

Identification of Material Parameters with LS-OPT®

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Overview

- About LS-OPT
- Introduction
 - *Parameter identification*
- Optimization algorithm
 - *Sequential Response Surface Method*
- Matching of scalar values and curve matching metrics
- *Setup of a parameter identification problem in LS-OPT*
 - *Live demonstration*
- Parameterization of LS-DYNA input curves
 - *Live demonstration*
- Remarks

About LS-OPT

- LS-OPT is a standalone optimization software
 - can be linked to any simulation code
 - Interface to LS-DYNA and MSC-Nastran
 - User-defined Interface

■ Current production version is LS-OPT 5.1

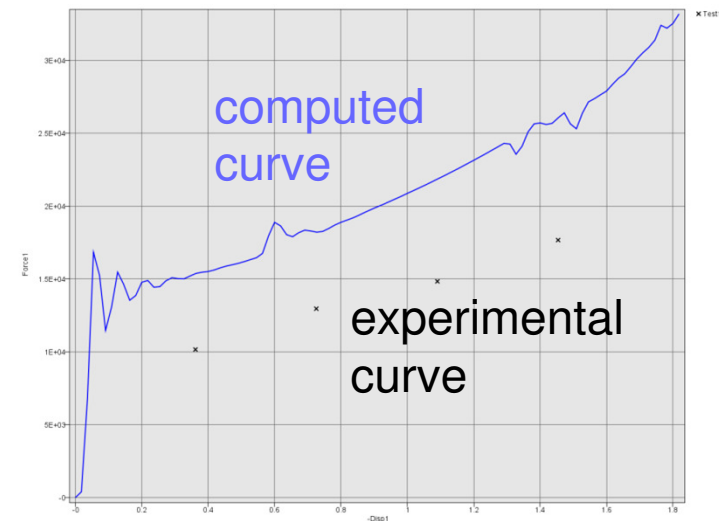
■ LS-OPT Support web page
→ www.lsoptsupport.com

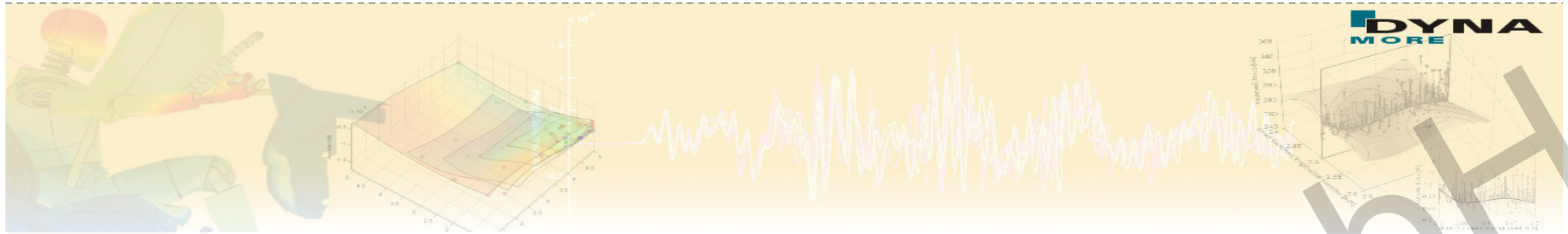
- *Download of Executables*
- *Tutorials*
- *HowTos / FAQs*
- *Documents*



Parameter identification: Objectives

- Parameter Identification problems are non-linear inverse problems solved using optimization
- A computed curve (from LS-DYNA[®]), dependent on parameters, is matched to an experimental curve
- Optimization provides a calibration of the unknown parameters
- Principle technologies involved:
 - *Optimization algorithm*
 - *Curve Matching metric*

