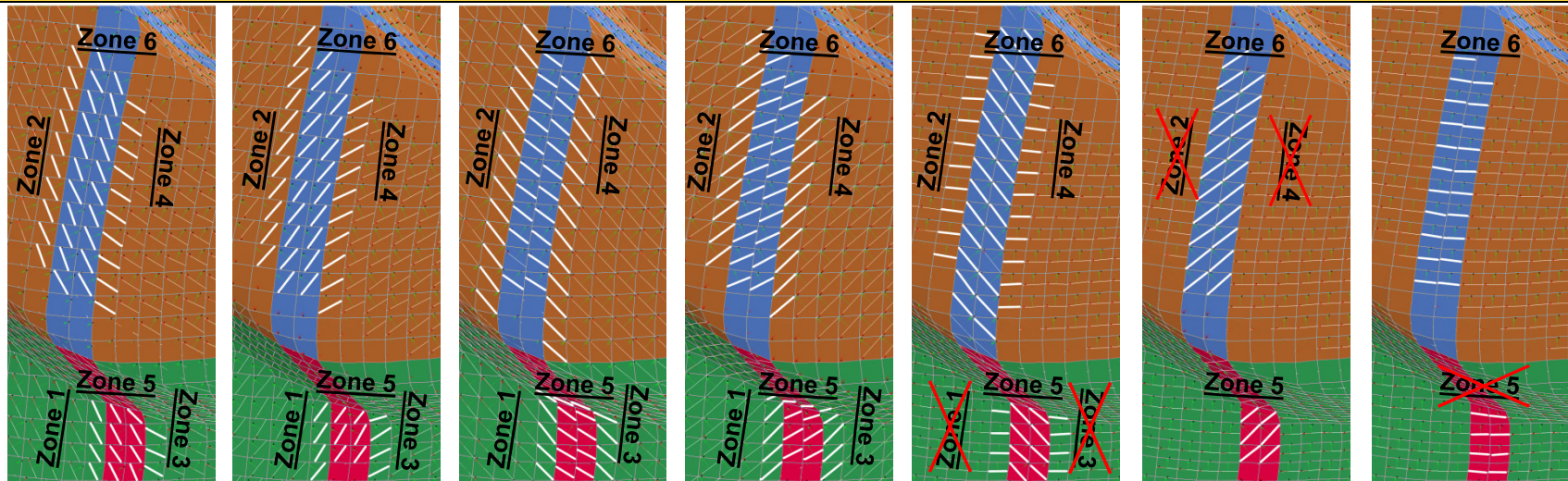


5 Fibers,
PlyID1, PlyID5
& PlyID7



4 Fibers,
PlyID1 & PlyID5





<u>Zone 1</u> PlyID #5 PlyID #1	<u>Zone 2</u> PlyID #5 PlyID #1 PlyID #7	<u>Zone 1</u> PlyID #5 PlyID #1	<u>Zone 2</u> PlyID #5 PlyID #1 PlyID #7	<u>Zone 1</u> PlyID #5 PlyID #1 PlyID #7	<u>Zone 2</u> PlyID #5 PlyID #1 PlyID #7	<u>Zone 1</u> PlyID #5 PlyID #1 PlyID #7	<u>Zone 2</u> PlyID #5 PlyID #1 PlyID #7	<u>Zone 1</u> PlyID #5 PlyID #1	<u>Zone 3</u> PlyID #3 PlyID #1	<u>Zone 2</u> PlyID #5 PlyID #1 PlyID #7	<u>Zone 4</u> PlyID #3 PlyID #1 PlyID #7	<u>Zone 5</u> PlyID #5 PlyID #3 PlyID #1 PlyID #7	<u>Zone 6</u> PlyID #5 PlyID #3 PlyID #1 PlyID #7
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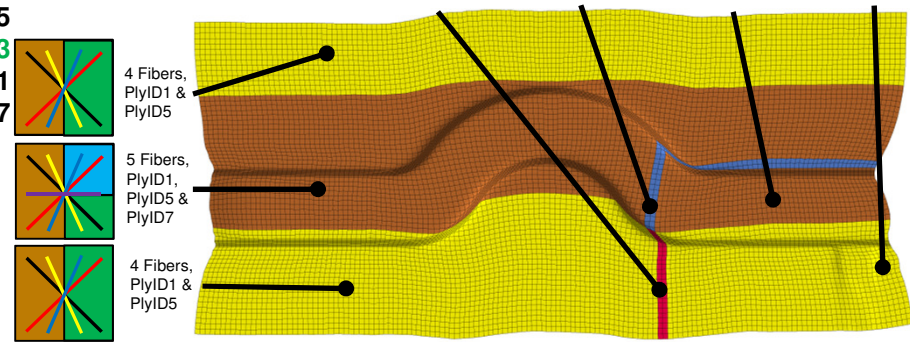
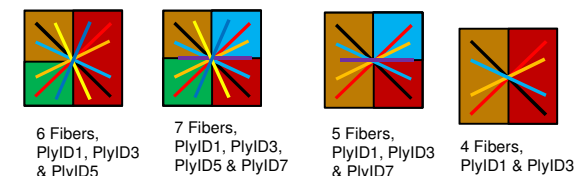
<u>Zone 3</u> PlyID #3 PlyID #1	<u>Zone 4</u> PlyID #3 PlyID #1 PlyID #7	<u>Zone 3</u> PlyID #3 PlyID #1	<u>Zone 4</u> PlyID #3 PlyID #1 PlyID #7	<u>Zone 3</u> PlyID #3 PlyID #1	<u>Zone 4</u> PlyID #3 PlyID #1 PlyID #7	<u>Zone 3</u> PlyID #3 PlyID #1	<u>Zone 4</u> PlyID #3 PlyID #1 PlyID #7	<u>Zone 5</u> PlyID #5 PlyID #3 PlyID #1	<u>Zone 6</u> PlyID #5 PlyID #3 PlyID #1 PlyID #7
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<u>Zone 5</u> PlyID #5 PlyID #3 PlyID #1	<u>Zone 6</u> PlyID #5 PlyID #3 PlyID #1 PlyID #7	<u>Zone 5</u> PlyID #5 PlyID #3 PlyID #1	<u>Zone 6</u> PlyID #5 PlyID #3 PlyID #1 PlyID #7	<u>Zone 5</u> PlyID #5 PlyID #3 PlyID #1	<u>Zone 6</u> PlyID #5 PlyID #3 PlyID #1 PlyID #7	<u>Zone 5</u> PlyID #5 PlyID #3 PlyID #1	<u>Zone 6</u> PlyID #5 PlyID #3 PlyID #1 PlyID #7
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IP #1

IP #2

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Vielen Dank!