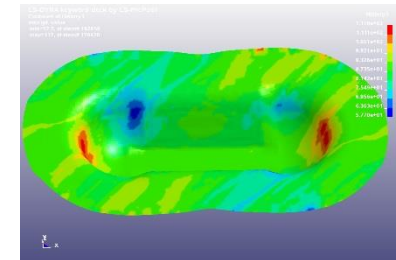
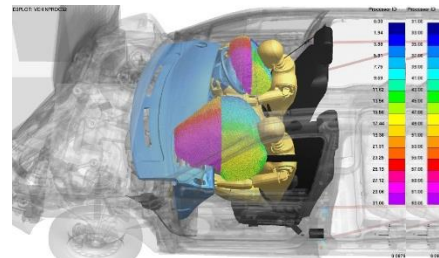
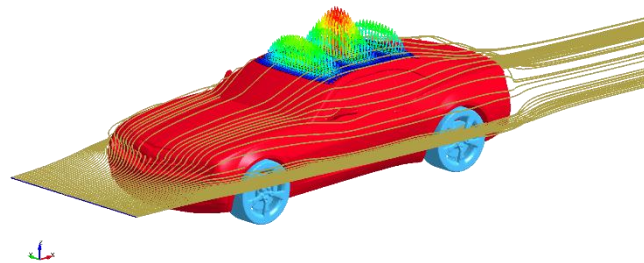


Recent Development – Part I



Presented by Jason Wang



15. Deutsches LS-DYNA Forum
15.-17. Oktober 2018, Bamberg

Outline – Part I

Introduction

Multi-Physics, Multi-formulation, Multi-scale, Multi-stage

- **Electromagnetics**
- **ICFD**
- **PARTICLE Methods**

Scalable code

- **MPP**
- **Parallel efficiency**
- **HYBRID**

Multi-Physics Solver, Pre-and-Post Processor, Optimization, and Library of Validated Dummies and Barriers

★

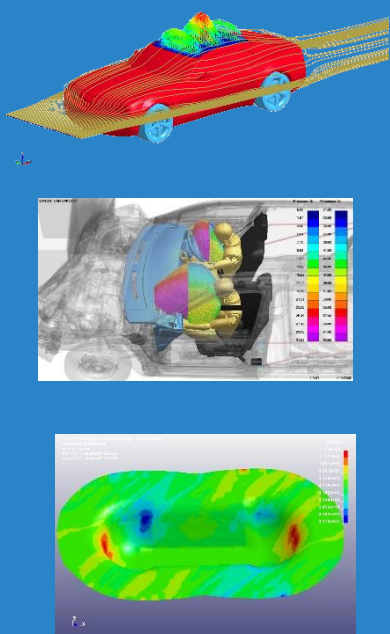
- ICFD Solution
- Analysis
 - Turbulent
- MAT Materials
 - Material1
- Model
 - Parts

LS-PrePost

★

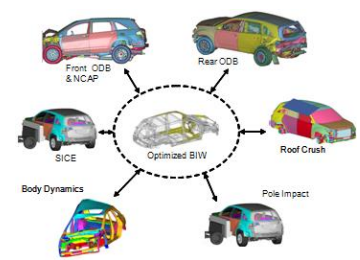


Dummies & Barriers

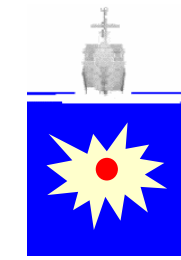


LS-DYNA®

★



LS-OPT/LS-TaSC



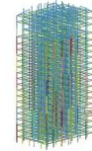
USA

Development costs are spread across many industries



Automotive

Crash and safety
NVH & Durability
FSI



Structural

Earthquake safety
Concrete and composite structures
Homeland security



Aerospace

Bird strike
Containment
Crash



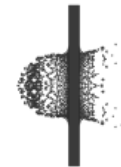
Electronics

Drop analysis
Package analysis
Thermal



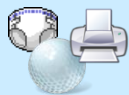
Manufacturing

Stamping
Forging
Welding



Defense

Weapons design
Blast and penetration
Underwater Shock Analysis



Consumer Products



Biosciences

LS-DYNA | Current Capabilities

Includes coupled Multi-Physics, Multi-Scale, and Multi-Stage in one Scalable Code



Explicit/Implicit



Heat Transfer



ALE & Mesh Free

EFG, SPH, Airbag Particle



User Interface

Elements, Materials, Loads



Acoustics, Frequency

Response, Modal Methods



Discrete Element Methods



Incompressible Fluids



CESE Compressible Fluids



Electromagnetics



Control Systems



Single Model for Multiple Disciplines – Manufacturing, Durability, NVH, Crash, and FSI

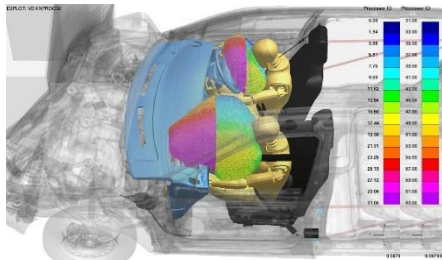
Multi-Physics and Multi-Stage
Structure + Fluid + EM + Heat Transfer
Implicit + Explicit

Multi-Scale

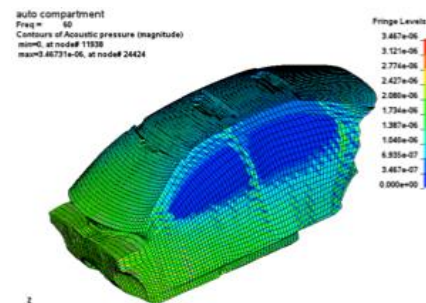
Failure predictions, i.e., spot welds

Multi-Formulations

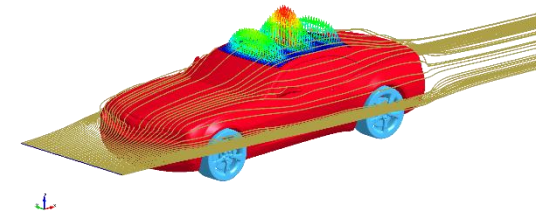
Linear + Non-Linear + Peridynamics + ...



Crash



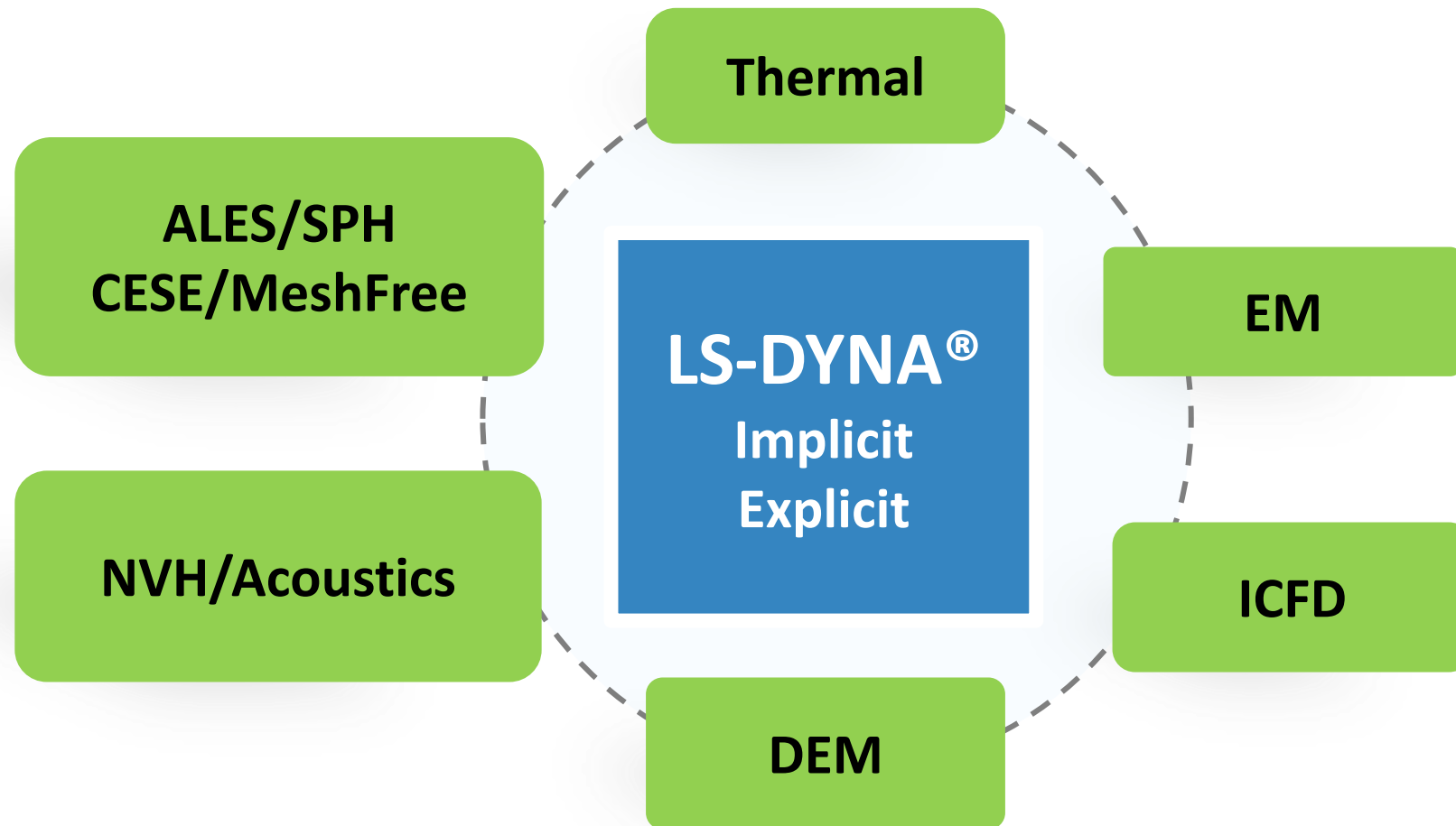
NVH/E-Coat/Paint Bake



Structure + Fluid

LS-DYNA | Strong Coupled Multi-Physics Solver

Computers capable of multi-physics simulations are becoming affordable.
Scalability is rapidly improving for solving multi-physics problem.



Multi-Physics, Multi-formulation, Multi-scale, Multi-stage

Pierre L'Eplattenier

Facundo Del Pin

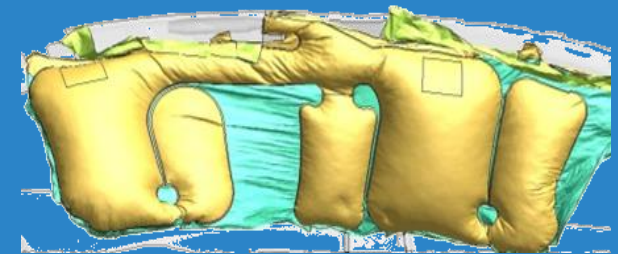
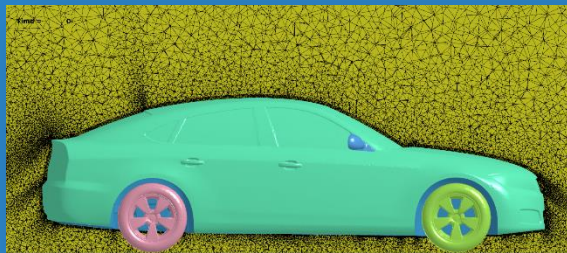
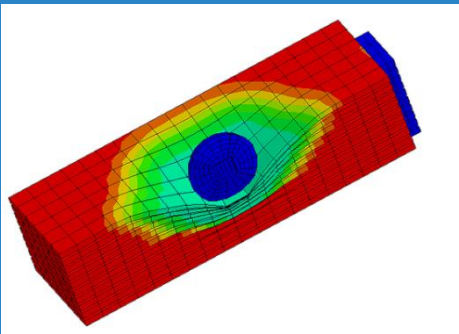
Edouard Yreux