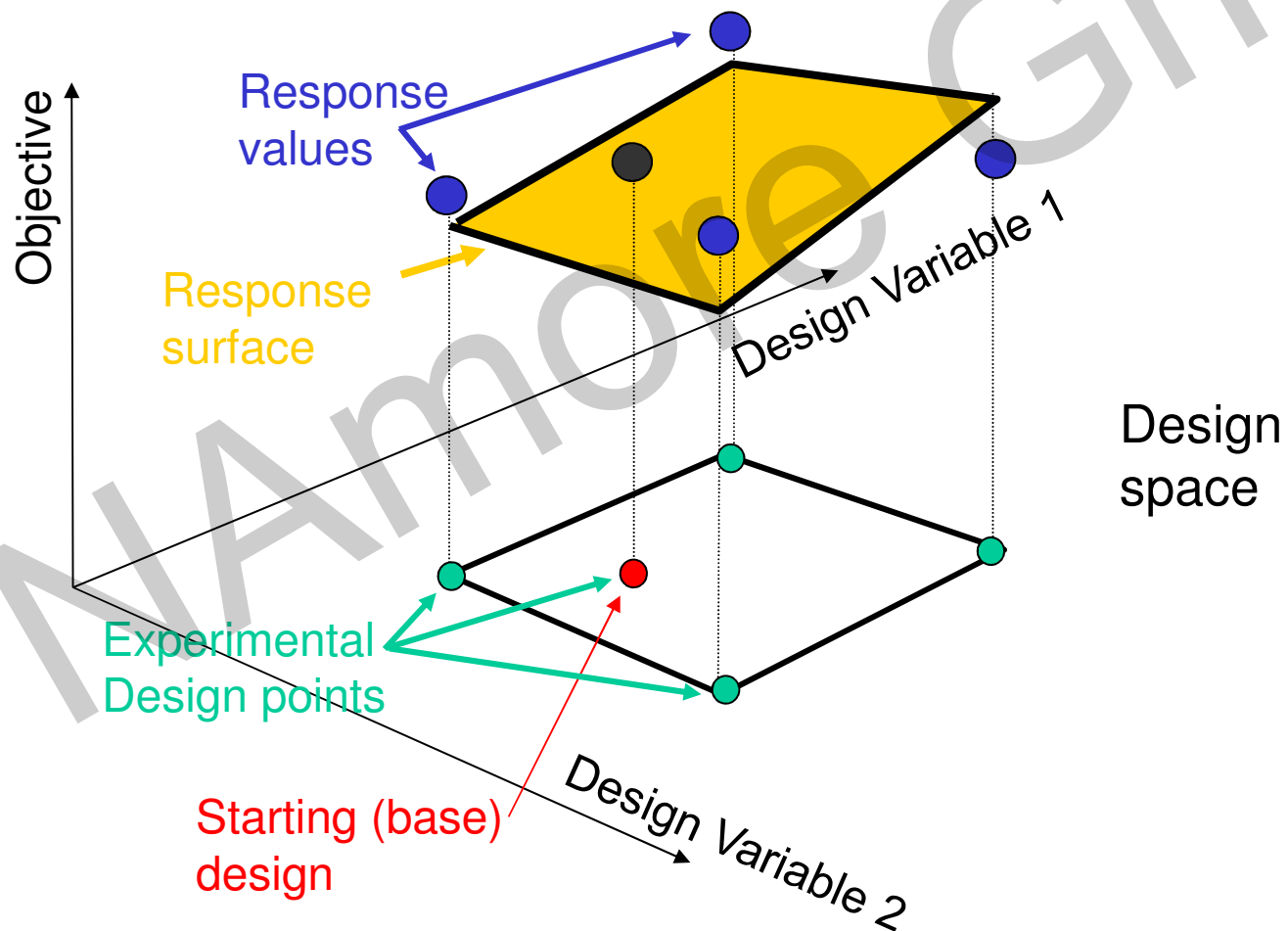




Optimization Algorithm - Sequential Response Surface Method (SRSM)

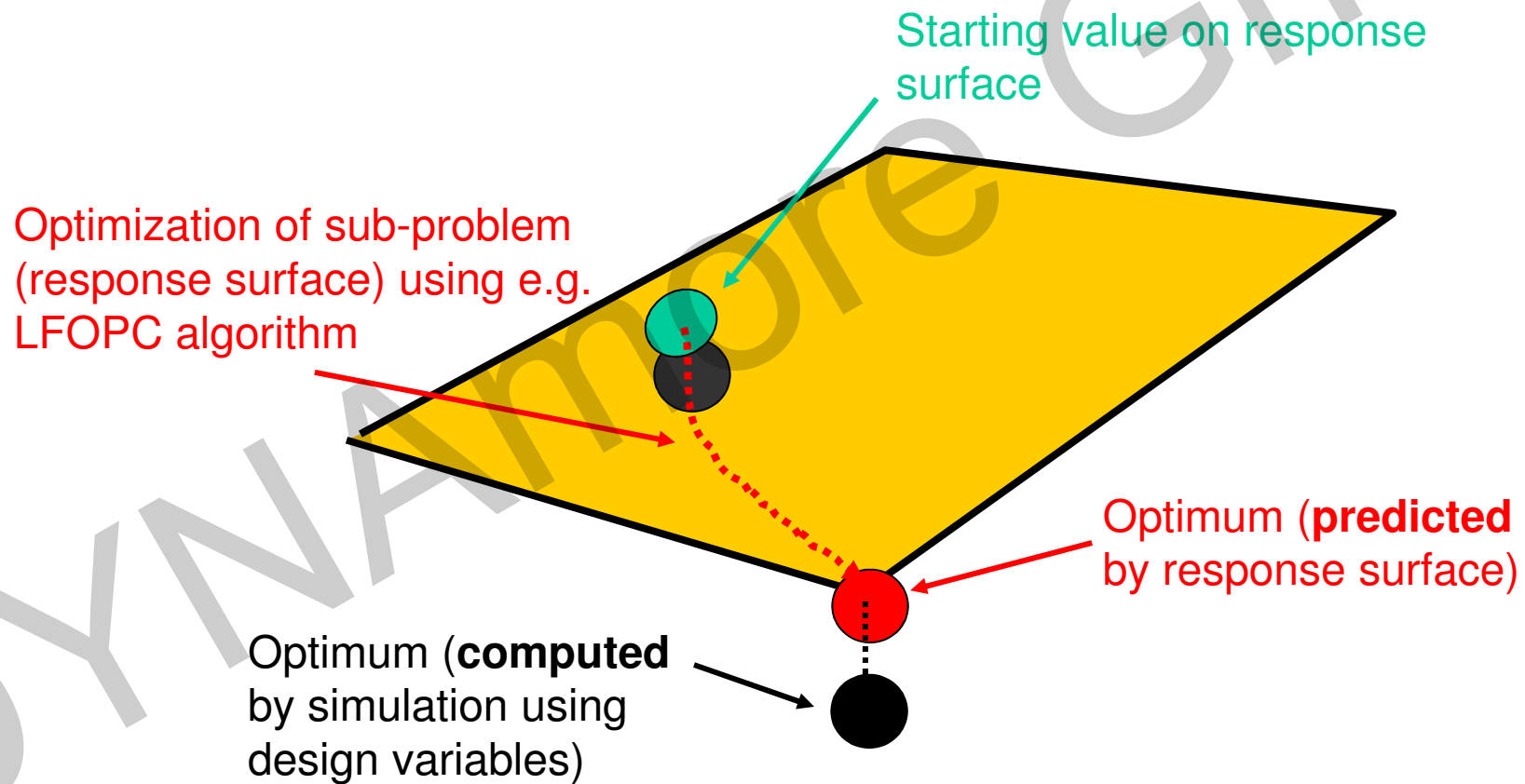
Optimization Algorithm

Response Surface Methodology - Optimization Process



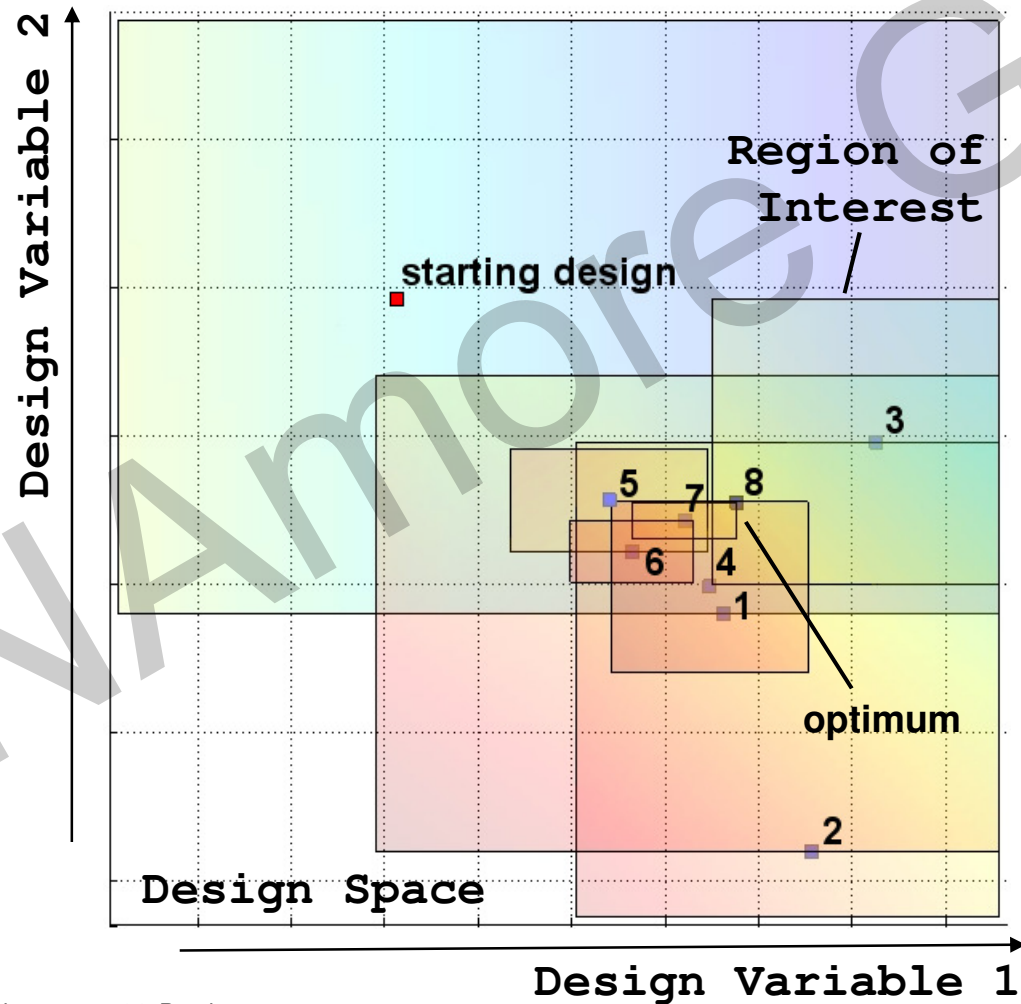
Optimization Algorithm

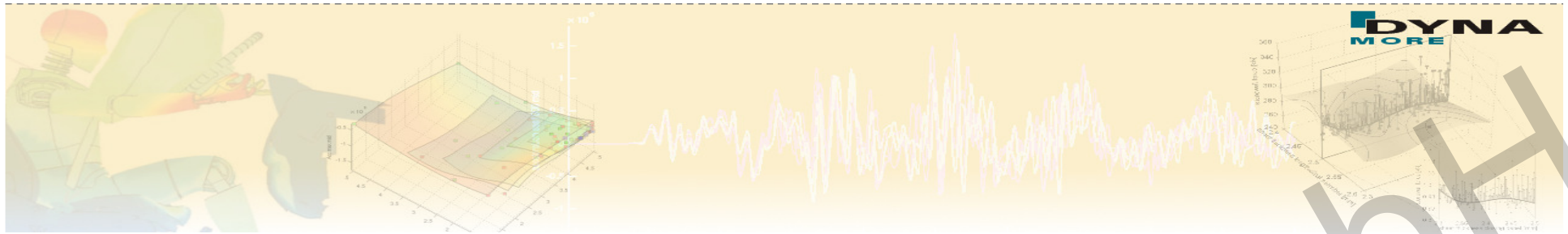
Find an Optimum on the Response Surface (one iteration)



Optimization Algorithm

Sequential Response Surface Methodology (SRSM)





Objective Functions - matching of scalar values and curve matching metrics

Matching of scalar values

Standard Composite Functions

▪ Targeted Formulation

$$F = \sum_{j=1}^m W_j \left[\frac{f_j(\mathbf{x}) - G_j}{s_j} \right]^2$$

$f_j(\mathbf{x})$: simulation response as function of variable vector \mathbf{x}

G_j : target value

W_j : weighting factor

s_j : normalization factor

Matching of scalar values

- Targeted Formulation

$$MSE(\mathbf{x}) = \frac{1}{P} \sum_{i=1}^P W_i \left(\frac{F_i(\mathbf{x}) - G_i}{S_i} \right)^2 \rightarrow \min$$