Iñaki Çaldichoury

Jason Wang

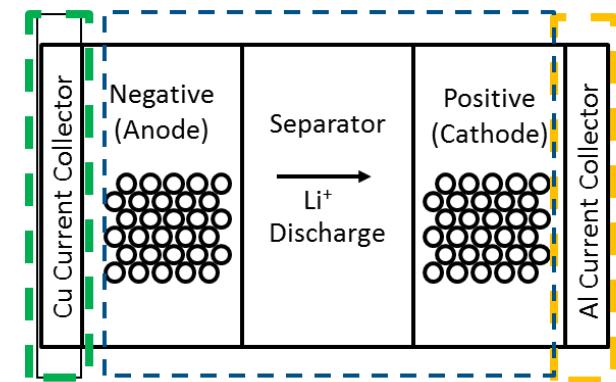
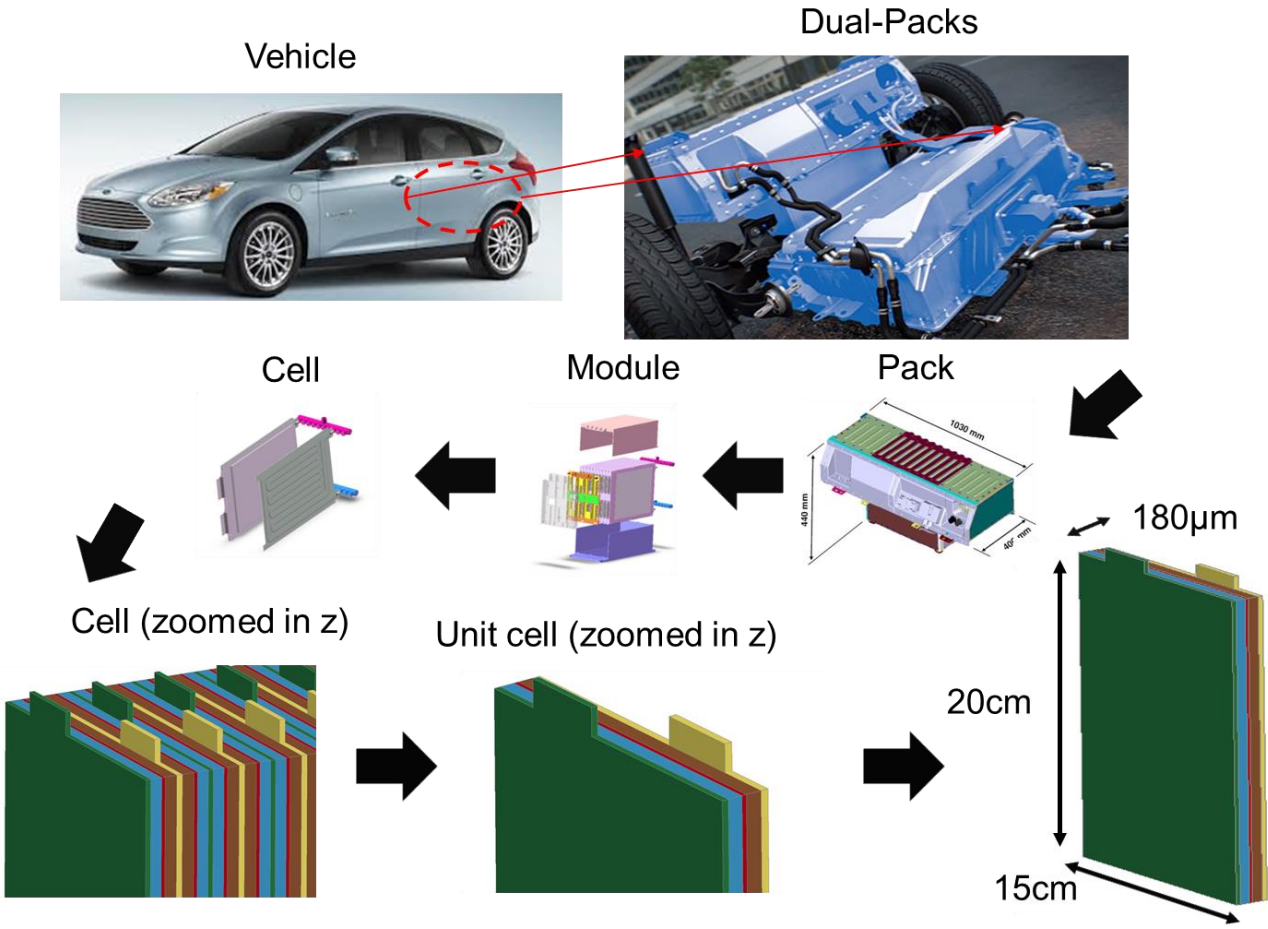
Rodrigo R. Paz

Chien-Jung Huang

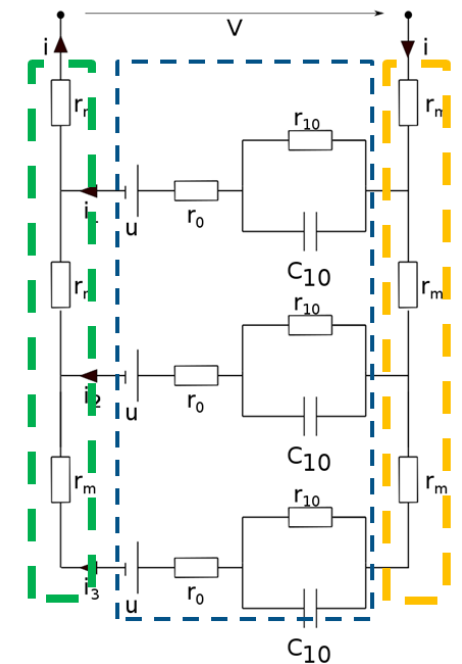


Battery – Distributed Randles circuit model

Electro-chemistry in the electrodes simulated by equivalent electrical circuits (Randles circuits)



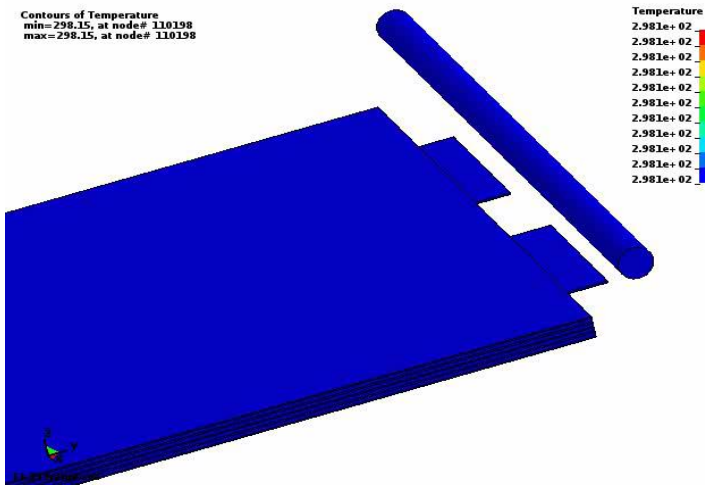
- Current collectors transport electrons to/from tabs; modeled by resistive elements
- Jelly roll (anode – separator – cathode) transports Li⁺ ions; modeled with Randle circuit



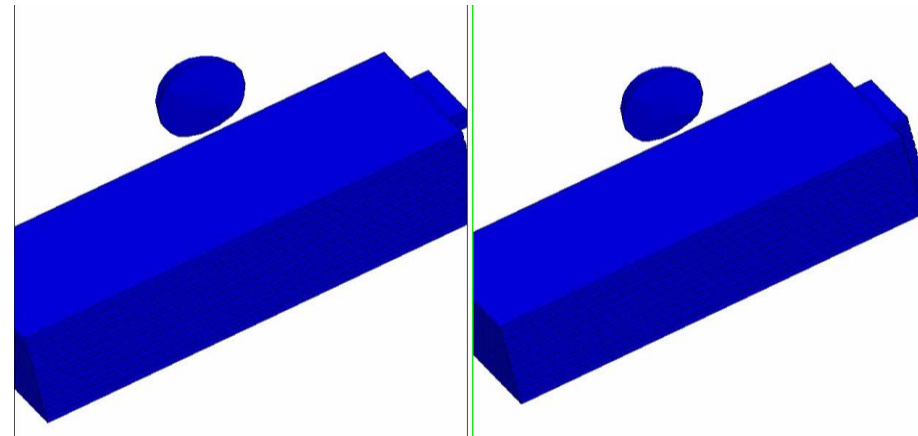
r_0 : Ohmic & kinetic
 r_{10} & c_{10} : Diffusion
 u : Equilibrium voltage (OCV)
 r_m : Current collectors

Battery abuse simulations

- Pouch cells, cylindrical cells available, soon prismatic cells
- Battery abuse simulations on cells, modules, packs
- Coupled with mechanical and thermal solvers
- Solid, shells and composite thick shells
- External and internal shorts
- Battery packaging application in LS-PrePost



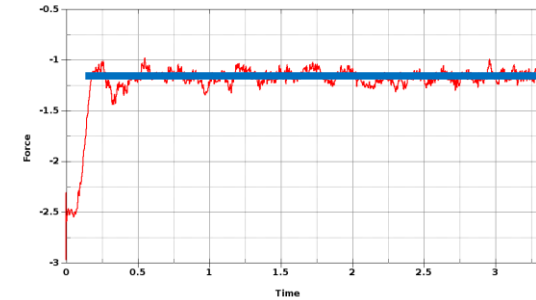
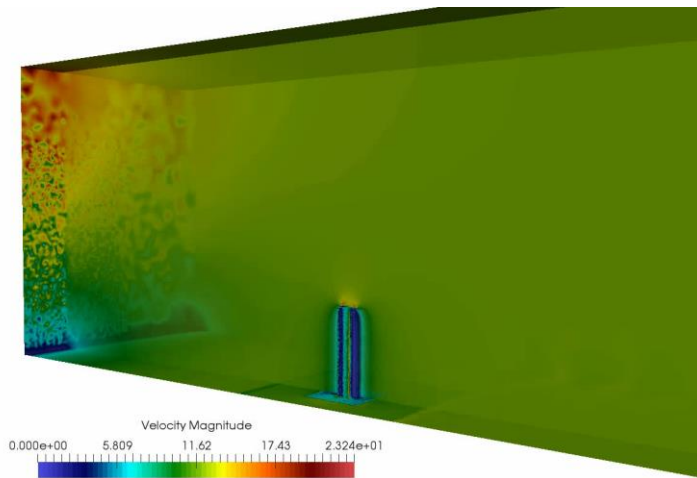
External short
5 cells module



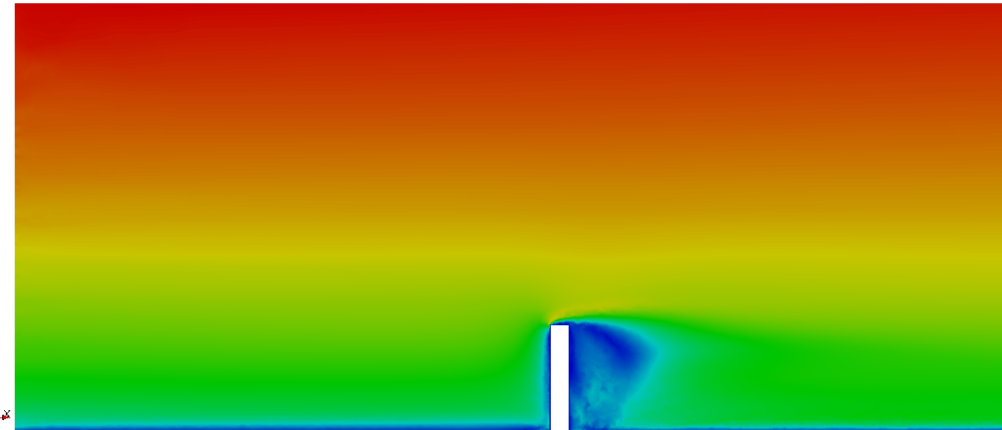
Internal short
10 cells module

Steady State for Conjugate Heat and FSI

The steady state solver or the potential flow solver allow for a fast linearization of Fluid Structure Interaction (FSI) and/or Conjugate Heat transfer (CH) problems

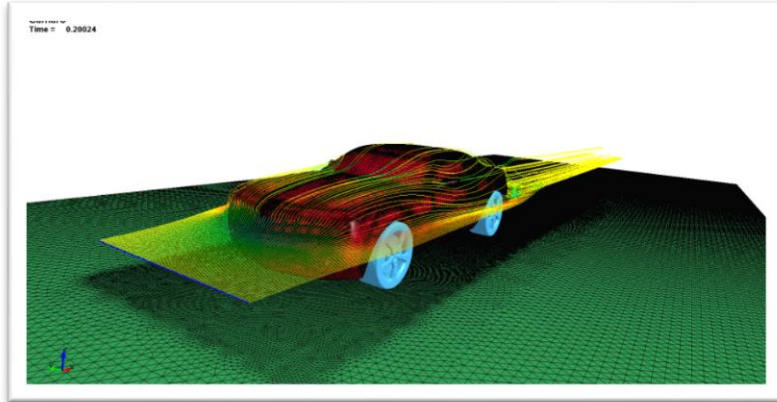


Steady state analysis allows engineers to study physical problems in a time average fashion.



These simulation provide valuable insight faster useful for prototyping.