Composites

Name for composite: F_damage

Composite function type: Sqrt MSE

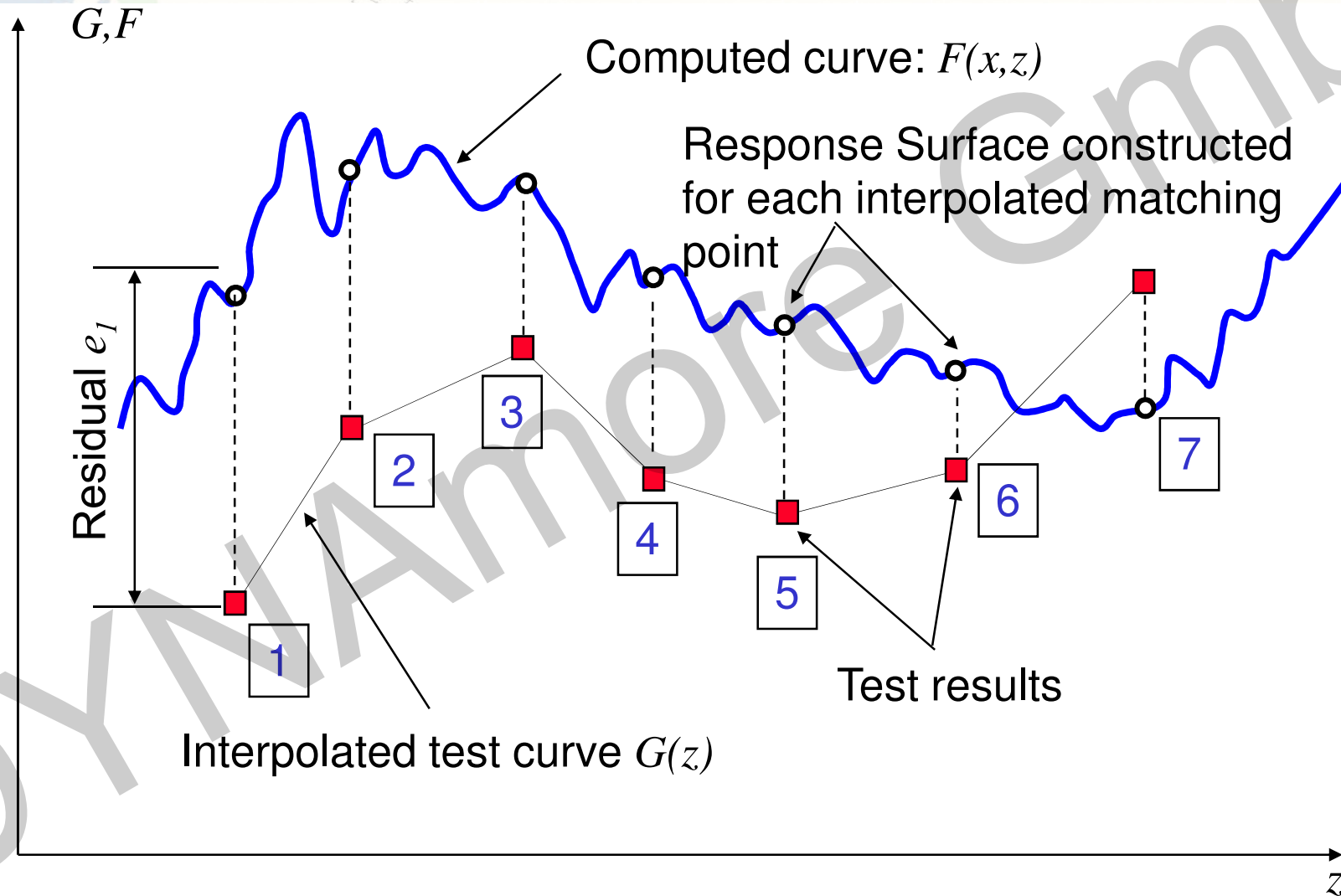
Entity	Multiplier	Divisor	Target
* intrusion_3	1 (default)	30 (default is 1)	20
* intrusion_4	1 (default)	25 (default is 1)	35

Add new

- Responses**
 - Disp2
 - Disp1
 - Acc_max
 - Mass
 - HIC
 - intrusion_3
 - intrusion_4
- Variables**
 - tbumper
 - thood

Buttons: Cancel, OK

Ordinate-based Curve Matching Metric (MeanSqErr)

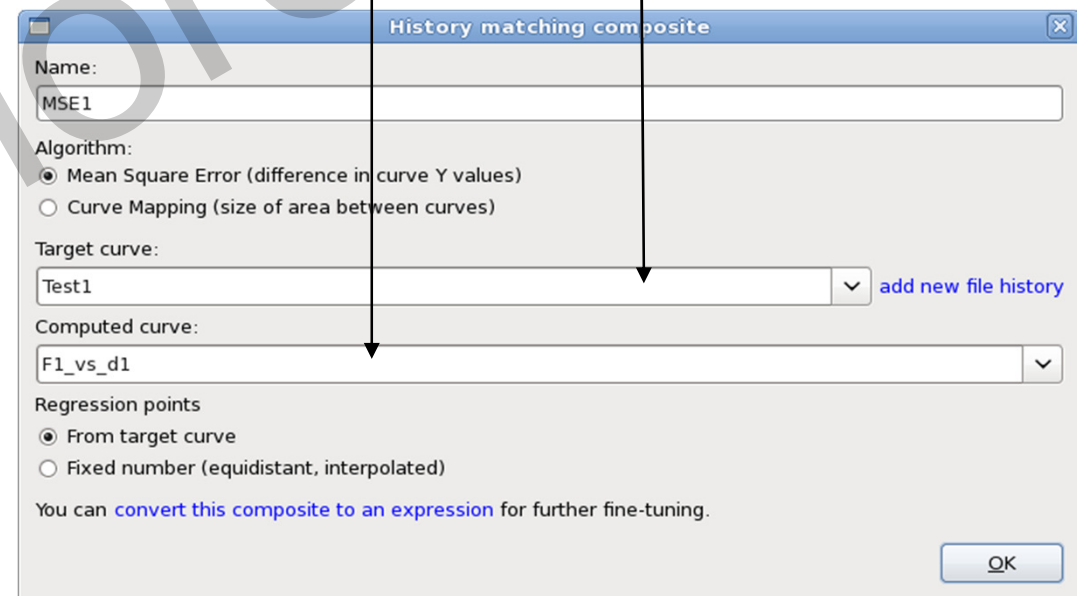
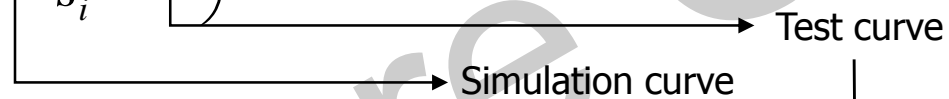


Ordinate-based Curve Matching Metric (MeanSqErr)

- Easy set-up in LS-OPT GUI

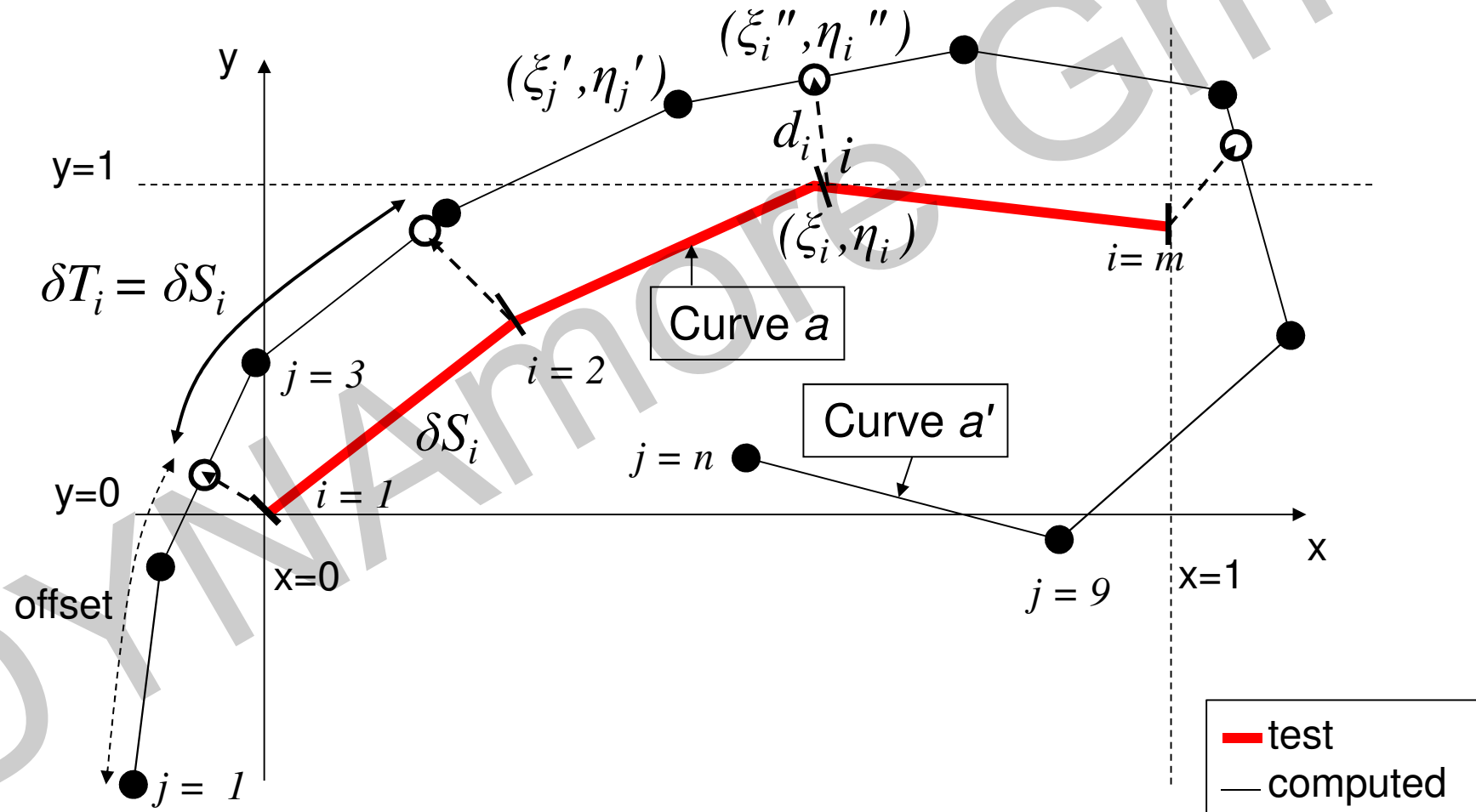
$$MSE(\mathbf{x}) = \frac{1}{P} \sum_{i=1}^P W_i \left(\frac{F_i(\mathbf{x}) - G_i}{S_i} \right)^2 \rightarrow \min$$

- Reads test curve files directly
- Options:
 - number of points,
 - start point, end points,
 - weighting/scaling options
- Crossplots can be defined, e.g. Stress vs. strain, Force vs. deformation ...