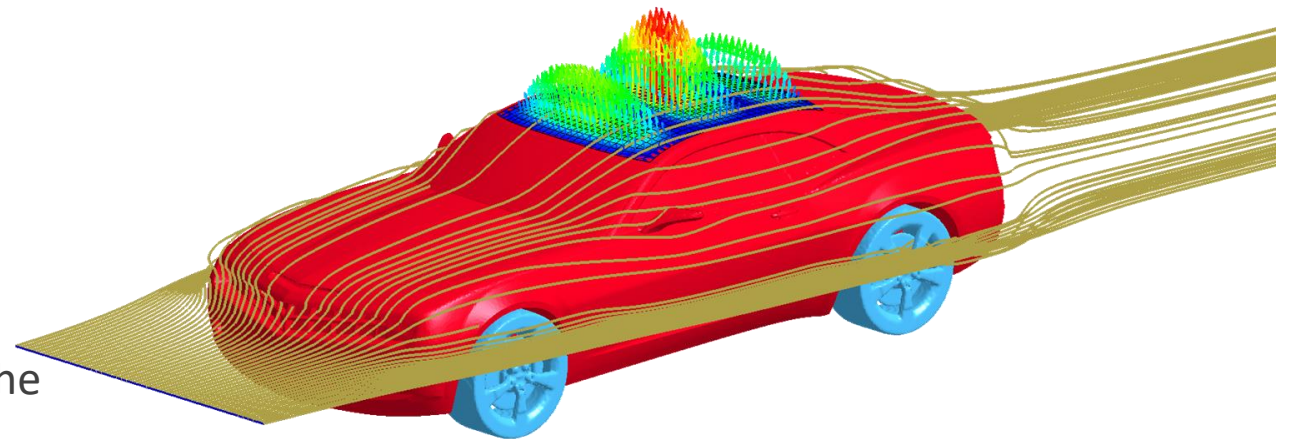
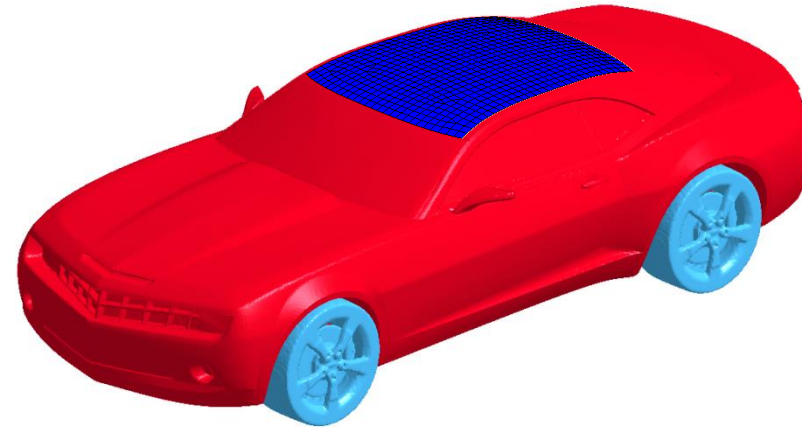
Steady State + Fluid Structure Interaction



- CFD analysis of full vehicle.
- Couple parts of the structure to analysis the response in a realistic environment.

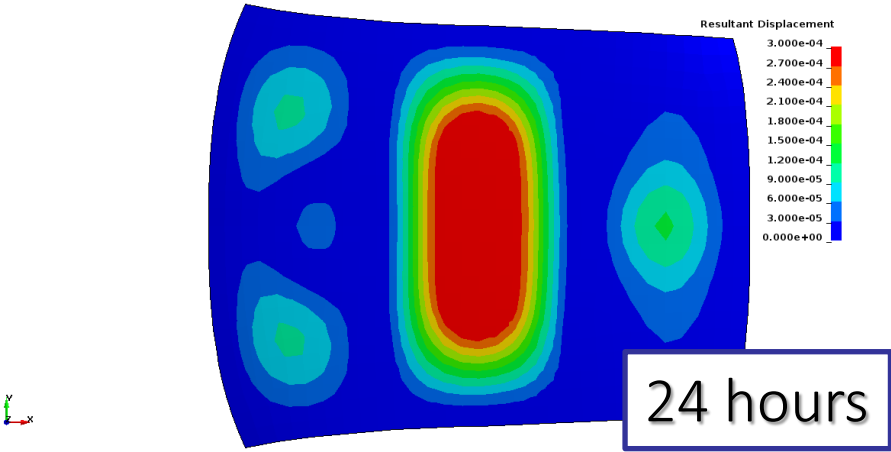
Three different option to solve the same problem:

- Solve **Full Navier –Stokes with FSI** non linear coupling.
- Solve **Potential flow with a non-linear step** at the end.
- Solve the **structural analysis alone using the output from Navier-Stokes** and the `*LOAD_SEGMENT` automatically generated input deck. Use `*ICFD_DATABASE_DRAG` write the files.

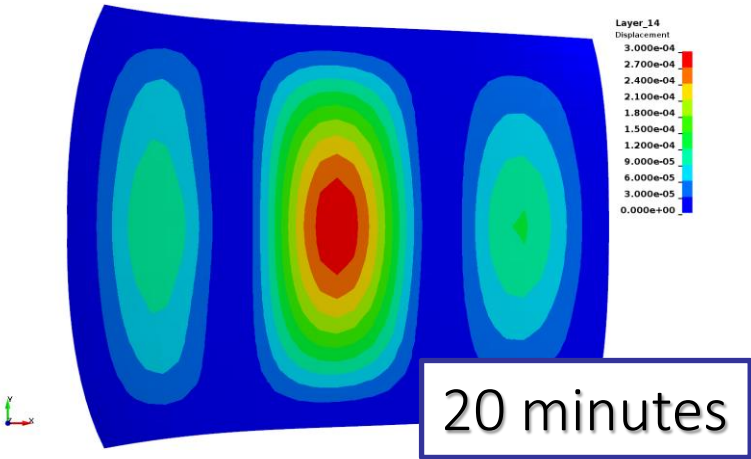


Steady State + Fluid Structure Interaction

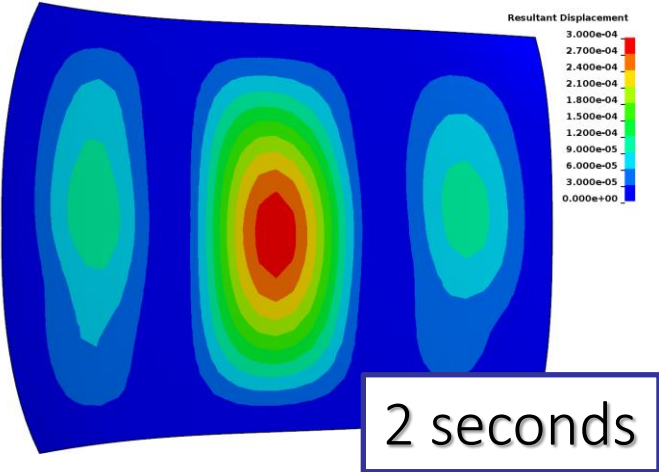
Navier Stokes



Potential Flow



Using *LOAD_SEGMENT from Navier-Stokes solution



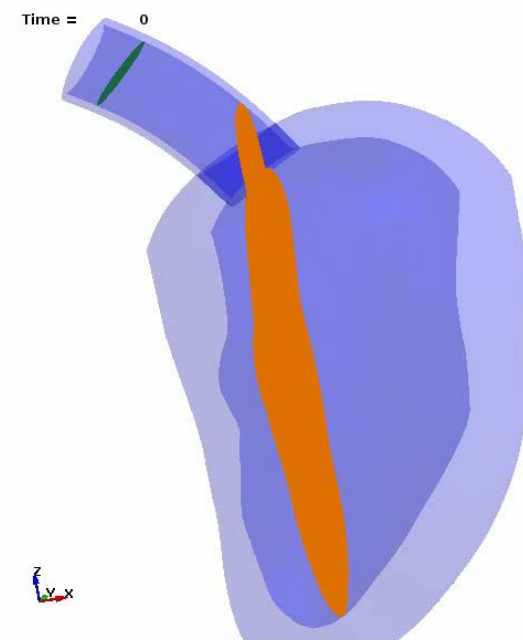
Multi-physics – Cardiac simulations (EM + ICFD + Structure)



Healthy ventricle

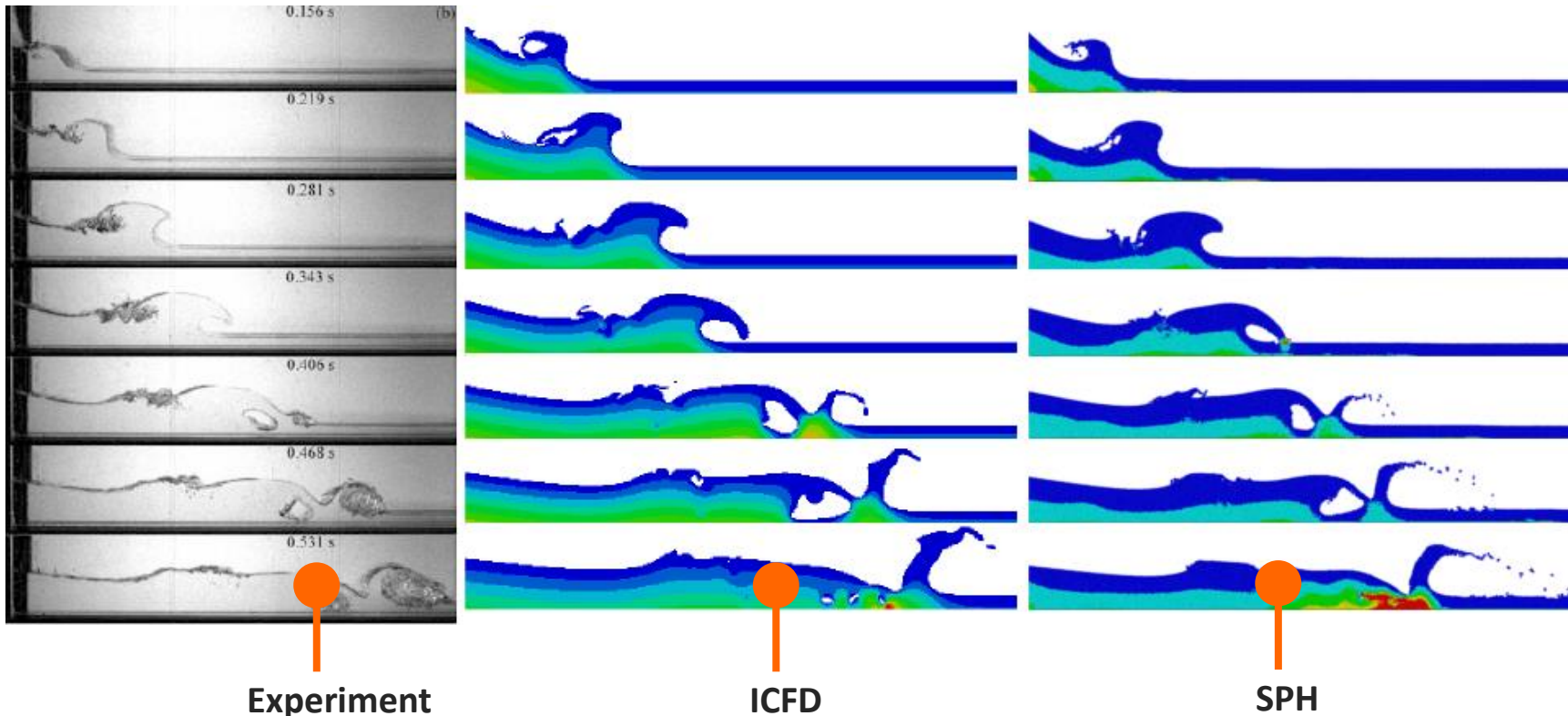


Fibrillation with spiral waves



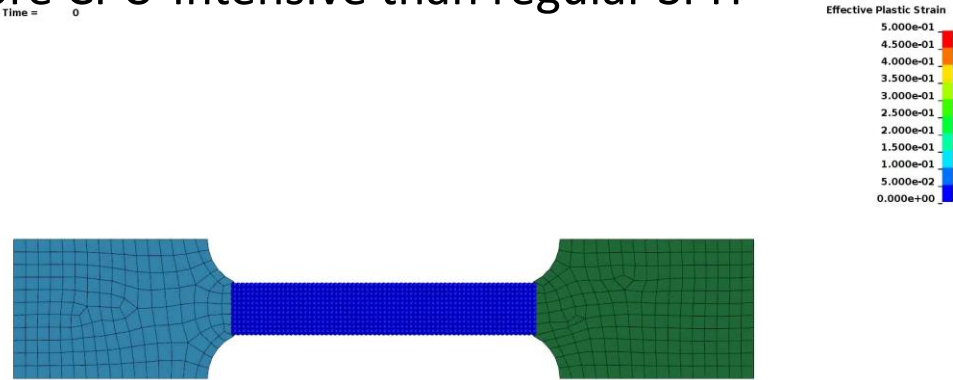
SPH | Fluid Simulation

- Density smoothing:
$$\tilde{\rho}_I = \frac{\sum_J \rho_J \phi_{IJ}}{\sum_J \phi_{IJ}} \quad \text{with} \quad \phi_{IJ} = W_{IJ} m_J / \rho_J$$
- Murnaghan Equation of State for weakly compressible modeling
$$p = k_0 \left[\left(\frac{\rho}{\rho_0} \right)^\gamma - 1 \right]$$
- Low artificial viscosity

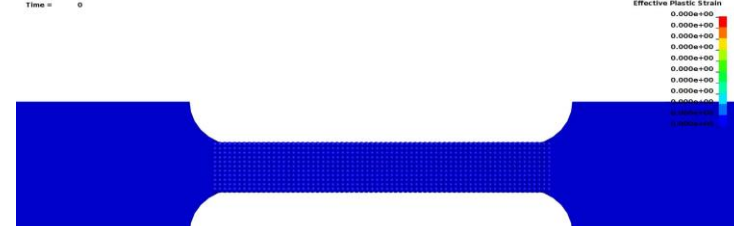
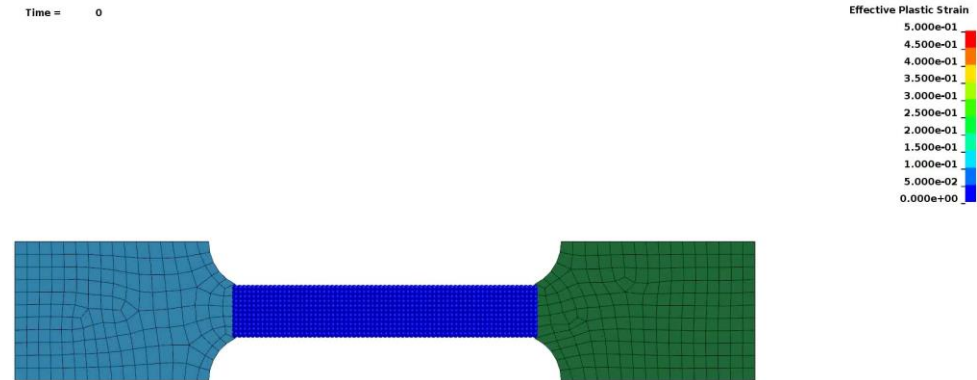