Partial Curve Mapping

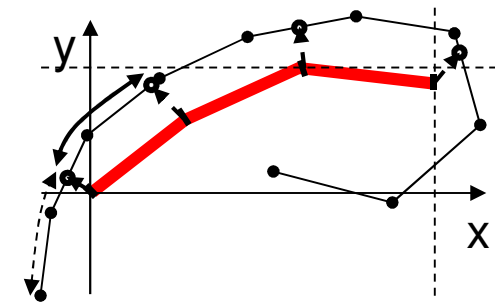
- Partial Curve Mapping (steep or hysteretic curves)



Partial Curve Mapping

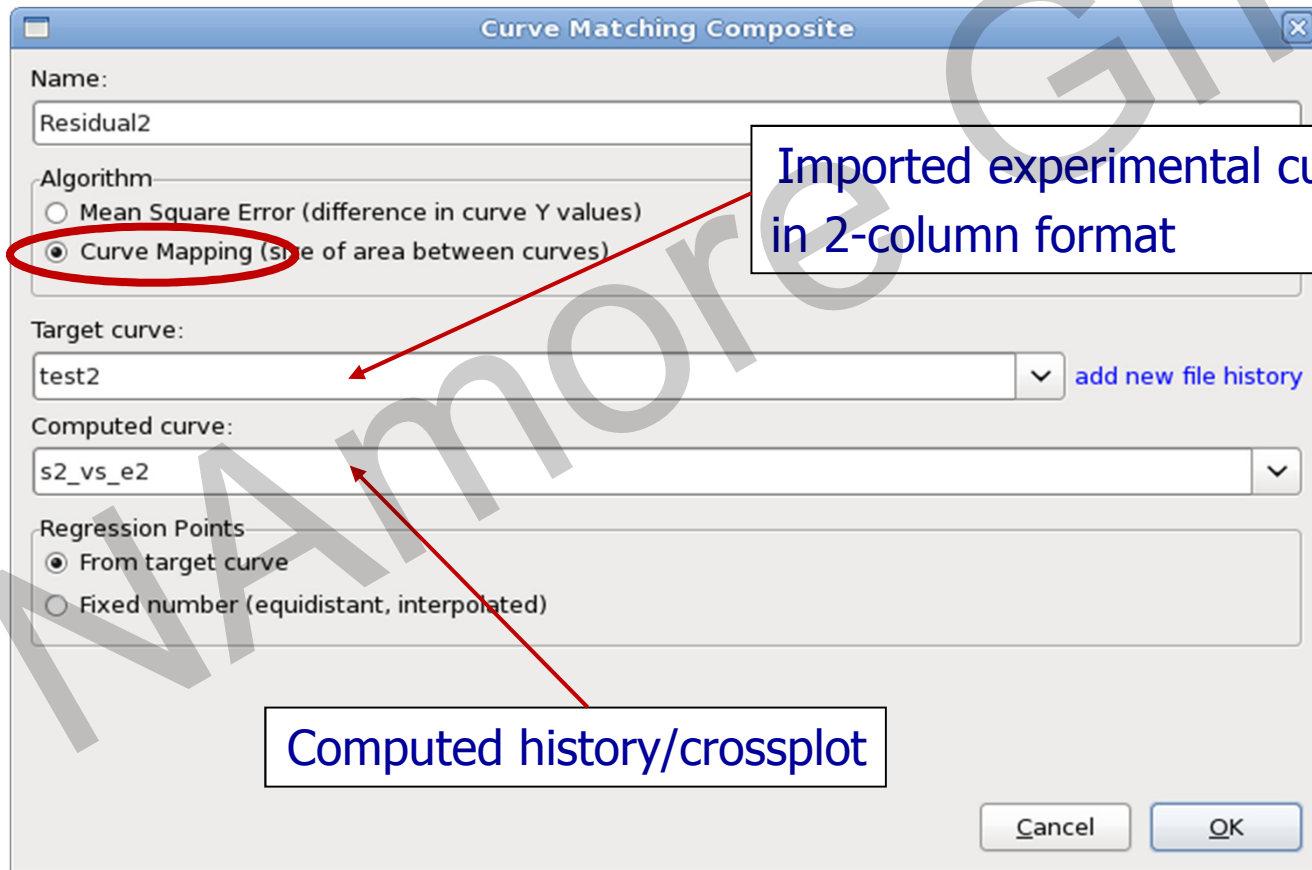
Partial Curve Mapping algorithm

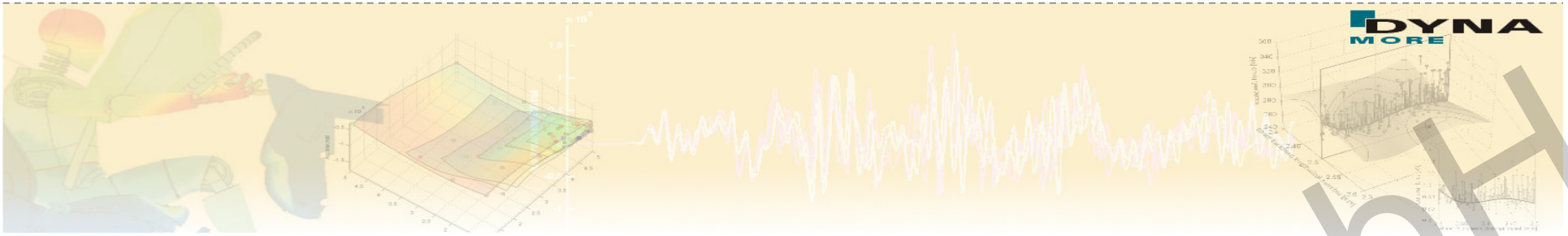
- Normalize the curves to the test (experimental) curve
 - *Avoids problems with different magnitudes for abscissa and ordinate*
 - *Unit independent*
- Map the short curve onto the long curve so that the lengths are equal (mild filtering of curves by user is recommended)
- The distance is defined by the area between the short curve and the mapping
- Optimize the offset to find the smallest distance between the curves