SPH | MLS-Based formulation

- Quasi-Linear Moving Least-Squares formulation for accuracy and consistency
- Stabilized nodal integration for better stability
- More CPU-Intensive than regular SPH



Traditional SPH



MLS-Based SPH

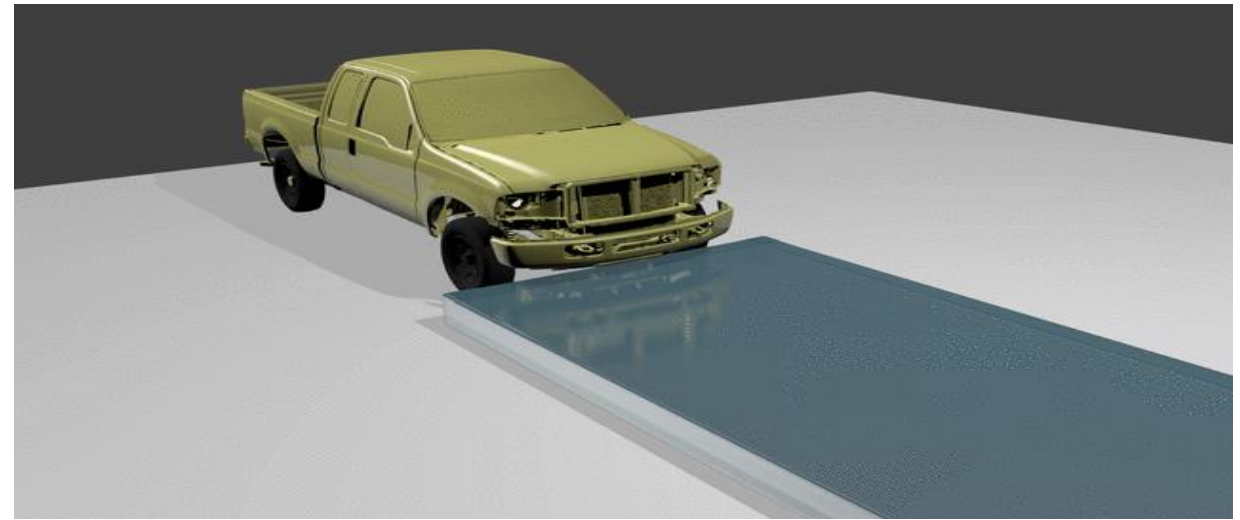
Higher accuracy – Better consistency – Alleviated tensile instability

SPH | Implicit formulation

- Implicit, incompressible SPH formulation allows larger timestep size
- Tailored for wading-type problems
- Example with 9.1 million particles:



Implicit SPH
Color-coded by velocity



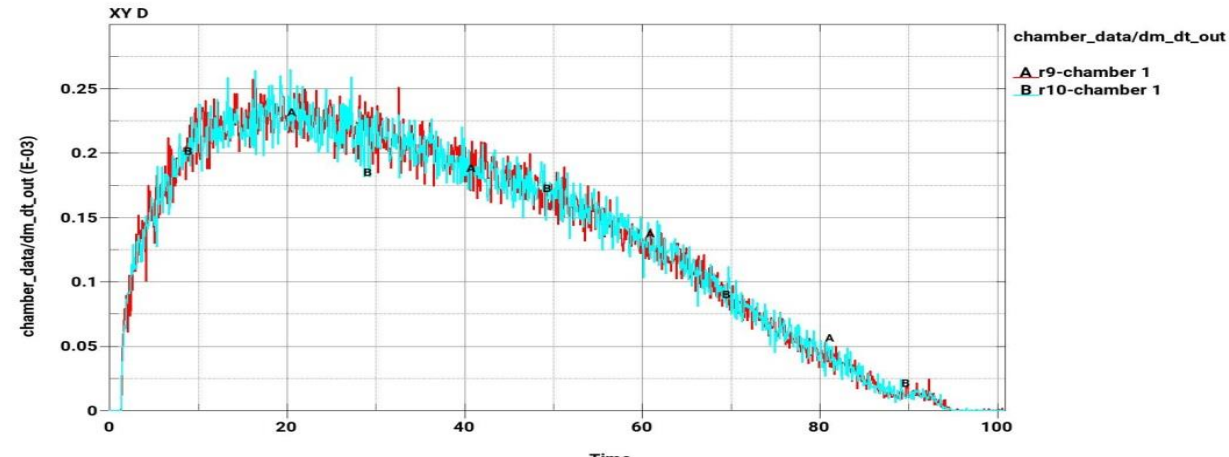
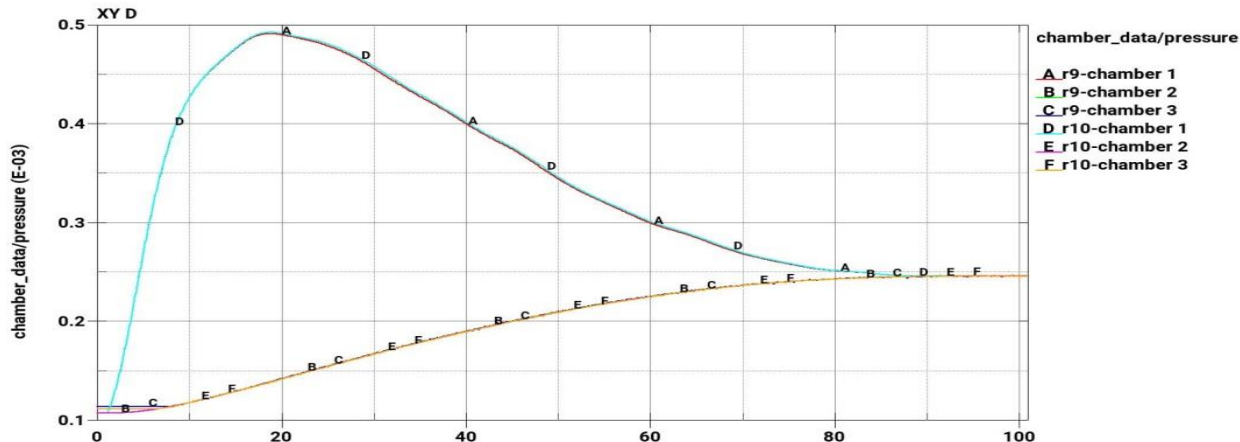
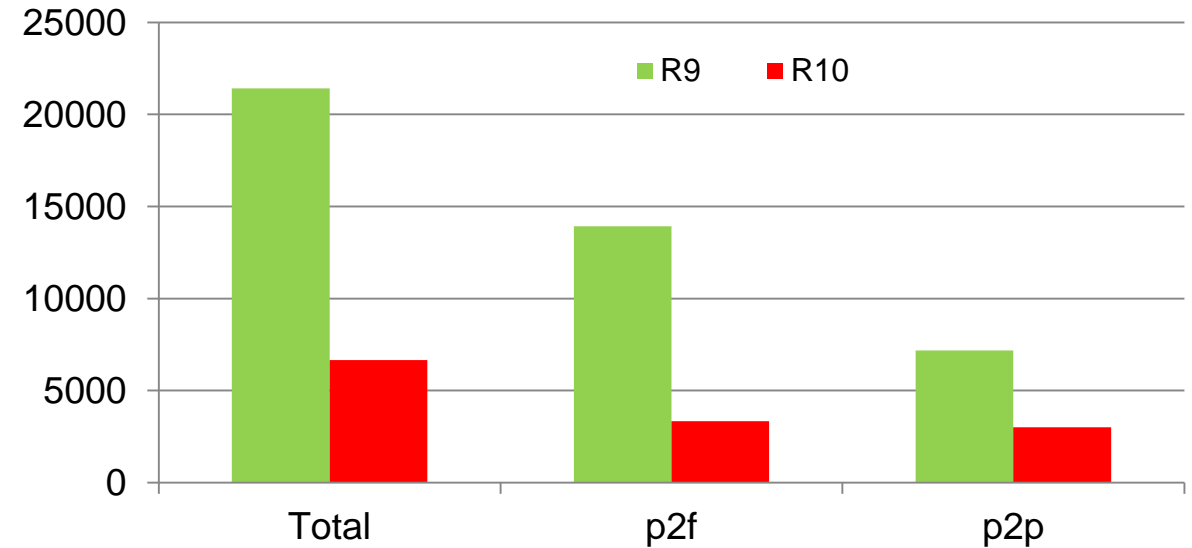
Blender rendering

CPM | New CPM for AIRBAG Simulations

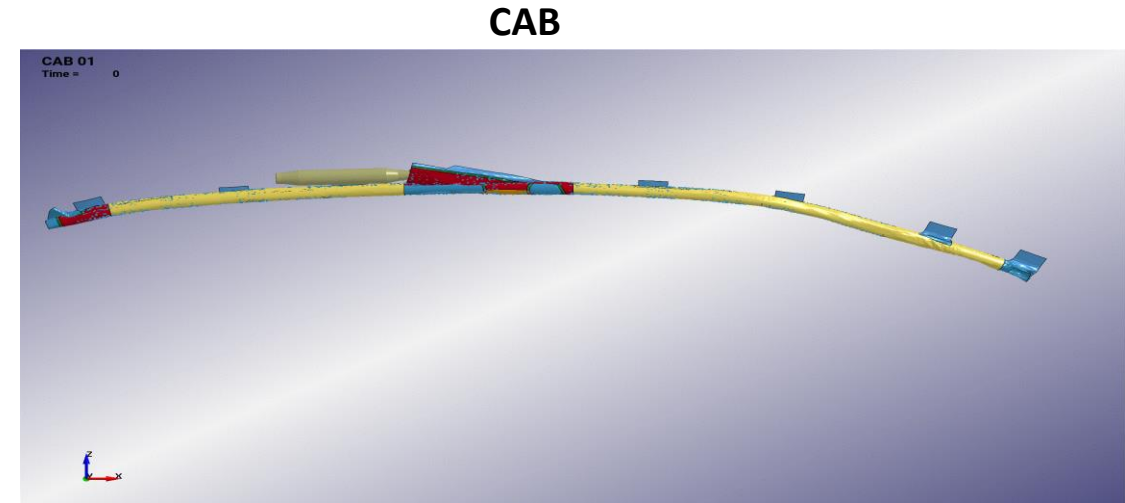
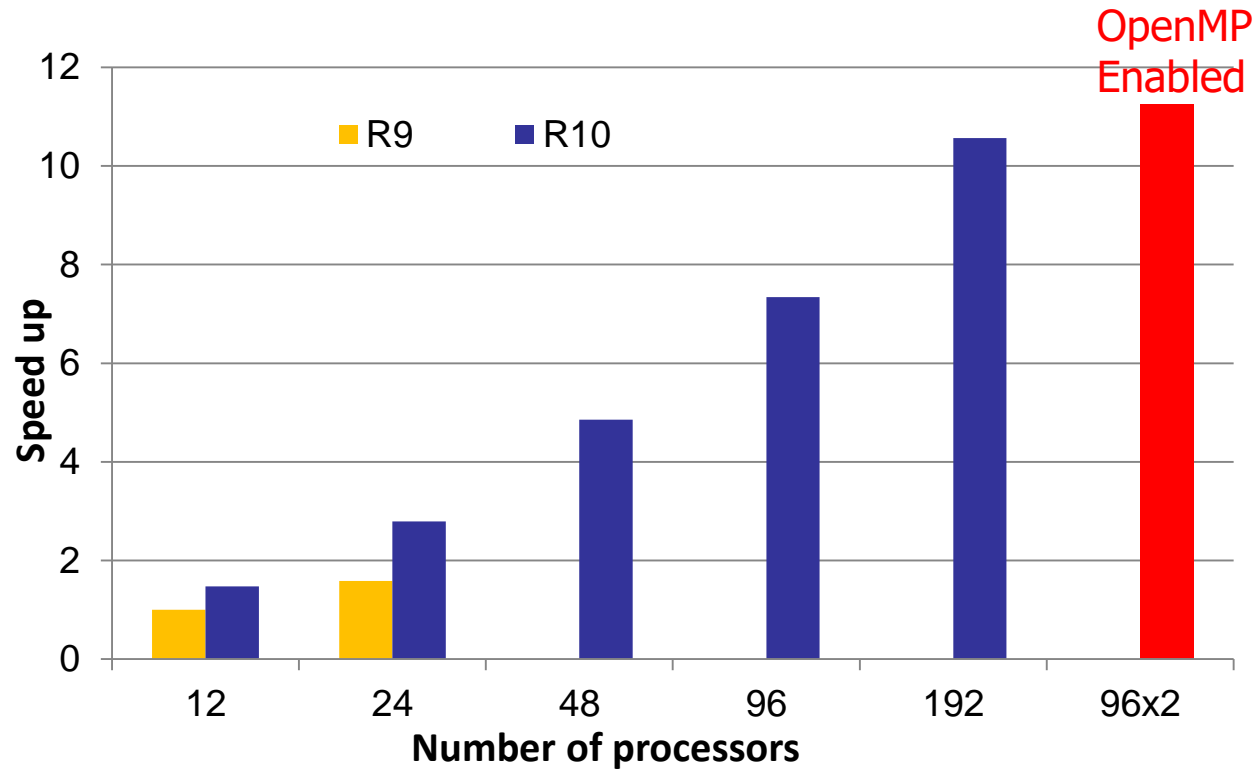
- Main cost for airbag simulation, (1)airbag self contact, (2)p2f and (3)p2p
- New and faster particle to fabric (p2f) contact algorithm
- Redistribute CPM particles among processors to achieve better scaling and efficient particle to particle (p2p) collisions

- *3x speedup for tank test*
- *Pressure history are consistent between releases*

Elapsed time (seconds)



CPM | CAB Performance Improvement



- OpenMP (HYBRID) enabled
- Reduced amount of data transferring between processors for better scaling
- It is more efficient for the full vehicle simulation which uses more than 200 processors
- Same input faster turn around time

Scalable Code

MPP and Hybrid Enhancements

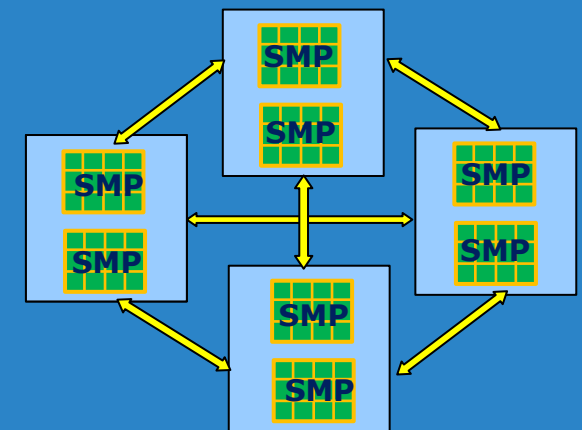
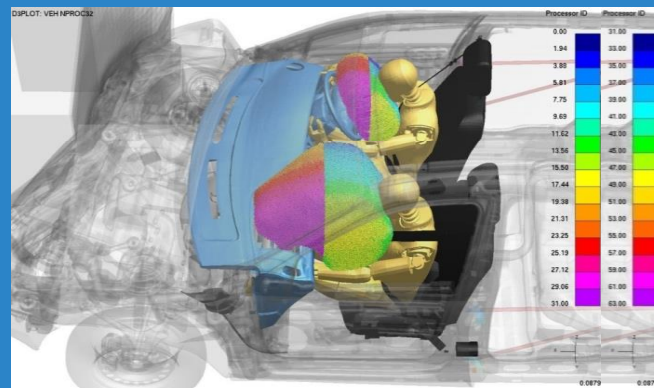
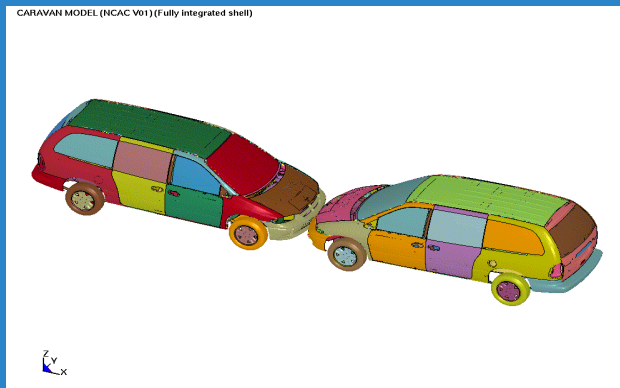
Jason Wang