Parameter Identification with Test Curves

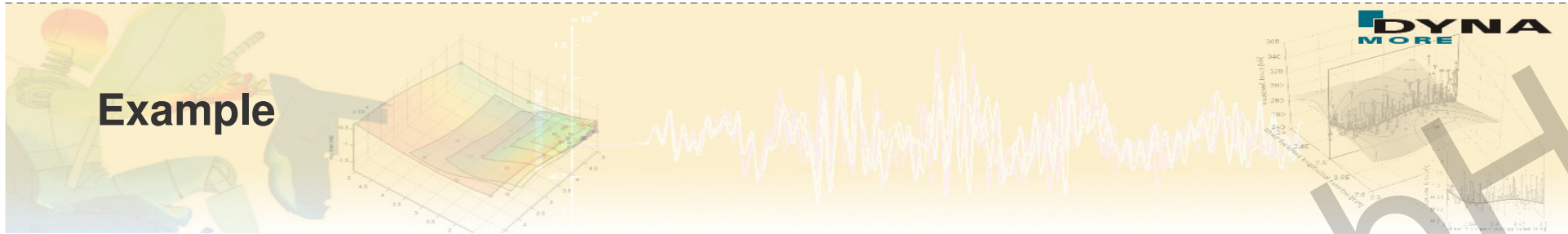
Interface for Curve Mapping



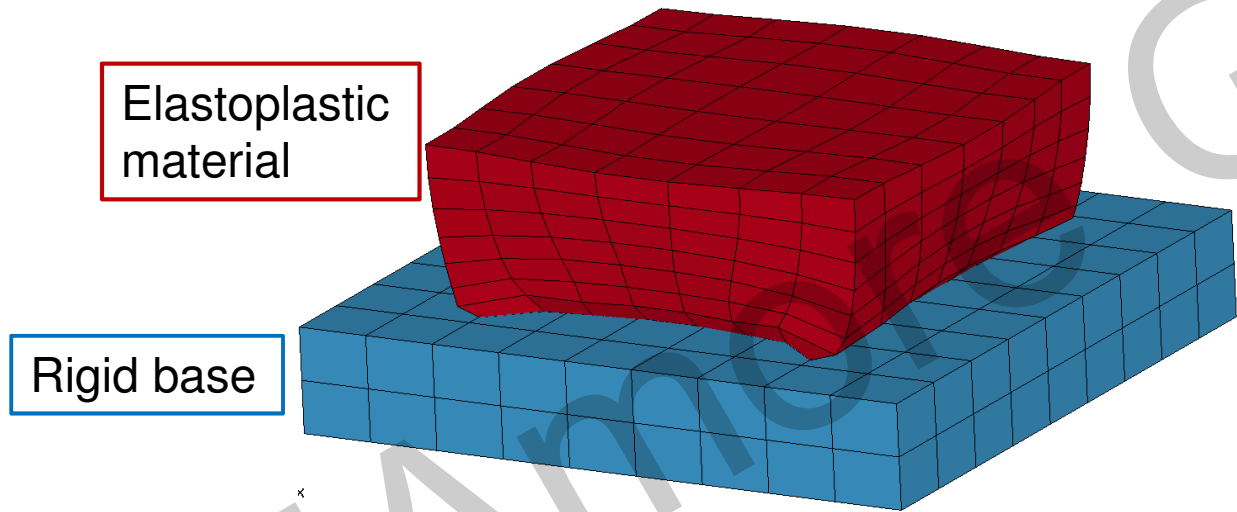


Setup of a parameter identification problem in LS-OPT - Example

Example



- Example: Material properties of a foam



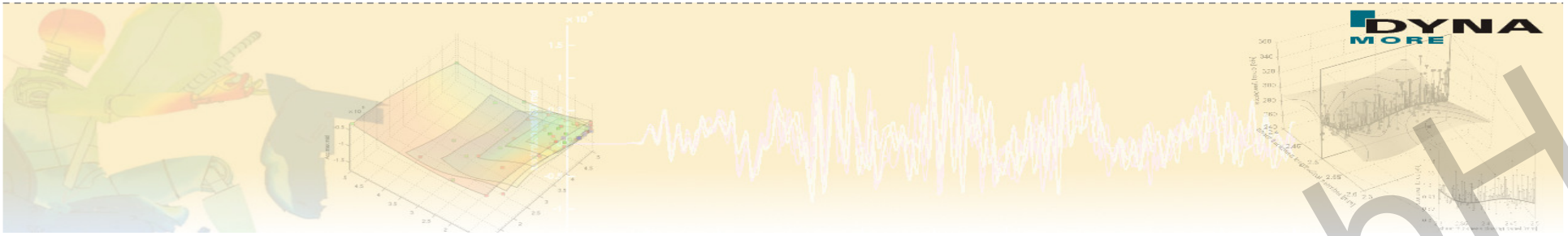
Experiment:

Displ	Force
0.36168	10162
0.72562	12964
1.0903	14840
1.4538	17672

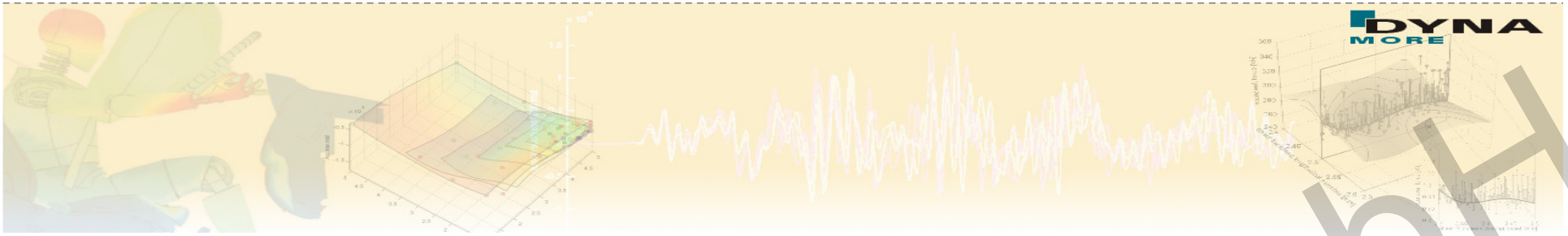
```
*PARAMETER
rYMod,7e5,rYield,15e2
*MAT_PLASTIC_KINEMATIC
1 1.0E-3&YMod 0.3&Yield 10.0 0.0
0.0 0.0 0.0 0.0
```