Tobias Erhart

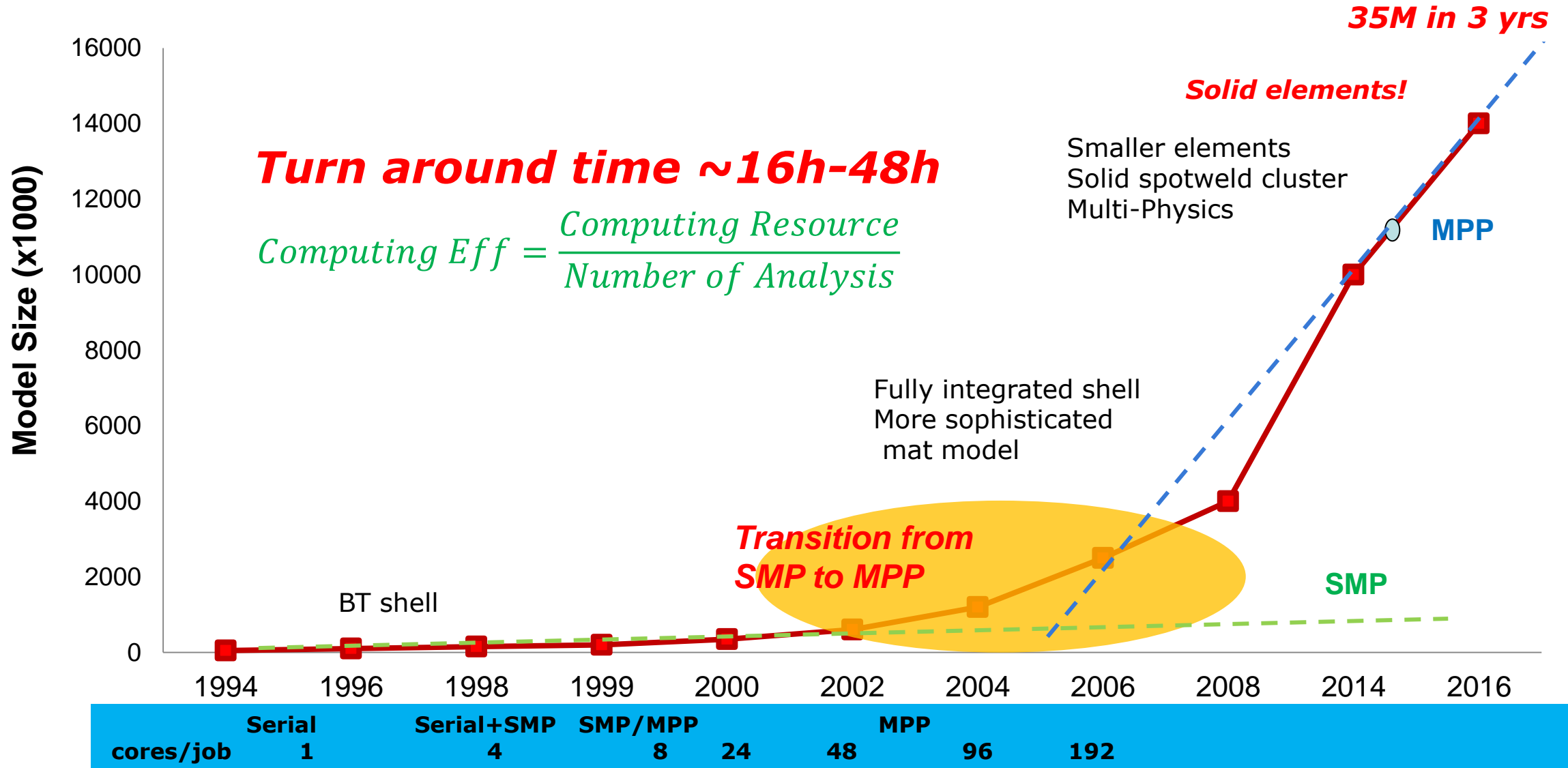
Gunther Blankenhorn

Lee Bindeman

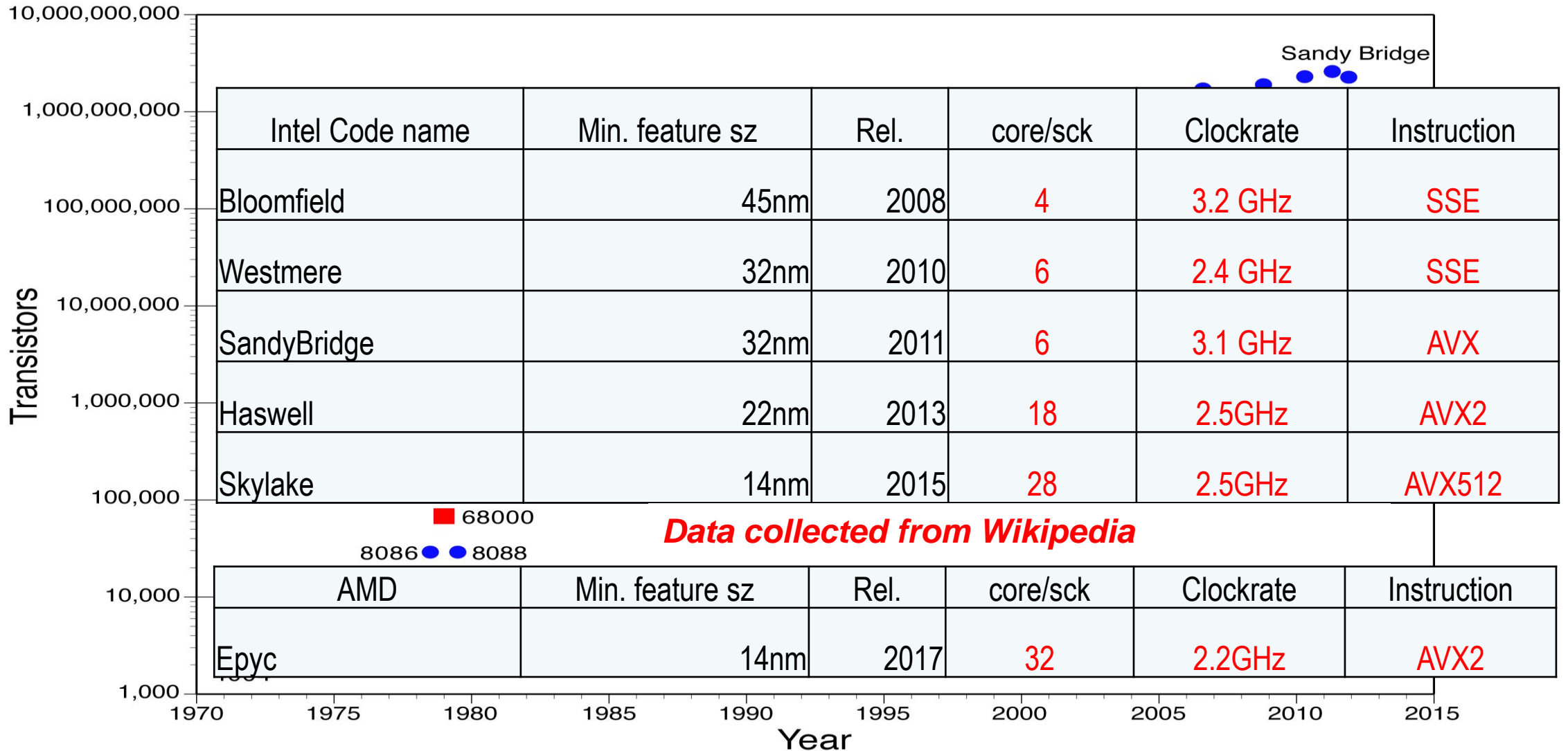
Edward Helwig



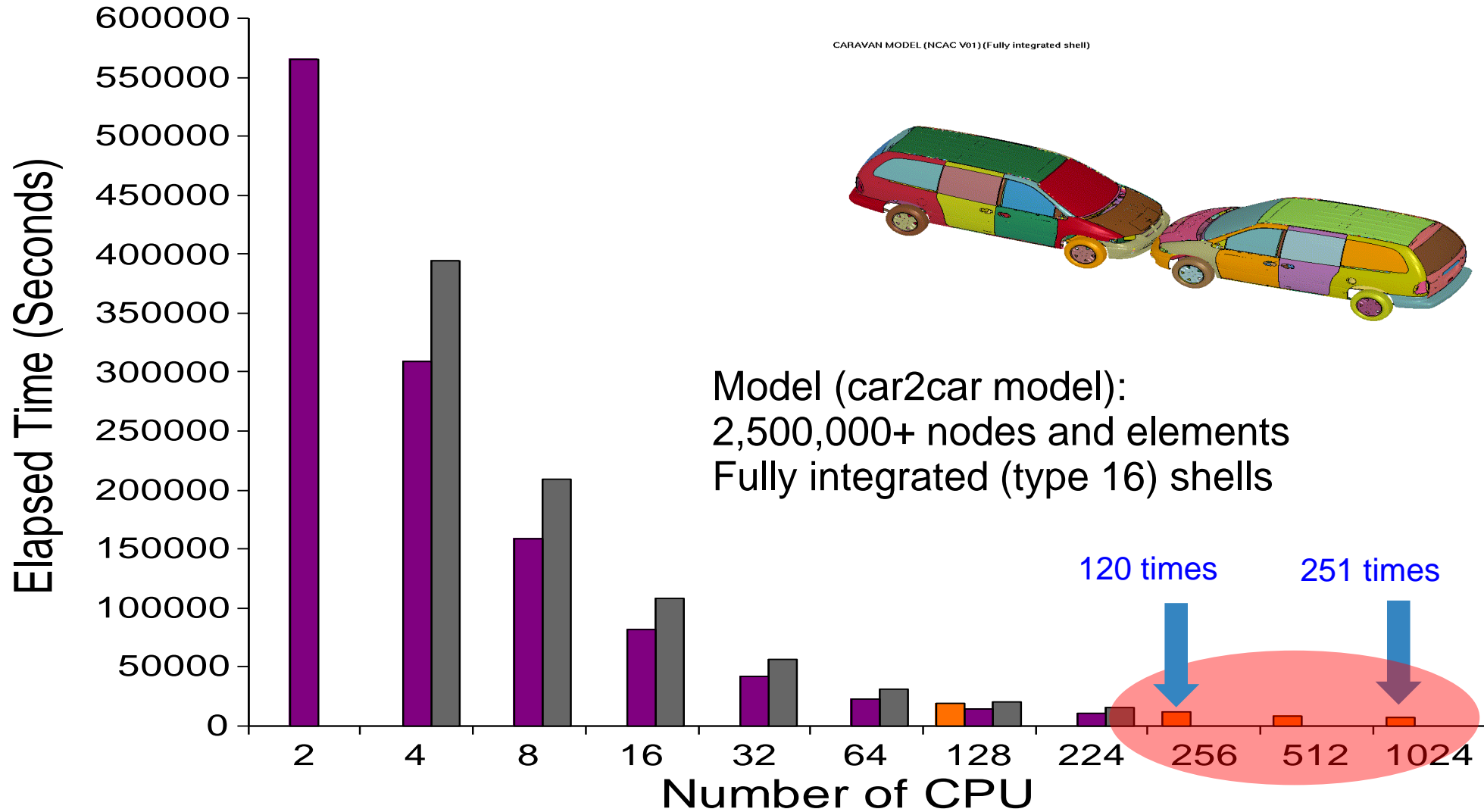
Model size for Safety Analysis



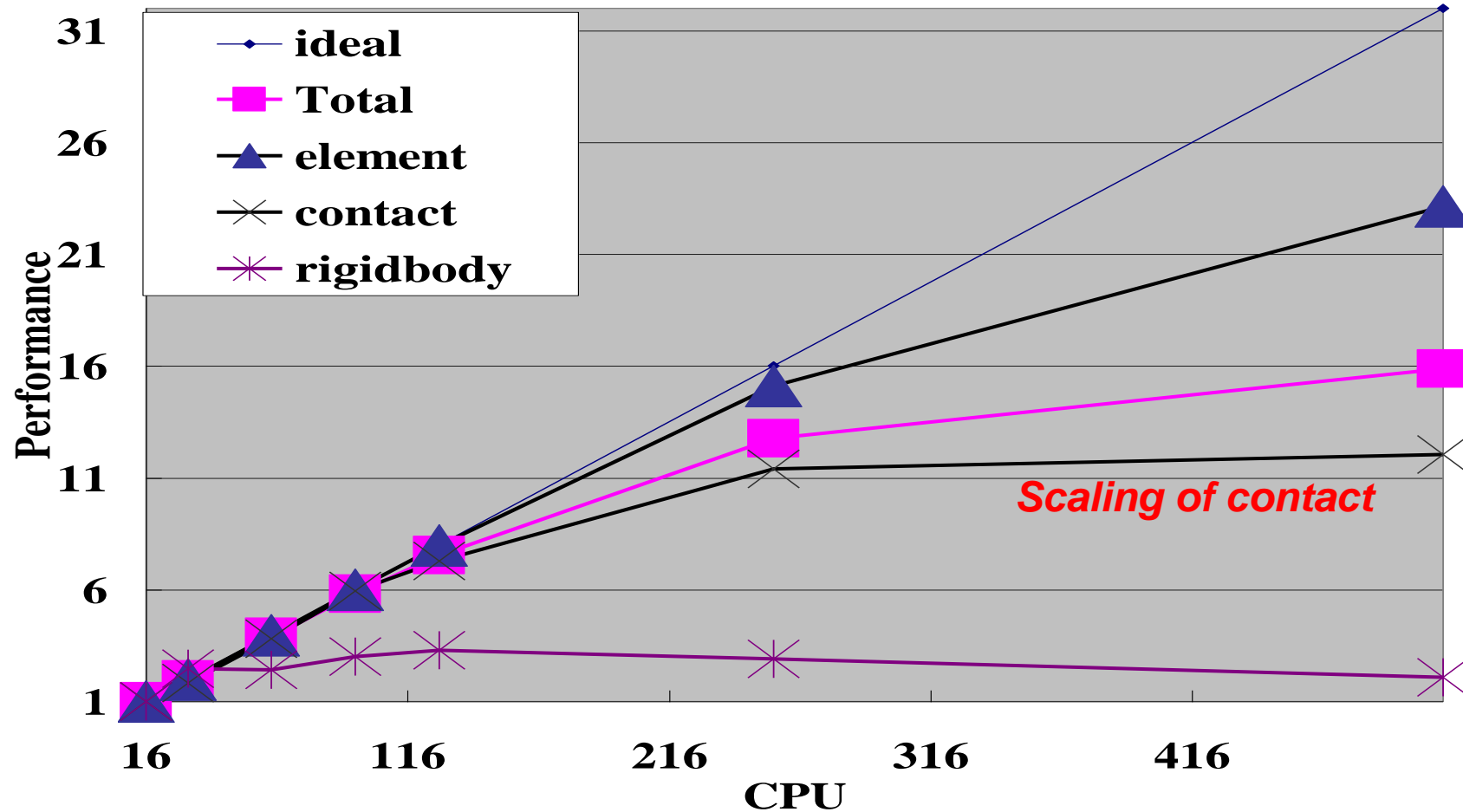
CPU technology - Moore's Law



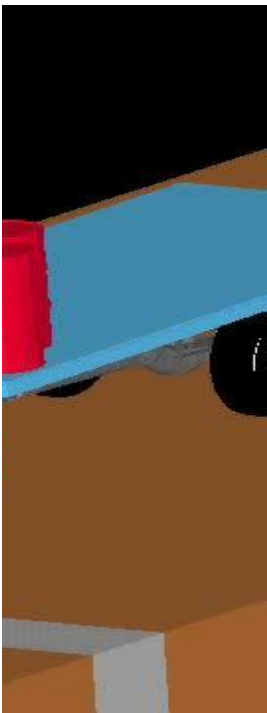
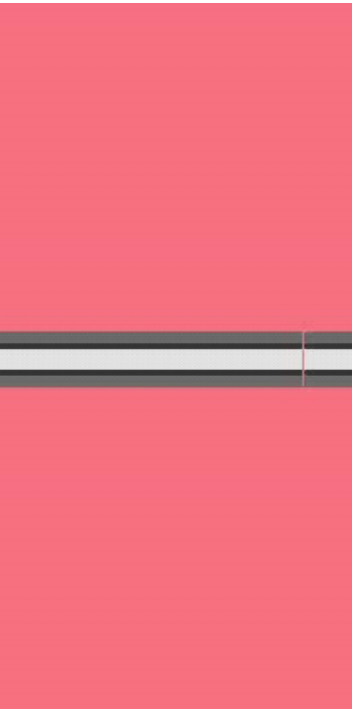
MPP performance – topcrunch.org (2007)



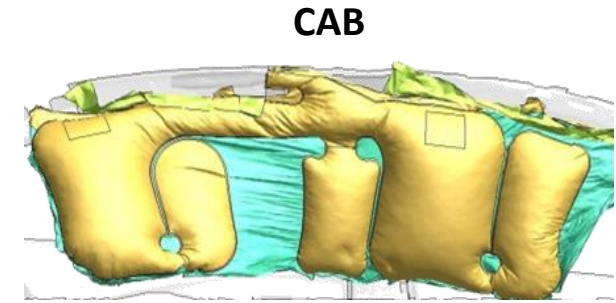
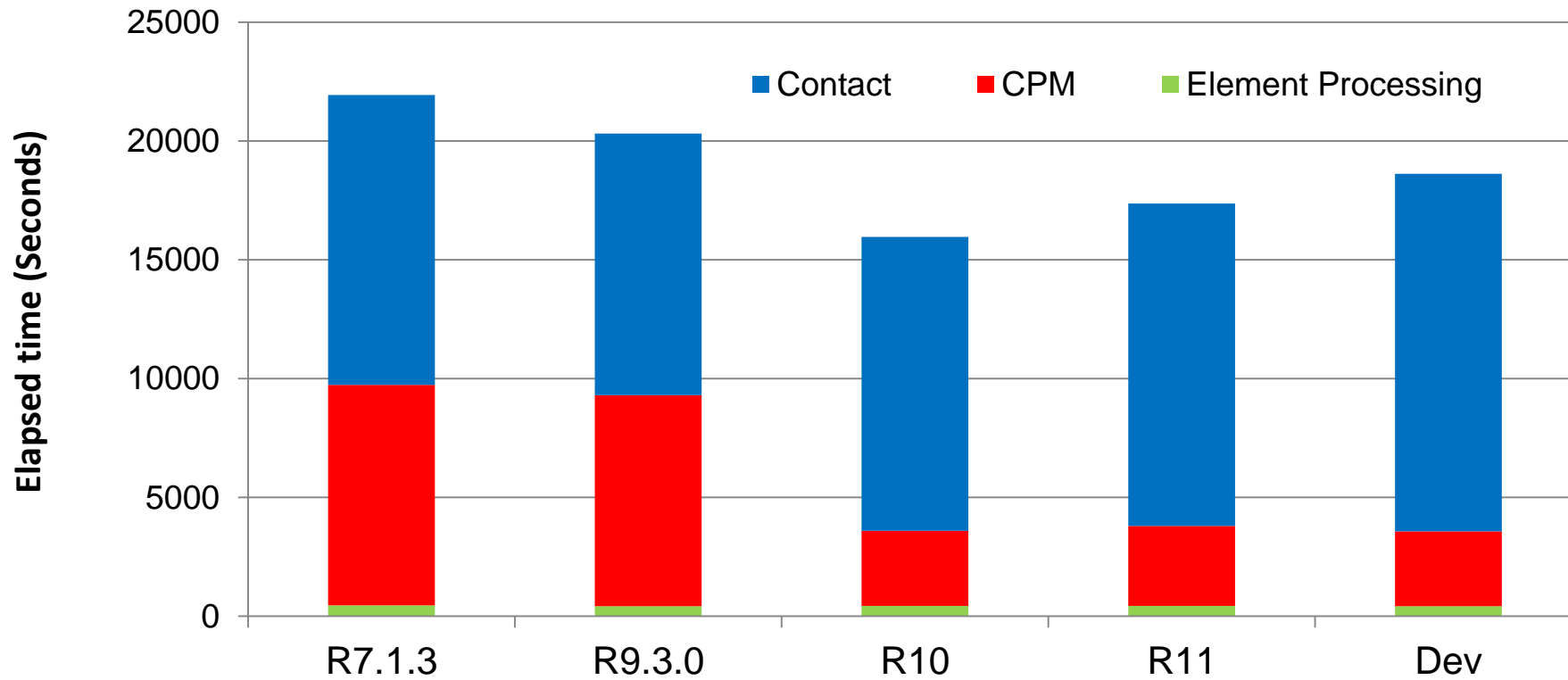
MPP Scaling



- Contact occurs in a small region
- Initial decomposition cannot keep contacts in local during simulation
- Element cost increases in the contact region



Special decomposition



- Performance was measured with 96 processors
- CPM is about 3x faster from R7 to R10
- Self contact about the same
- The overall speed up is about ~20% for bag, ~5% for full car

*CONTROL_MPP_DECOMPOSITION_ARRANGE_PARTS

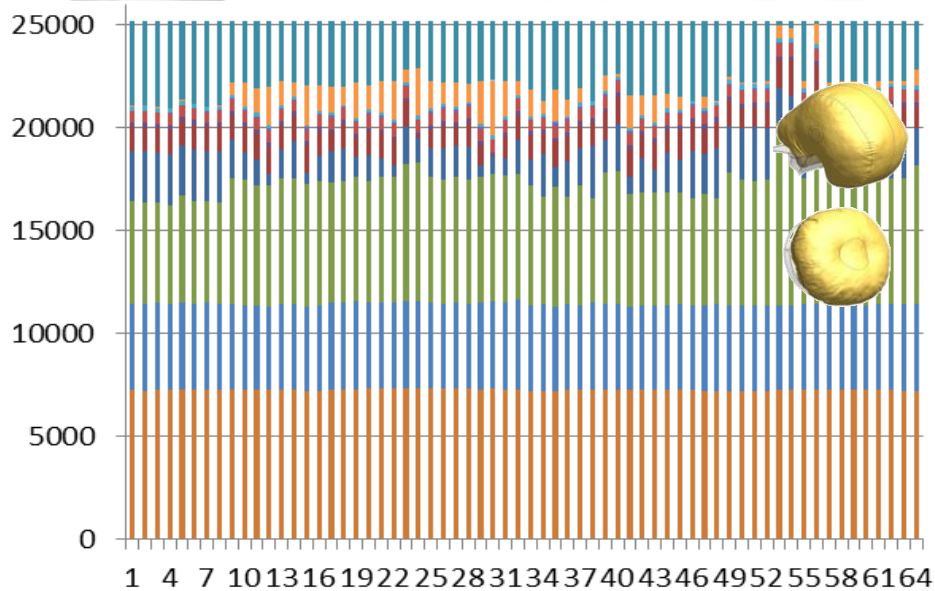
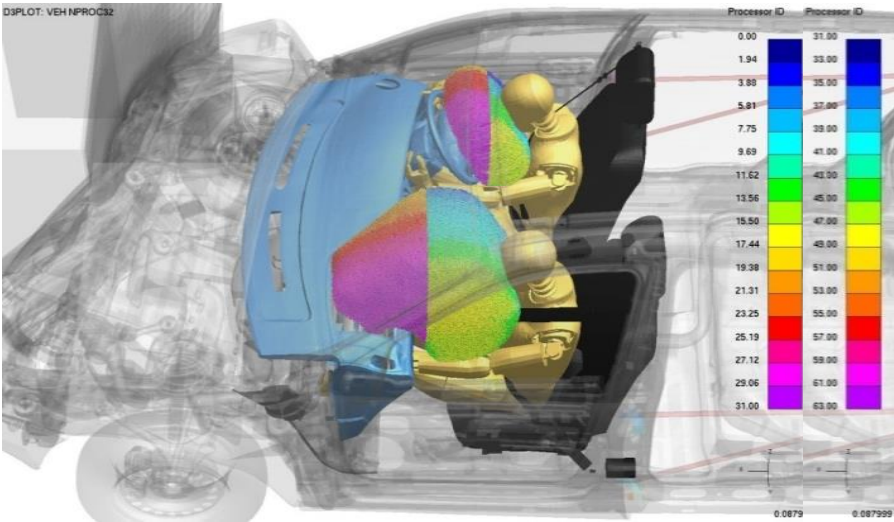
Runtime reduced from 7hrs 5min to 5hrs 53min. 20% faster!

Bags in parallel

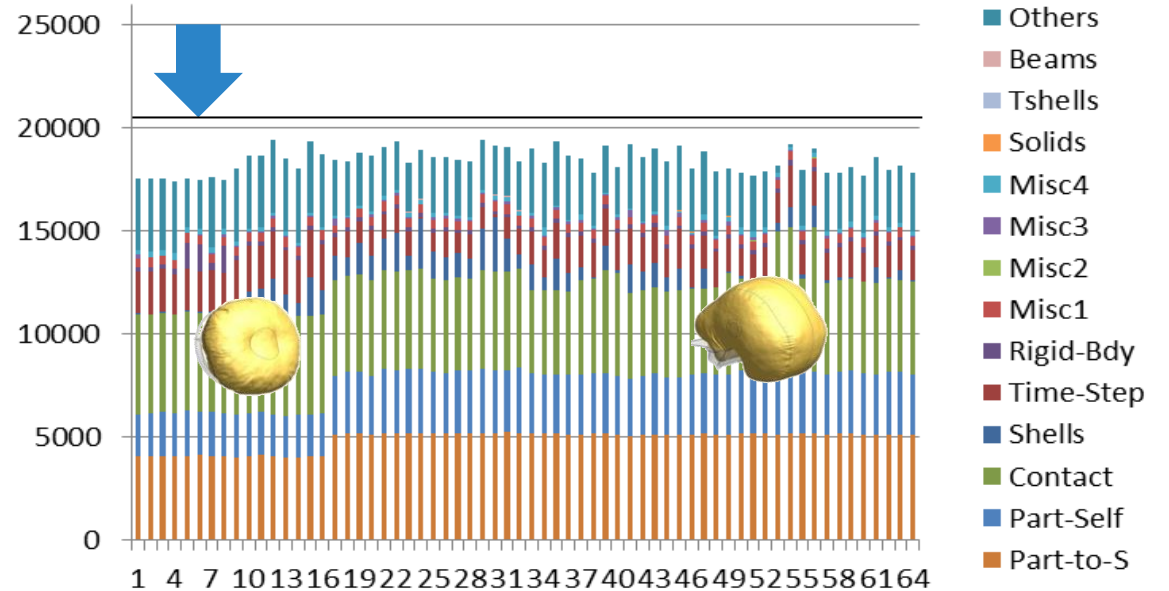
Bag self contacts in parallel

Contacts between bag and dummy in parallel

- set 16 for the DAB
- Set 48 for the PAB



DAB & PAB 64cpu, Default

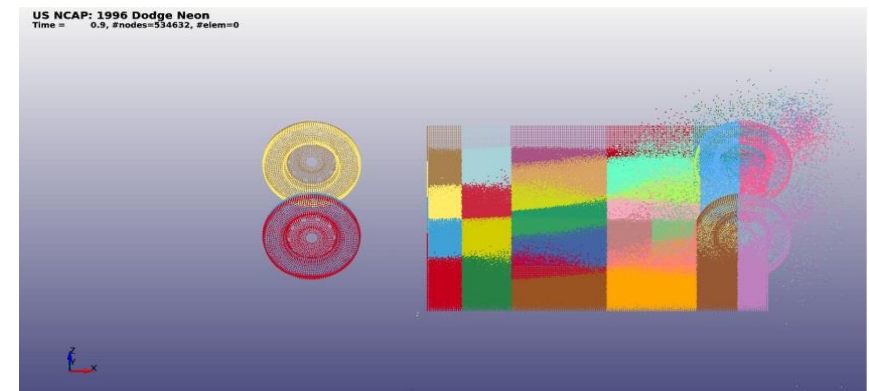
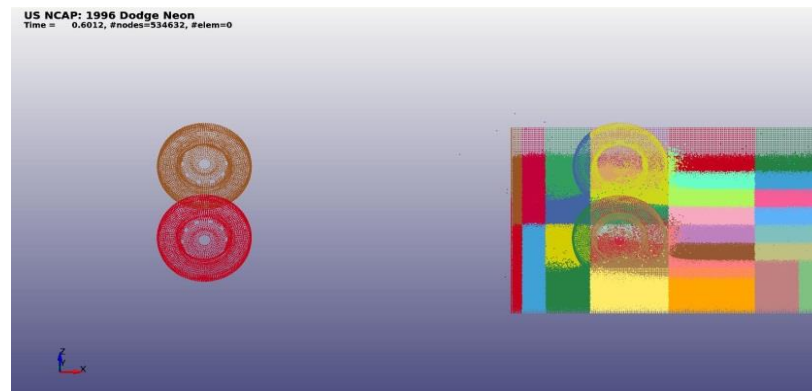
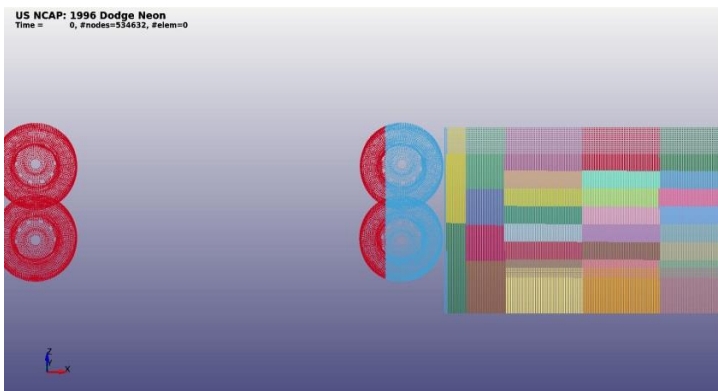
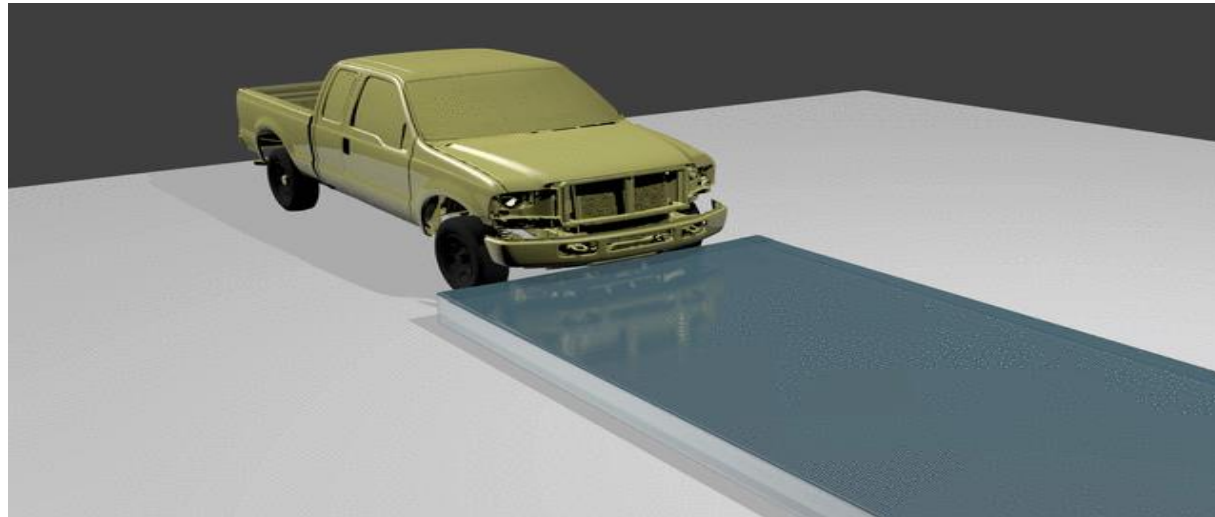


DAB & PAB 16/48 Distributed

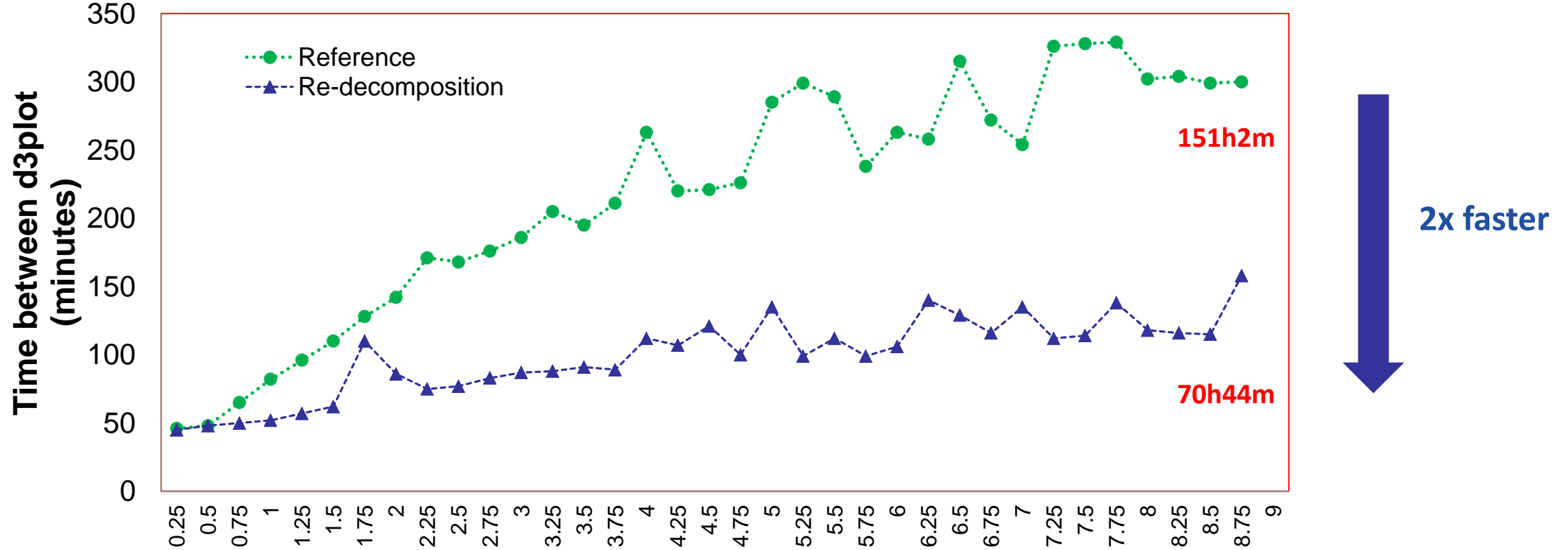
Courtesy of: Richard Taylor, Arup

Re-decomposition

- Deformation/translation creates extra communication and causes load unbalancing.
- `decomp { defgeo }` : The model is decomposed using the current geometry.
- Re-decomposition rearranges partition and reduces network traffic.