Parameters:

- Young's modulus
- Yield stress



Live Demonstration



Parameterization of LS-DYNA input curves

Parameterization of LS-DYNA input curves

- Material properties of Confor Blue Foam CF45[®]
- Material model *MAT_FU_CHANG_FOAM

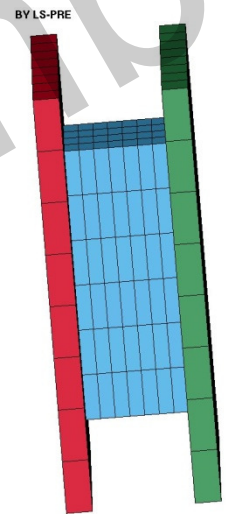
```
*MAT_FU_CHANG_FOAM_TITLE
MAT FU CHANG FOAM (Confor blue)
$# mid ro e ed tc fail damp tbid
2 1.0720E-7 0.150000 0.000 0.000 0.000 0.00500 7
$# bvflag sflag rflag tflag pvid sraf ref nu
1.000000 1.000000 1.000000
$# d0 n0 n1 n2 n3 c0 c1 c2
0.000 0.000 0.000 0.000 0.000 0.000 0.000 0.000 0.000
$# c3 c4 c5 aij sij minr maxr shape
0.000 0.000 0.000 0.000 0.000 0.000 0.000 0.000 0.000
```

- Strain rate dependent material

```
*DEFINE_TABLE_TITLE
Dehnraten Table
$# tbid
7
$# value lcid
```

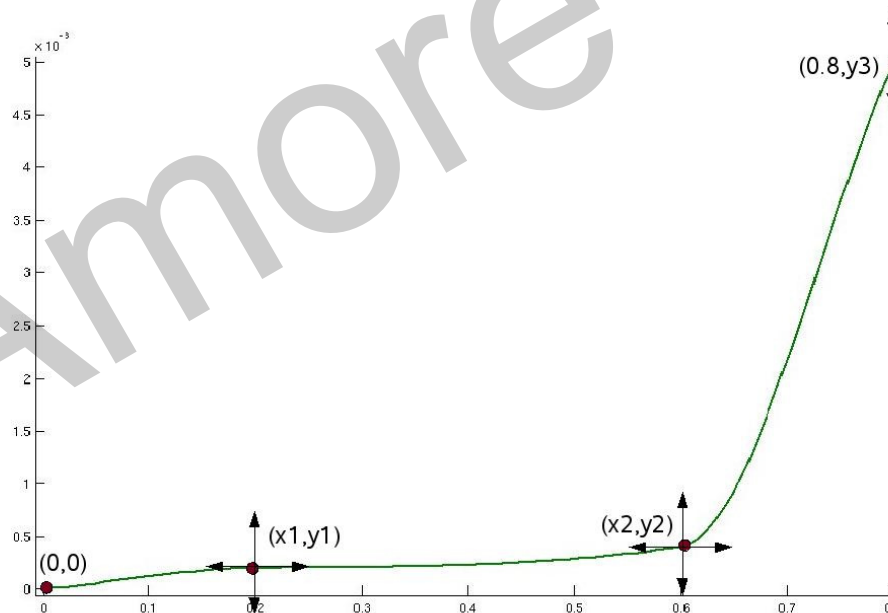
- Use LS-OPT to determine stress vs. strain curves

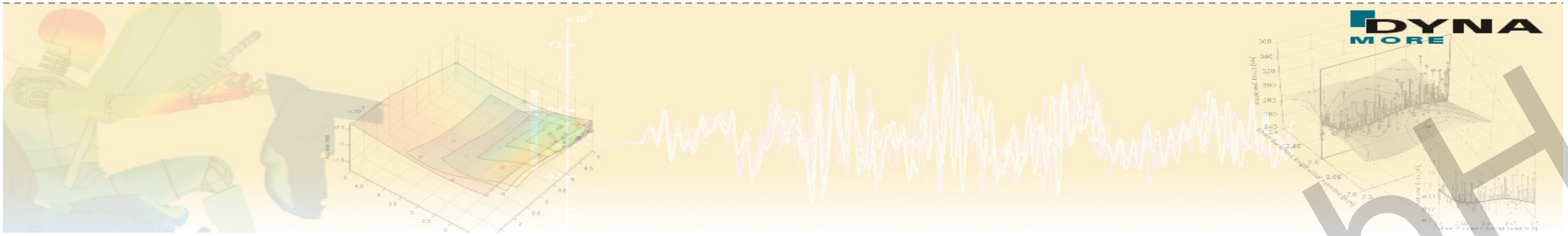
```
*DEFINE_CURVE
$Dehnraten für 1 1/s
$ LCID SIDR SCLA SCLO OFFA
$ 1 0 1.0 1.000000
$a1 o1
```



Parameterization of LS-DYNA input curves

- User-defined preprocessor (Python, Perl, ...) that generates LS-DYNA include file containing the curve
- Parameterized analytical function
 - *spline, polynomial, exponential function, ...*





Live Demonstration

Remarks

- Make sure to evaluate exactly the same entities from simulation and test (filtering, ...)
- The result can never be better than the (material-) model
- Use appropriate analytical function for parameterization of LS-DYNA input curves
- Ranges for parameters?
→ increase if optimal value is bound and result not good enough (if parameter is sensitive!)
- Additional objective functions like max value, time of failure, ... might improve the results
- Multiple load cases: objectives might be in conflict