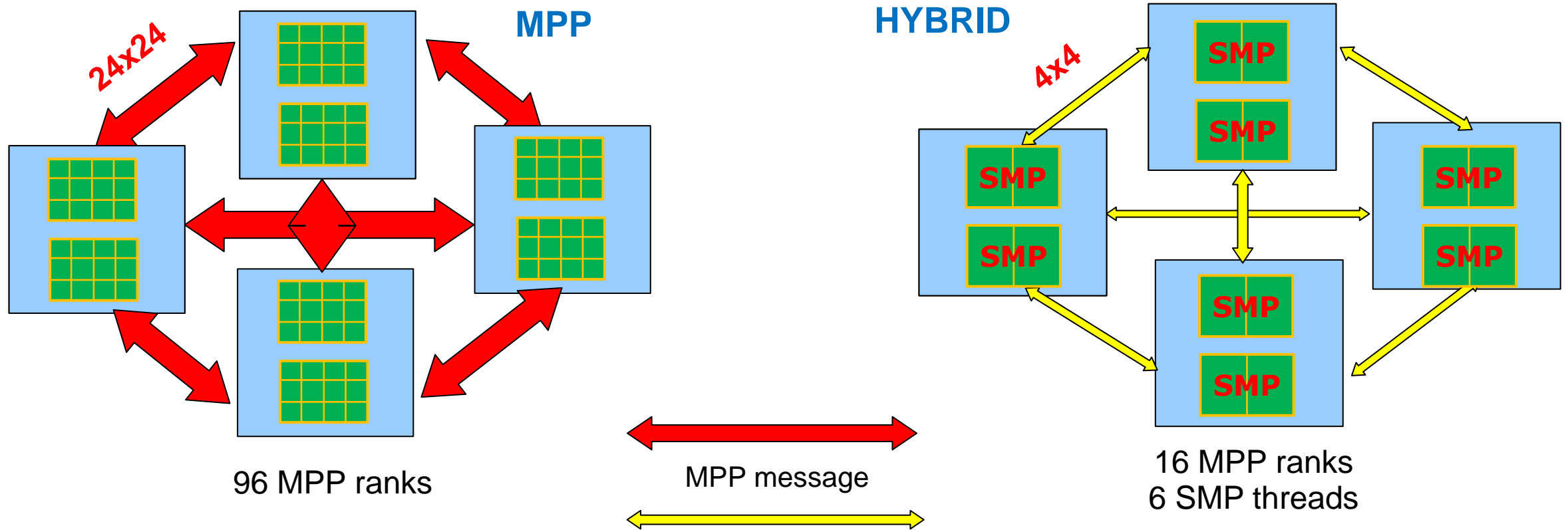
Re-decomposition



- More development work to make an automated process similar to adaptive simulation.
- Currently it uses fulldeck restart capability, user has full control to get better performance.
- Testing other problems, i.e. bird strike, small offset, ODB, etc.

SMP and MPP >> HYBRID

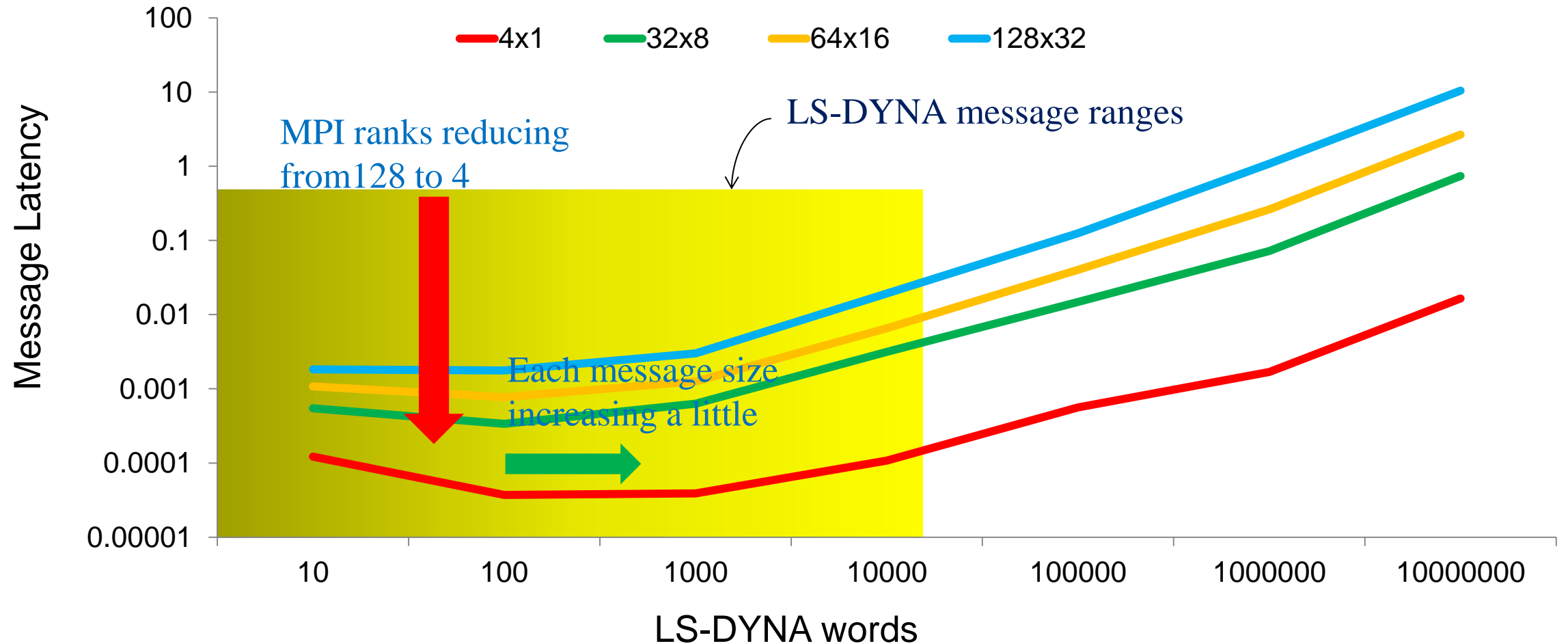
12core/2socket 4 nodes clusters



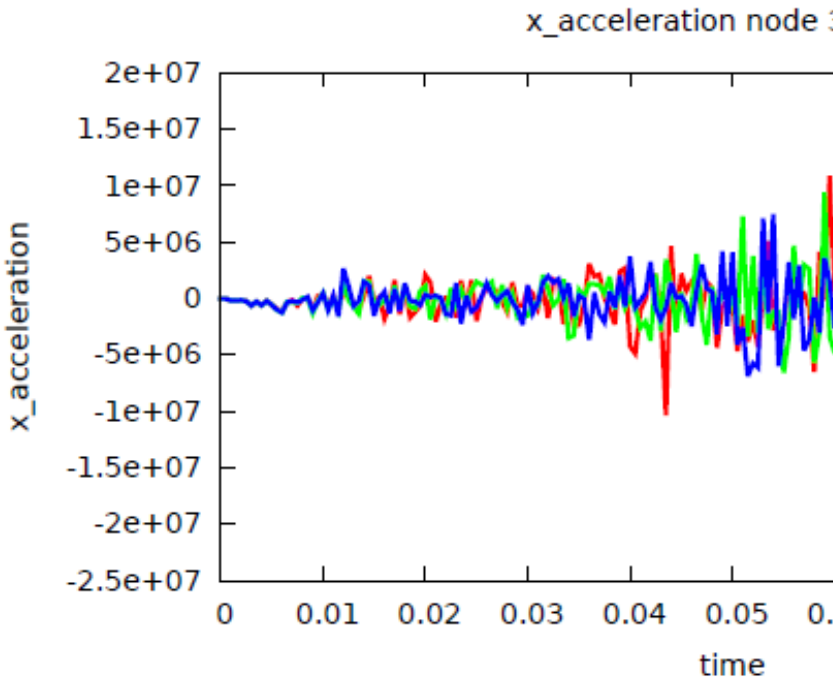
Number of messages reduce by 36x

Message latency between 4 nodes

PFILE: decomposition { vspeed }

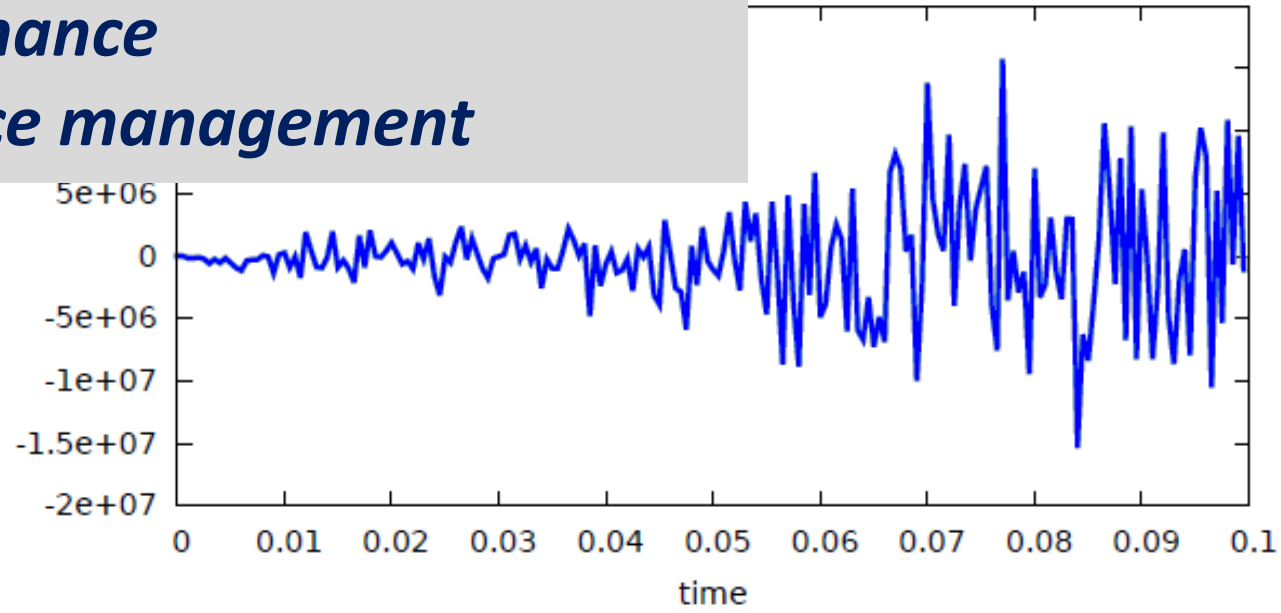
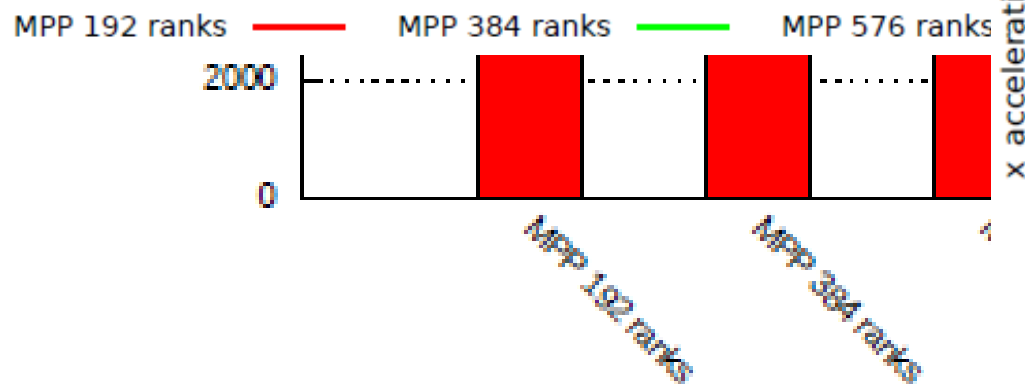


Explicit MPP/Hybrid Scaling and Consistency



HYBRID is a good choice

- ***Consistency***
- ***Reduce network traffic***
- ***Performance***
- ***Resource management***



HYBRID 192 ranks/ 1 thread (red line)
 HYBRID 192 ranks/ 2 threads (green line)
 HYBRID 192 ranks/ 3 threads (blue line)

Implicit MPP/Hybrid Performance

Performance on Linux AMD64 systems

No. of cores (node x socket x core)	WCT of Factor Matrix (seconds)	WCT for job to complete (seconds)
16 x 4 x 1	2055	14417
	985	13290
	582	29135
	960	9887

HYBRID is an obvious choice

- ***Performance***
- ***Reduce network traffic***
- ***Reduce memory requirement***
- ***Reduce I/O requirement***

Scalability - To Infinity and beyond

Hardware

- More cores
- Higher clock rate
- Wider instructions
- Higher memory bandwidth
- Faster interconnect

- Quantum computer

Software

- Efficient algorithm
- MPP/HYBRID
- Special decomposition
- Re-decomposition
- In-network computing
- Dynamic load balancing

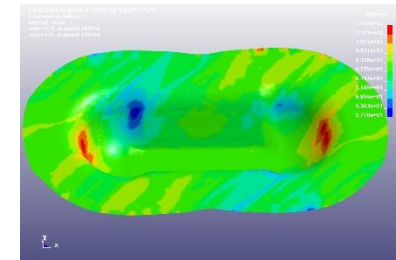
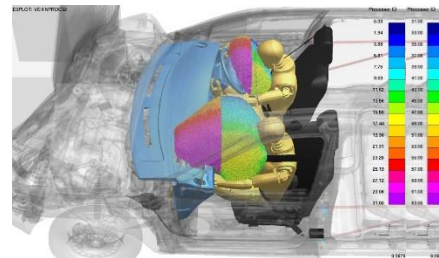
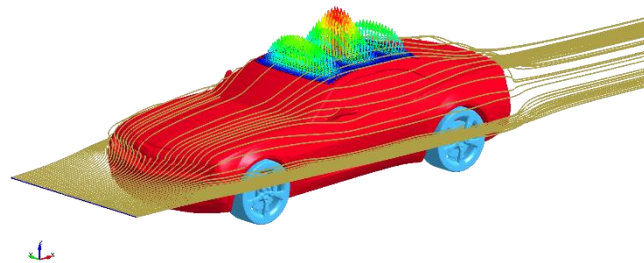
- AI

Recent Development – Part II



Presented by Yun Huang and Tobias Erhart

Thank you!



15. Deutsches LS-DYNA Forum
15.-17. Oktober 2018, Bamberg